VRDC

Creating Mixed Realities with Tango, HoloLens, and Beyond!

Aaron Pulkka CEO Rabbx Inc

Cyrus LumCTO Ant Hive Games





Cyrus Lum







Prior AR Experience







Aaron Pulkka











METAL GAMES



Prior VR XP







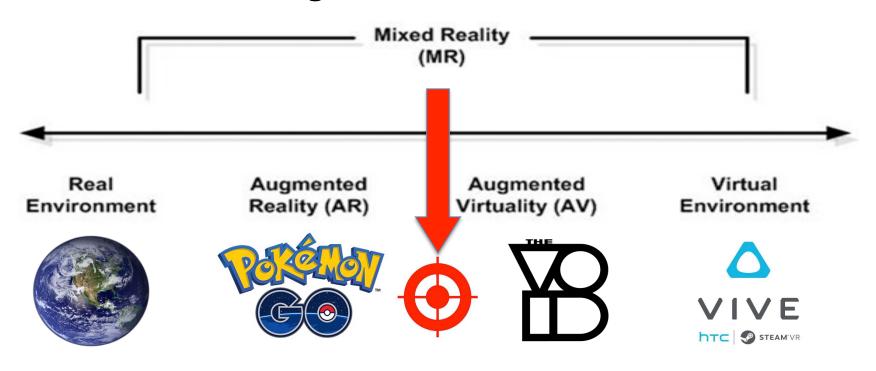








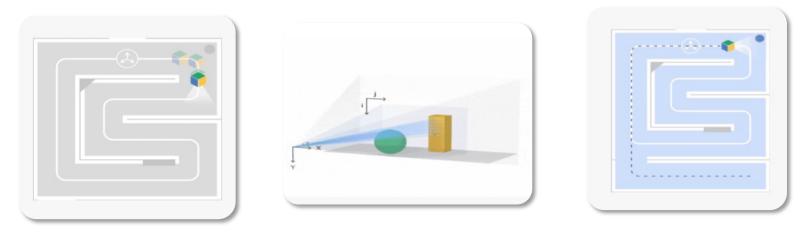
Mixed Reality





Spatial Awareness

Motion Tracking – Depth Sensing – Area Learning

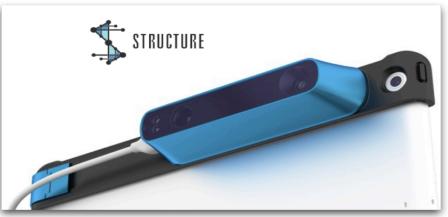


Surface Reconstruction - Plane & Void Detection



Spatially Aware Devices







Microsoft HoloLens







Now available in Australia, Canada, France, Germany, Ireland, New Zealand, United Kingdom, and United States.













Motion and Gesture Tracking



Hands

ID	X	Υ	Z	ISPRESSED	
99	0.114871	-0.021094	-0.541399	true	
188	-0.16518	-0.033638	-0.509941	false	

Head Rotation Quaternion

CONST	1	J	K	
0.999422	0.031709	0.011533	-0.004099	

Origin Translation Vector

X	Υ	Z	
-0.020313	-0.032074	-0.164817	



Speech Recognition



- System level commands
- User configurable commands



App Crash Dumps File Explorer Logging Simulation Networking Virtual Input

(q)

ONLINE

SHUTDOWN

RESTART

Rotate: left click + mouse; Pan: right click + mouse; Zoom: mouse scroll

Tracking options View options Surface reconstruction Spatial Anchors □ Force visual tracking ☑ Show floor Update Update Pause Show frustum Show stabilization plane Show mesh Save Show spatial anchors First person view Show details Full screen



Hands

3D View

ID	X	Y	Z	ISPRESSED
99	0.114871	-0.021094	-0.541399	true
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SECURITY





Behemoth for HoloLens

- Enabling epic cinematic experiences anywhere!
- Discover mysterious dangers lurking beyond your walls
- Explore space for resources







Mixed Reality UX

- Embrace 3D Space
- 3D Audio is Critical
- ReFlow to environment



MxR ReFlow

Adapt to each space

- AI/CSS for MxR
- Mesh generation
- Plane extraction
- Feature identification
- Relative placement







HoloLens Development Environment













Microsoft UWP/ HoloToolKit / SpatialMapping \ SpatialProcessing



Spatial Processing

FLARE: Fast Layout for Augmented Reality Applications

Microsoft Research

Lior Shapira† Microsoft Research Microsoft Research

Microsoft Research



Figure 1: Designing an immersive augmented reality (AR) application such as a dynamic racing game is difficult. In our framework (a) declarative rules are used to define application elements and the rules operaning them (b) in real-time we analyze an environment to extract scene geometry and horizontal and vertical planes (o) our move-making algorithm targets the application to the room (d) an additional result of our system in a

Creating a layout for an augmented reality (AR) application which embeds virtual objects in a physical environment is difficult as it must adapt to any physical space. We propose a rule-based framework for generating object layouts for AR applications. Under our framework, the developer of an AR application specifies a set of rules (constraints) which enforce self-consistency (rules regarding the inter-relationships of application components) and scenestency (application components are consistent with the physical environment they are placed in). When a user enters a new environment, we create, in real-time, a layout for the application, which is consistent with the defined constraints (as much as possible). We find the optimal configurations for each object by solving a constraint-satisfaction problem. Our stochastic move making algorithm is domain-aware, and allows us to efficiently converge to a solution for most rule-sets. In the paper we demonstrate several augmented reality applications that automatically adapt to different rooms and changing circumstances in each room.

Index Terms: F.4.1 [Mathematical Logic]: Logic and Con-straint Programming—; G.3 [Probability and Statistics]: Markov

Augmented reality is a growing trend on mobile platforms, as well as on emerging wearable computing platforms. Yet, AR systems have struggled to make the transition from laboratory to the real world. A particular hindrance to the successful deployment of AR systems is the complex and variant nature of reality. AR applications must work in any environment the user finds herself in. Therefore, the layout of the different elements comprising the AR

'e-mail: rgal@microsoft.com e-mail:liors@microsoft.com e-mail:evalofek@microsoft.com

2014

application must be consistent with the environment. Simple applications might consist of planar information overlaid on reality, or virtual objects hanging in free space in front of a user. However, creating an application which truly integrates with the envi-ronment, embedding virtual objects among real physical objects is

Several issues make this task challenging: First, the layout of virtual objects must be consistent with the placement of other virtual objects, as well as with the geometry of the physical environment they are placed in. For example, an application might require that two elements be placed within two feet of each other, but also that both be placed on an elevated horizontal surface. Second, a user might deploy several applications in the same environment, all of which must be laid out successfully without interfering with each other. Finally, several users might be collaborating using an AR application in a shared environment, further complicating the layout of the application elements.

In this paper we describe FLARE (Fast Layout for Augmented Reality), an application development system that enables targeting of AR applications to a variety of environments. In this system the layout of an AR application is designed using declarative rules, describing the desired mapping of the application elements to an environment. Each element has a state defined by a set of properties (e.e. position, scale, color). The declarative rules refer to these properties and to environment properties, and have a cost function associated with them. Mapping an application to an environment consists of finding an optimal (or close to optimal) state for all ele ments, such that the overall cost of the rules is minimized. Targeting several applications to a single environment, or sharing an applica tion between multiple users is translated in our system to additional rules constraining the system.

We canture the user's environment using a Kinect camera (RGR and depth streams), and process it using Kinect Fusion [25] to extract dense scene geometry. We detect planar surfaces in the room and label them as vertical (e.g. walls, cabinets), horizontal (e.g. floor, table) or other. Planar features are common in indoor scenes and are useful to many applications. Adding additional detectors (e.g. object detection, recognizing previously visited rooms) could enable more complex rules and applications. FLARE performs a real-time mapping of the application to the user's current enviror

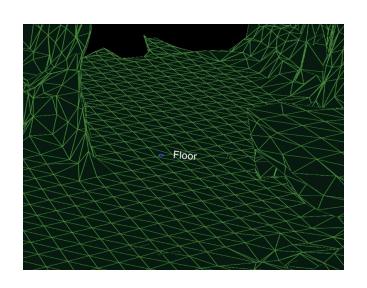






Spatial Processing HoloToolkit

- Basic Spatial Mapping
 - Access/Visualize Spatial Data
 - Save/Load Rooms
- Spatial Processing
 - Surface Meshes to Planes
 - •wall, ceiling, floor, table, unknown
 - •Floor Buffer
 - Ceiling Buffer
 - Custom Shape Definitions



VRDC









Development Kit Launched in Select Countries June 1st, 2014



Launched Worldwide November 1st, 2016



Tango Motion Tracking



- Visual-Inertial Odometry (VIO)
- Tracking image differences
- Inertial motion sensors
- Combined for greater accuracy
- Limits:
- Drift
- No memory
- Lighting



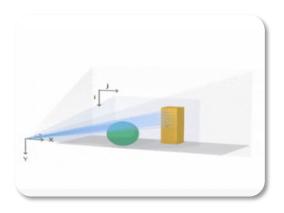
Tango Area Learning



- Simultaneous Location and Mapping (SLAM)
- Location memory
- Drift correction
- Limits:
- Mapping time
- Areas change over time



Tango Depth Sensing



- Point Cloud
- Infrared light
- Markerless AR
- Limits:
- Environmental
- 0.5 to 4 meters



Environmental Issues

- "I can't see." too dark
- "I am lost." featureless
- "I am dizzy." too fast







I can't see

Lam lost

Lam dizzy



Tango Development Environment

- ✓ SDK Options
 - C, Java, Unity
- ✓ UX Framework
- Active Community

























"In this mystery sleuthing title, you play an imprisoned spirit, trying to find peace by solving the mystery of your own death."



"It takes place in a spooky 3D mansion, and the entire game is controlled by walking around holding Tango."



"The room is merely projected through the Phab 2 Pro's 6.4-inch display, but because of its motion tracking mechanisms, I was able to keep my head inside the game despite not having the phone physically strapped to my face."







You MOVE, you live!

Stay - and you die!





- Must physically move to pick up items
- Level select by walking, not tapping
- Highly natural and intuitive!













Now – User Reliant Spatial Identification

- Walls
- Surfaces
- Objects



Next step - Spatial Understanding

- Spatial mesh just gives you collision.
- Segmentation
- Classification



Designing for Arbitrary Spaces

- Traditional design based on specific placement
- Experience composition at the time of use
- Rules and constraints design pattern



Responsive Environment Design

- Environment Composition at the time of use
- Rules and constraints design pattern
- Solvers and AI based layout



Environment Re-visualization









Bending Reality – XR

- VR influenced by the real world
- Tactile presence
- Moving between the real and the virtual







Subtraction = Magical







VS



- Infrared mapping
- Visual tracking
- Phablet
- Touchscreen
- Android
- Consumer
- \$499

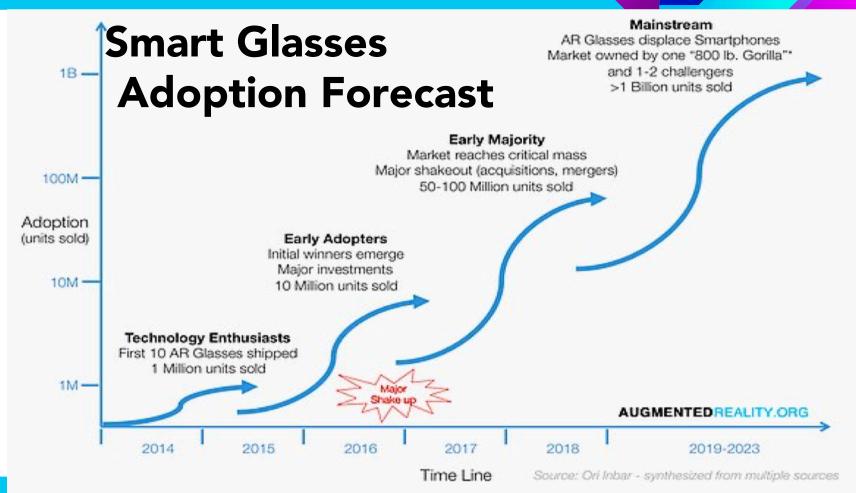
- Infrared mapping
- Visual tracking
- Headset
- Gestures
- Windows
- Enterprise
- \$3000

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Beyond Tango & HoloLens



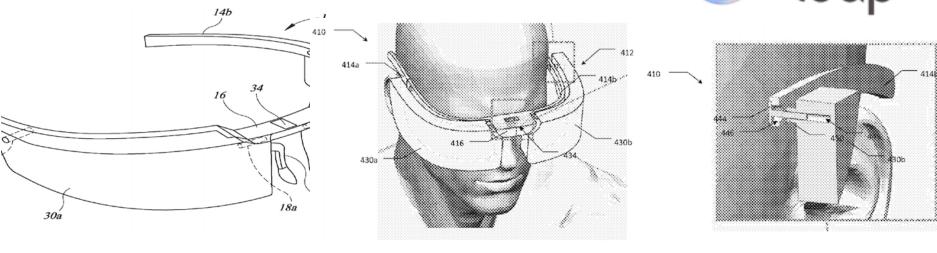


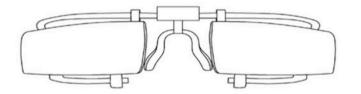


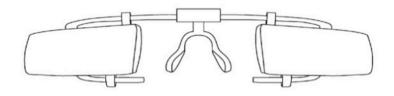


Ultimate AR Headset?

















Pokemon Go getting addictive with the R-7 glasses. Using ODG's ring controller to interact @CatchEmAll



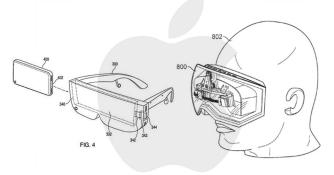
R-7 Smartglasses





Apple iPhone 7 Plus and Beyond

- Dual-cameras
- PrimeSense
- Metaio



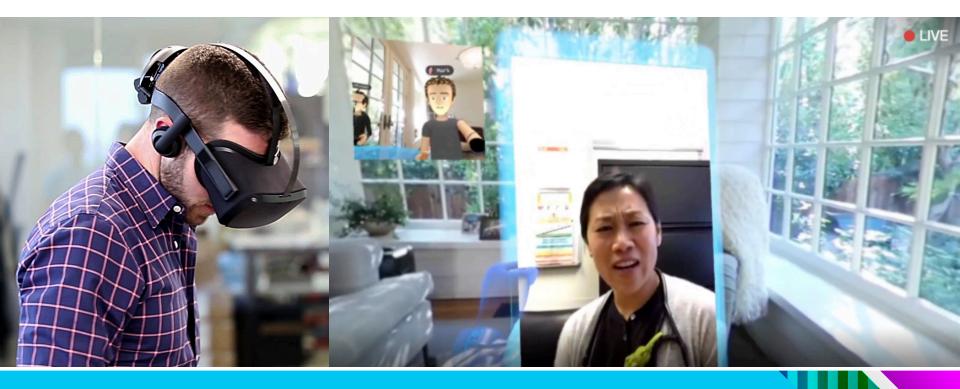








oculus Santa Cruz Prototype





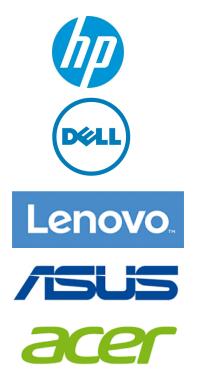
Project Alloy







Microsoft Democratizing VR + MxR







Summary

- HoloLens Enterprise MxR headset
- Tango Consumer MxR handheld device
- Embrace 3D motion controls
- Design for arbitrary spaces
- Develop for the future, today!

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Questions?

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