

A cinematic still from the video game The Last of Us Part II. The character Ellie is shown from the waist up, positioned on the left side of the frame. She has short, reddish-brown hair tied back and is looking off to the right with a serious expression. She is wearing a grey, short-sleeved button-down shirt over a dark t-shirt. Her left arm, which has a prominent tattoo, is holding a wooden rifle. The background is a dark, misty forest with bare trees, creating a somber and atmospheric setting.

Motion Matching in

# THE LAST OF US PART II

Michał Mach  
Maksym Zhuravlov



**Michal Mach**  
**Lead Animator**  
**@gameplayAnim**







**Maksym Zhuravlov**  
**Principal Animator**  
**@MaksZhuravlov**

# What is Motion Matching? Quick Recap

System was first presented to the gaming industry by:

- **Simon Clavet** (GDC 2016) – “Motion Matching, Road to next-gen animation”
- **Kristjan Zadziuk** (GDC 2016) – “Motion Matching, The Future of Games Animation... Today”
- **Michael Buttner** (Nucl.ai 2015) – “Motion Matching - The Road to Next Gen Animation”

In general, it works as follows:

- A piece of code we call Motion Model provides desired trajectory based on move stick extrapolation or AI pathing
- Every frame - all animations in the set and each single frame in them are being searched to find the best match in terms of pose and trajectory
- The frame of animation that matched closest is picked and gets played on the character
- Procedural adjustments applied
- Next frame - everything repeats again from step 1.



# Motivations

It was a bit step for us. Leaving the proven system behind and jumping straight into this novel technology that hasn't been really proven in a shipped game yet.

- We needed a **higher quality** and more **natural looking locomotion**
- Handling a **massive scope** at high quality
- Locomotion system **stability**
- It was **easy to try**

# Initial Implementation Problems

- Animation **playback continuity**
  - Slightly unstable animation selection for authored angles

## Initial Implementation

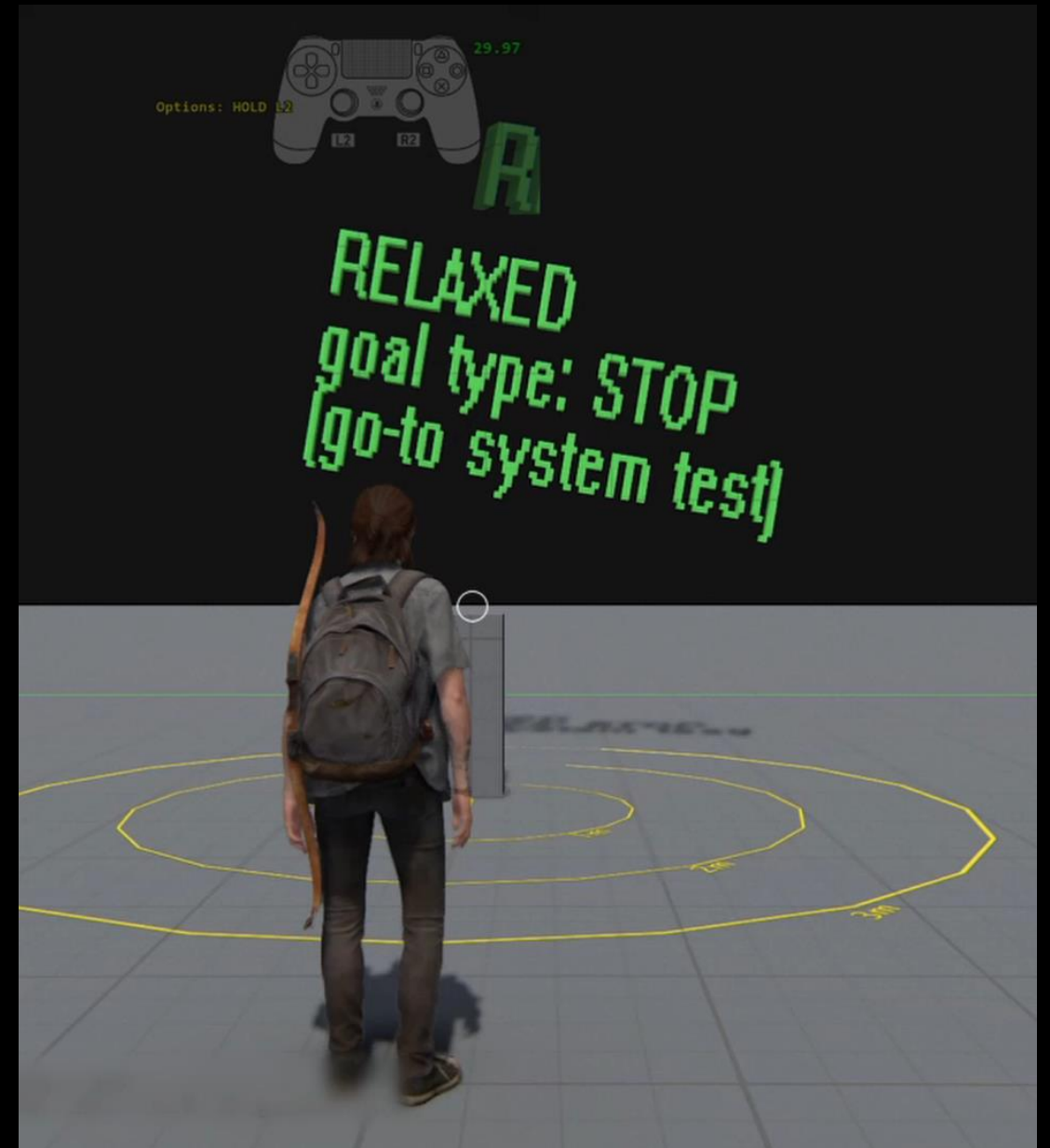
- Totally unstable animation selection for off angles

Woah! It works and looks amazing!

- Animations **"confusion"**

Many animations in the set share segments that have Sort of very similar trajectory and poses but serve a very different purpose

- Motion Matching is **not user friendly**
  - It works with information that is normally hidden to animators
- Transitions **handover** is bad.
  - Transitions tend to either "stuck" or get completely "swallowed" depending on settings







# Our take on Motion Matching

# Root Motion Node

The core node of the character that drives the capsule and root motion.

In our engine it's called **Align**.

All joints are animated and evaluated in **Align** space, therefore its accuracy is critical!

We **hand animate** it for every animation clip:

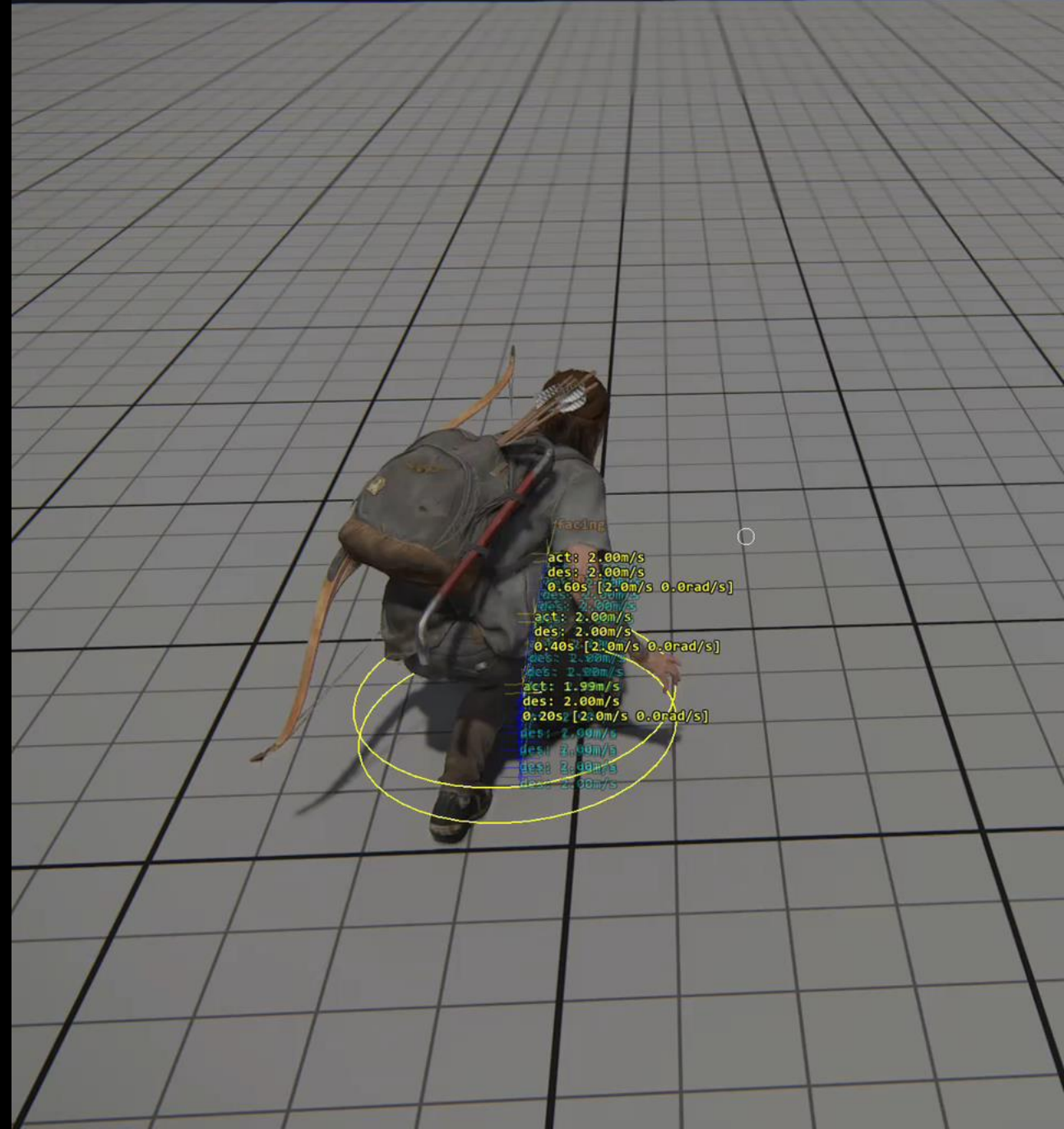
- Curves must be smooth (no weird tangents)
- Unnecessary lateral motion removed
- Align rotation animated in compliance to Motion Model setup
- Idle pose pasted where needed with exact align \ pose match



# Motion Model

Represents how the character's **Align should move** in the space and is our simulation of character motion

We use a critically damped spring to simulate **position** and **velocity** and we also simulate **turn speed** and **facing direction**



# Motion Models

- Stick Input Mode: **Strafing**, Player
- Stick Input Mode: **Non-strafing**, Player
- Stick Input Mode: **Cover**, Player
- **Horse** Motion Mode
- **Path Following** Mode: NPCs
- **Path Transition** Mode: NPCs

## Root Motion Allowance

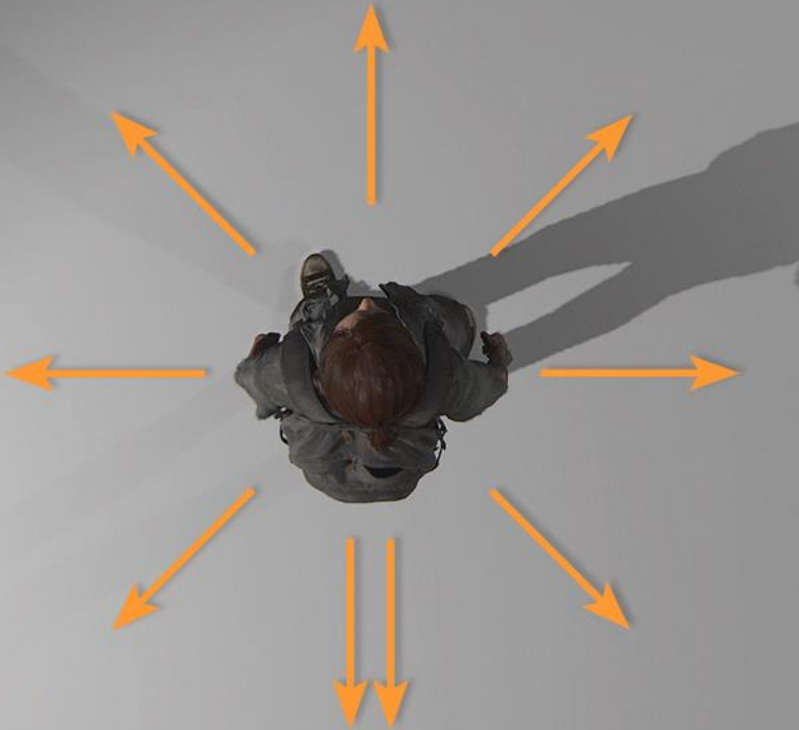
- **0.3 – 0.6** m for AI
- **None** for Player





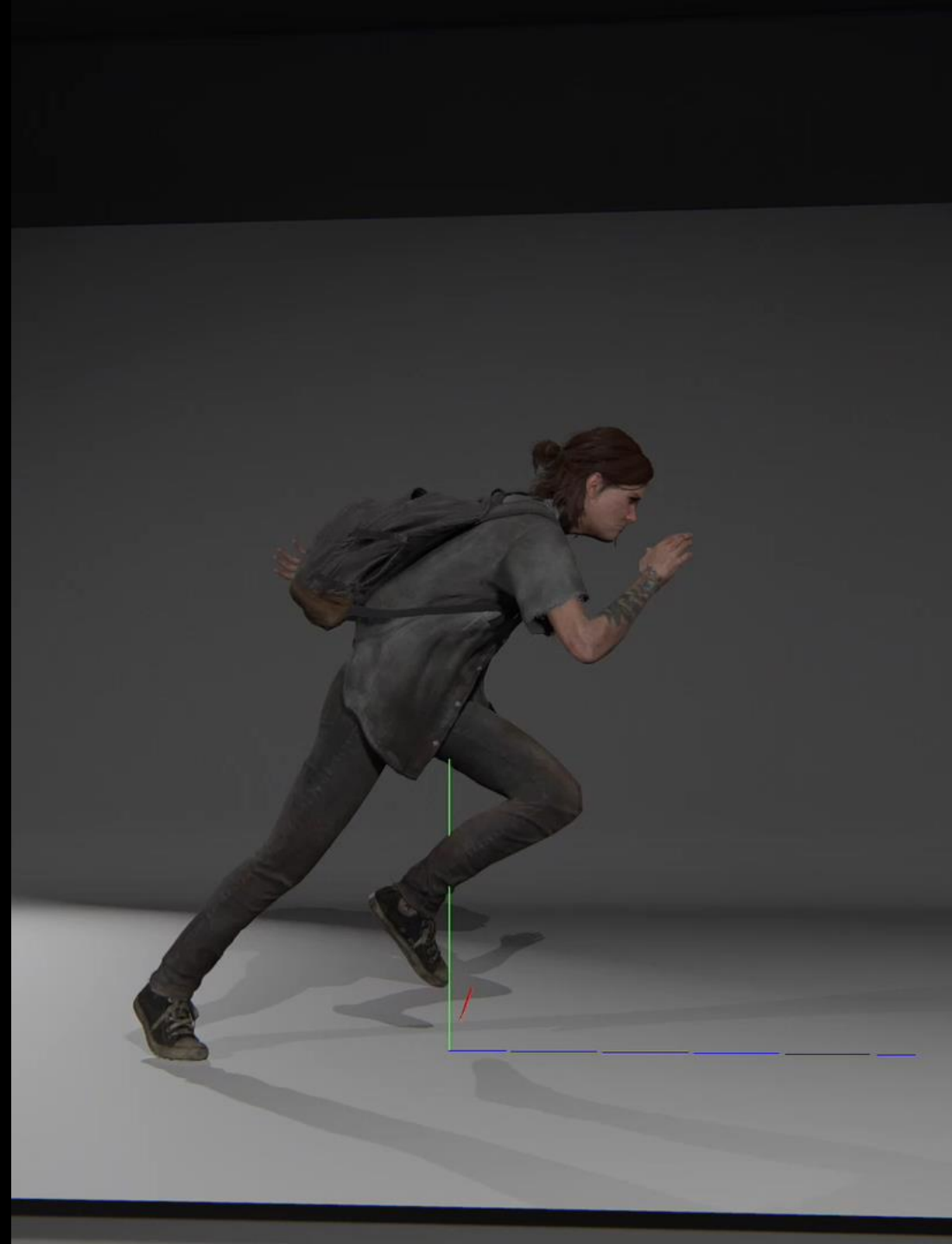
# Motion Model Parameters

- Most settings can be defined as **directional values**
- **Velocity spring** constant
  - **Acceleration** spring
  - **Deceleration** spring
- **Maximum speed** (m/s)
- **Turn rate** (degrees per second)
- Translation clamp distance (root motion allowance)



# Motion Matching Data Samples

- On average our individual sample vectors have around **100 floats** in them
- We match only data with **significant impact** on the motion.
- **Unnecessary** joints or trajectory **samples** is wasted **memory** and **performance**





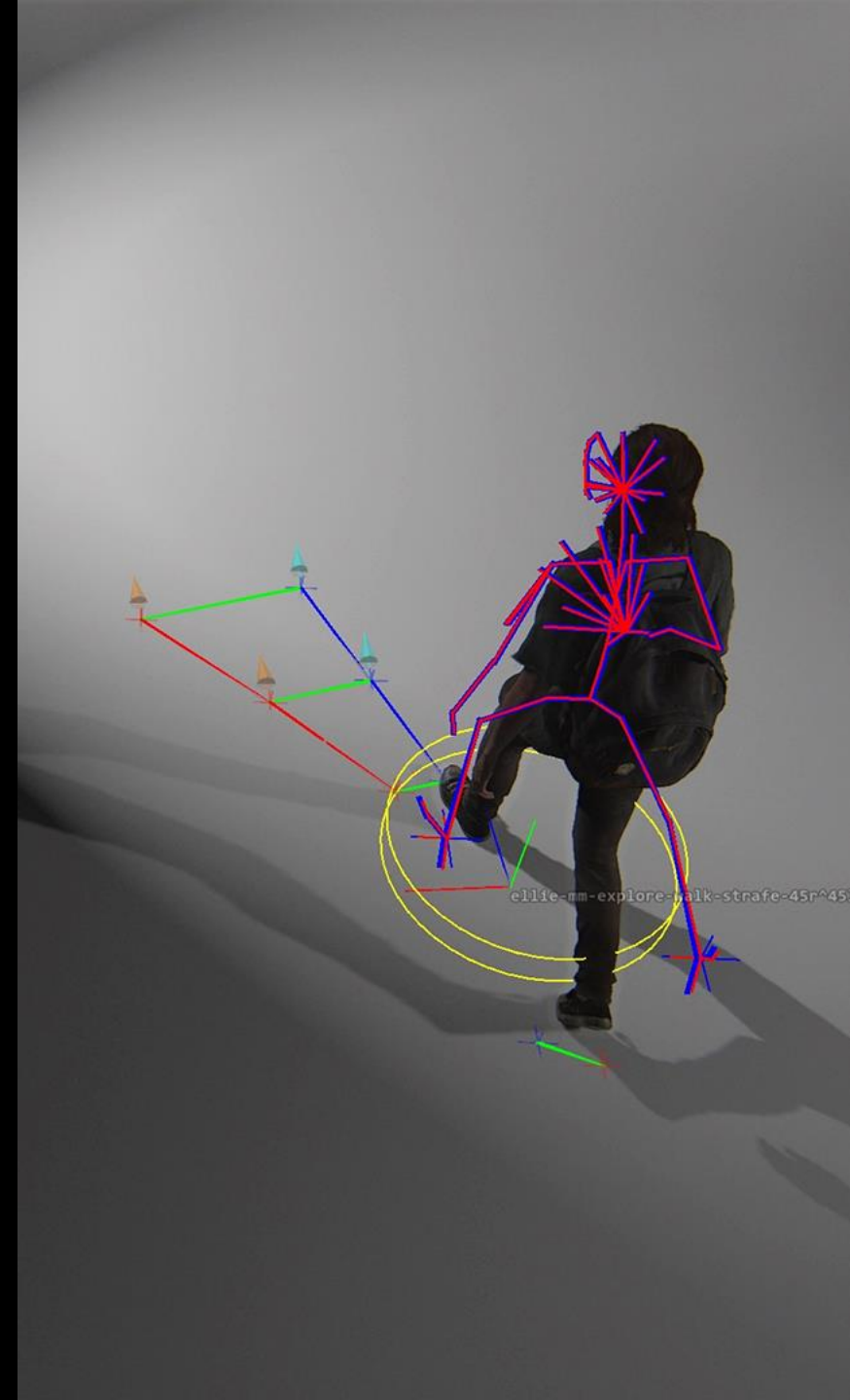
# Motion Matching Trajectory Sample

Enough trajectory points to capture a **simple shape**

- 3 samples up to **1.8s in the future**
- 1 sample up to **0.7s in the past**

## Sample Data

- Align Position
- Align Velocity
- Align Direction
- Align Turn Speed

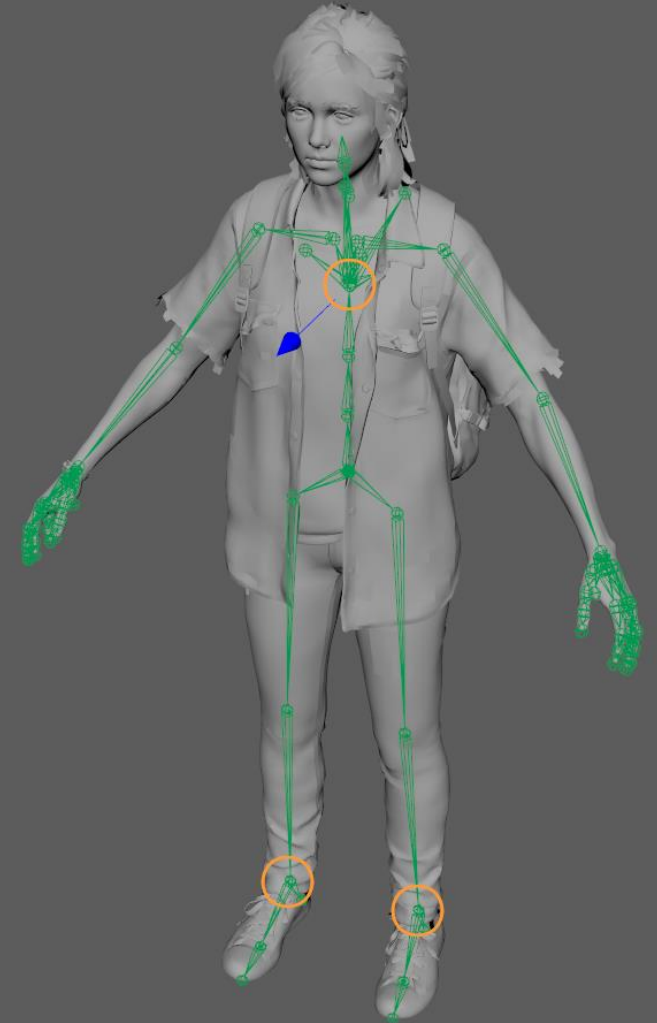


# Motion Matching Pose Sample

- Ankles to keep a **continuous gait cycle**
- Spine to capture the **body weight shifting** and **posture height**
- **Bipeds** — both ankles, top spine
- **Quadrupeds** — all four feet, one spine joint

## Sample Data

- Joint Position
- Joint Velocity
- Facing Axis — typically a top spine joint forward axis





# Animation Data

We don't mocap **unstructured data** or **long dance cards**.

- Directing and **performing long takes** is uncomfortable
- A lot of **redundant data**
- Animation **polish and editing is inconvenient** on very long takes

Instead, we direct **medium to short** takes depending on complexity of locomotion and how well the actor is managing performance / volume of this set

# Player Specific Animation Data

Premise:

- Animations shouldn't “shred” on straight inputs
- Transitions should play out in full on straight inputs
- Animations will be heavily polished in post and can deviate from raw MoCap
- Any director's note should be straight forward to address
- Animation subsets should be easy to reuse across similar locomotions
- Complete freedom to direct MoCap sessions as see fit



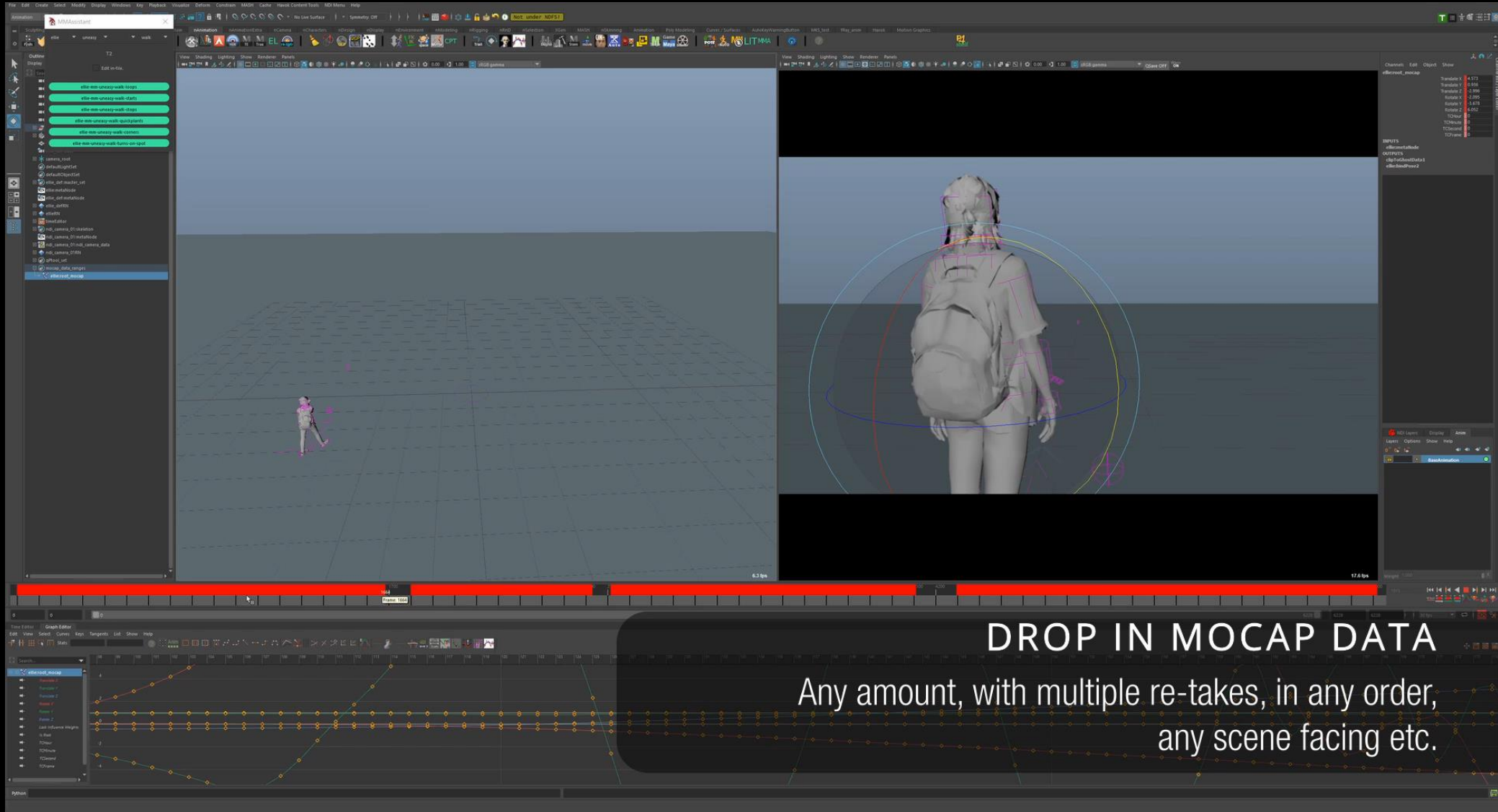


# Player Specific Animation Data

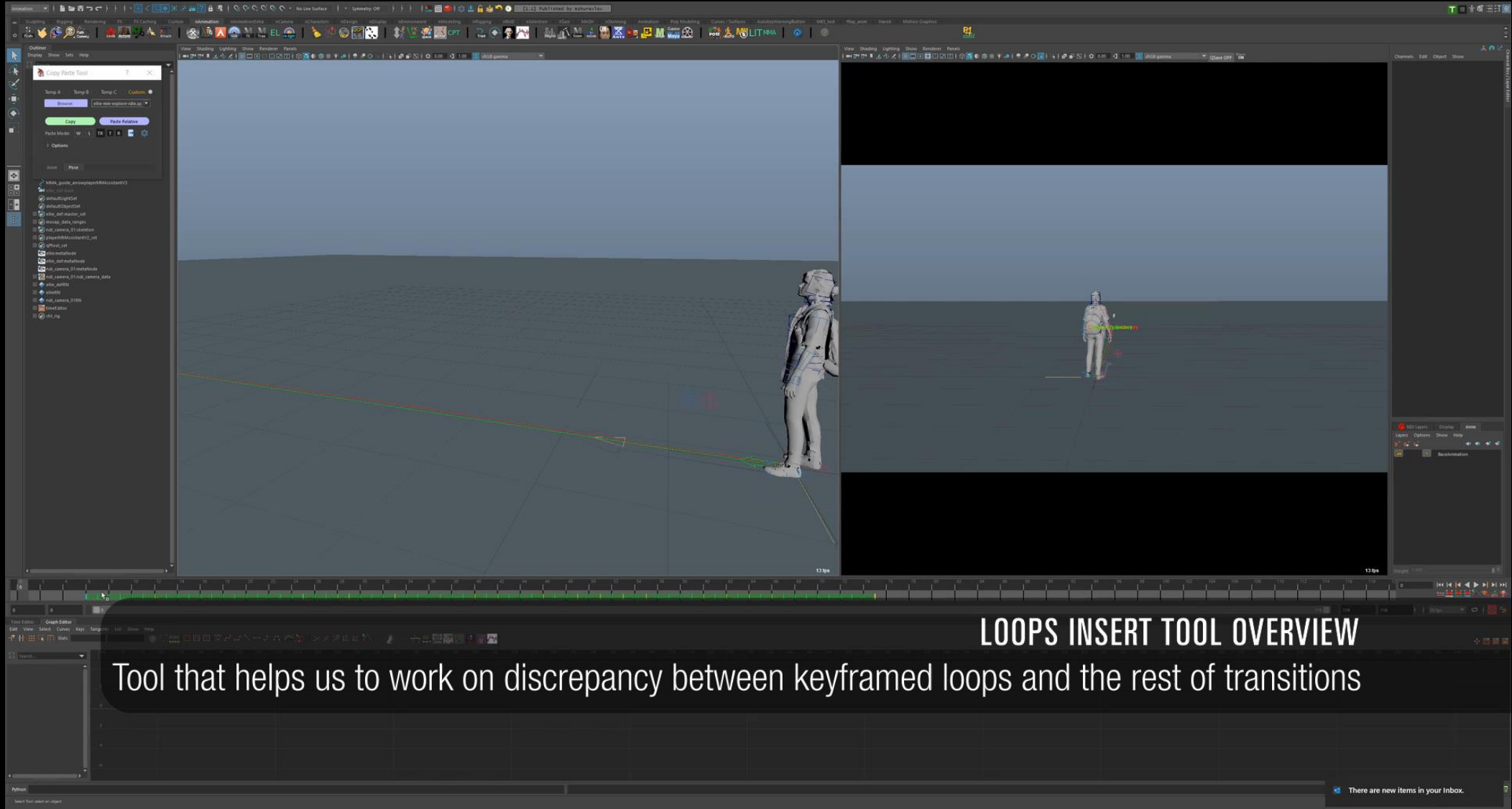
Early discoveries:

- **Minimum-enough** coverage is good for the player mm system and artist both
- Animation “**heads**” and “**tails**” should be of **specific controlled length**
- It is still **vital** to bracket animations with **core poses**
- Sets polish and editing is **greatly** more **stable** and **comfortable** when transitions are split per file and named according to the convention

# Player Specific Animation Data (Set Authoring)



# Player Specific Animation Data (Polish)





# Player Locomotion Total

2627 animation clips

2 hours and 17 minutes of animation data

\*Ellie and Abby Players combined

# NPC Specific Animation Data

## Challenges:

- Huge cast of characters of different sizes, genders, species, using different demeanors
- We wanted the NPC locomotion to look as natural as possible with proper weight
- NPCs need to be able to keep up with player



# NPC Specific Animation Data

## Premise:

General playback continuity requirements are same as player's with addition of

- No foot sliding (or very minimal)
- Allow AI to maneuver with minimal restrictions
- Be able to navigate the space with precision
- Be able to enter cinematic sequences seamlessly





# NPC Specific Animation Data

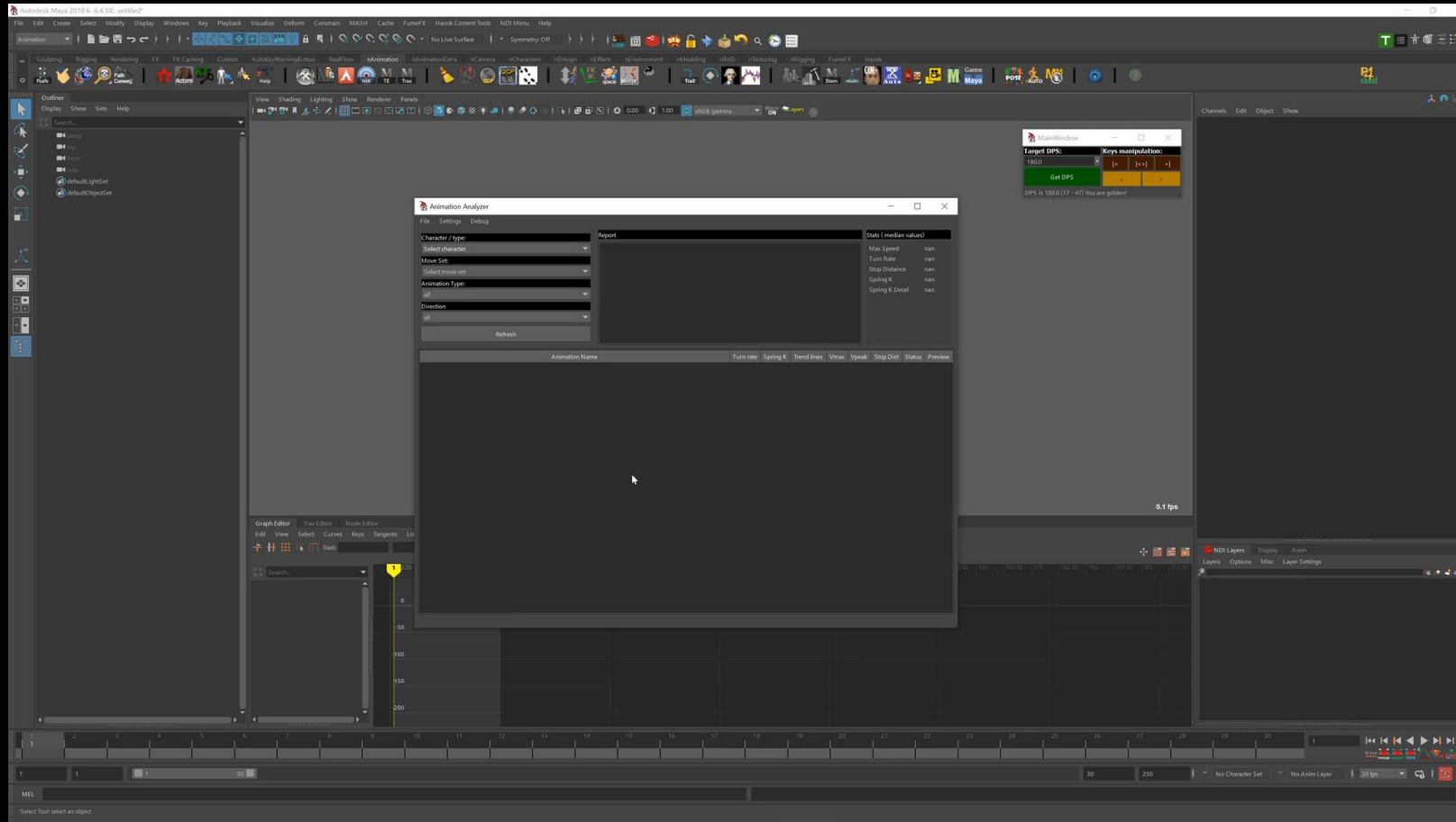
- Human NPCs **share move sets** to save time and memory
  - **Male and female enemies** use the same **androgenous move sets**
  - **Combat** move sets are **shared across the board**
  - **Buddies** have **male and female specific** relaxed move sets
- We've built the **initial move sets** using **motions we were expecting** the characters to do
- It's easy to add more moves later and **fill in the gaps**
- All moves have **left foot and right foot variants**
- We did a lot of post processing but not as much as player team did
  - Straightening trajectories, pasting poses relative to the Align, we didn't insert loops
  - The Maksym's tools were not available to us at the time but we're adopting them

# NPC Specific Animation Data

- We can mirror animations and technically double the dataset
- Data consistency is key to Motion Matching
- We've semi-automated generating the Align trajectory
  - It still needs to be touched up because Maya's auto tangents cause velocity spikes
- In order to preserve the natural motion, we needed to marry the animation data and motion model

But we didn't even know what data we have...

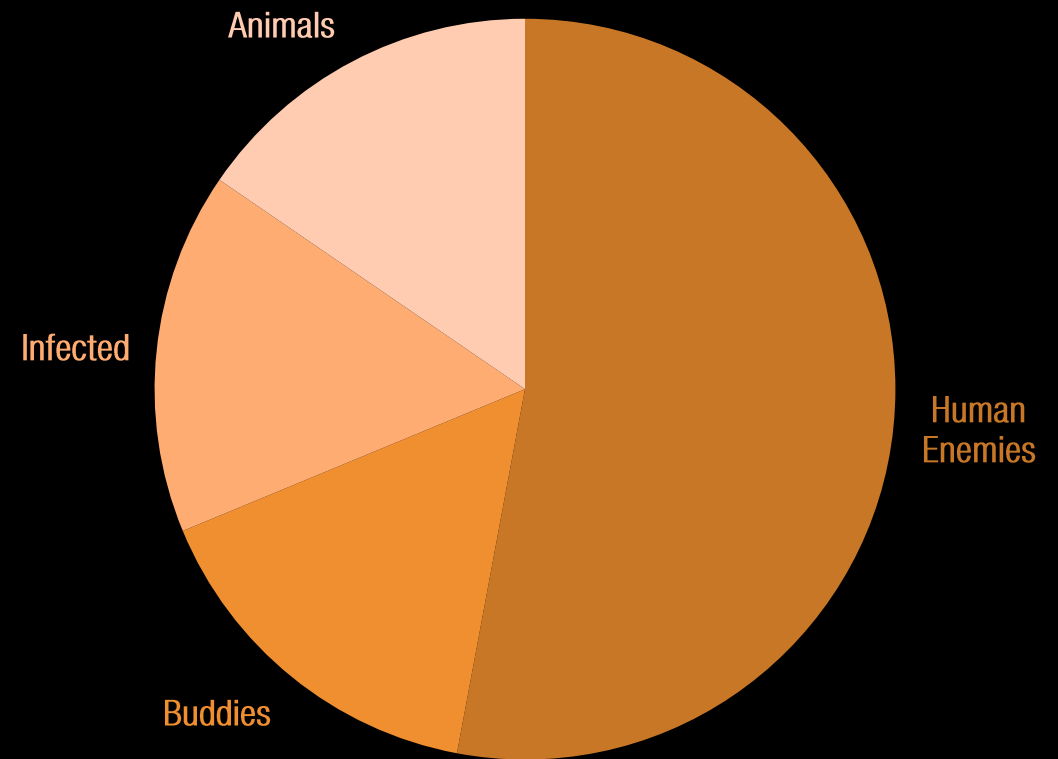
# Animation Analyzer (full screen video)





# NPC Locomotion Statistics

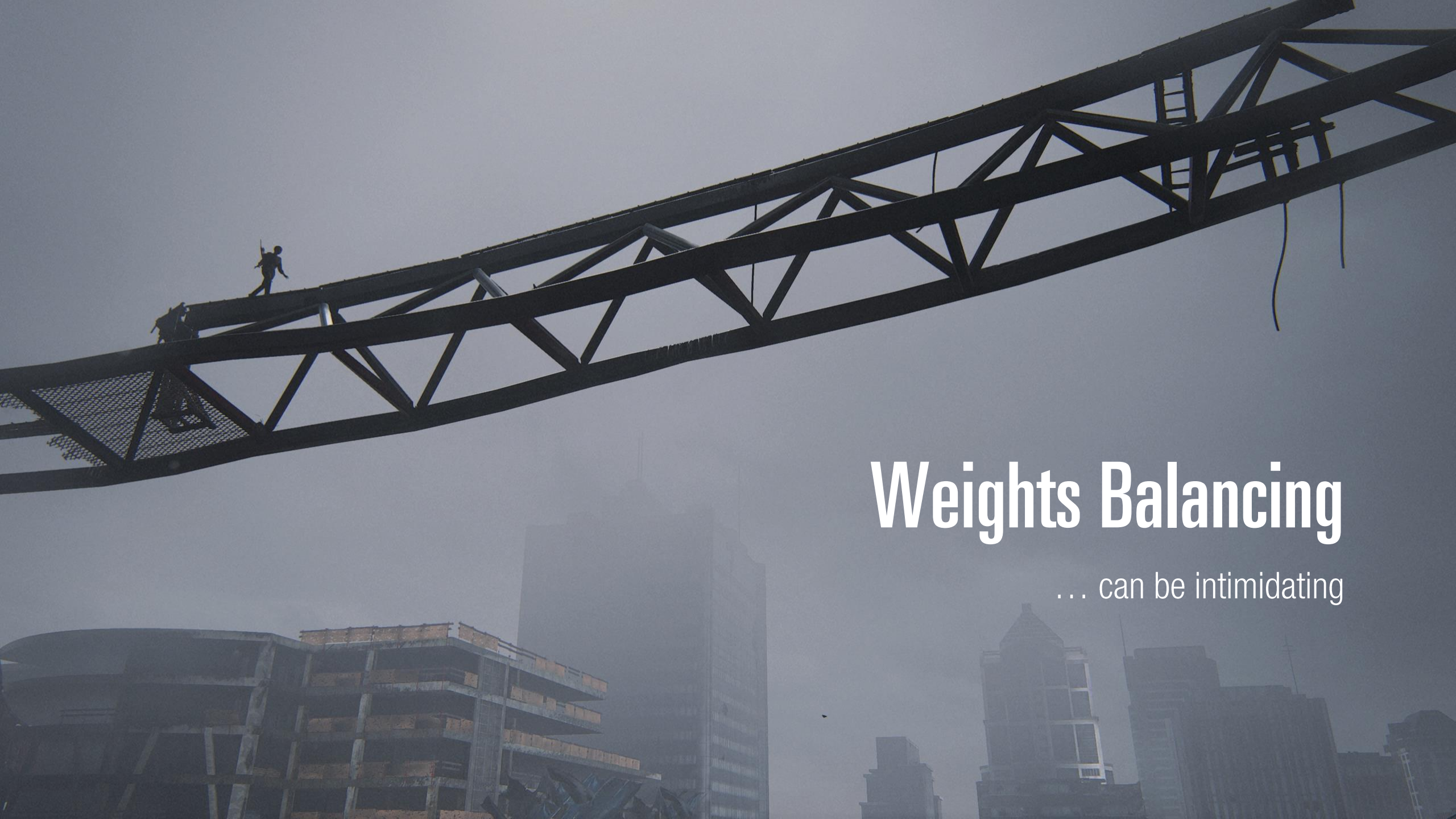
- **Human Enemies**
  - 2387 animation clips
  - 2 hours and 24 minutes
- **Buddies**
  - 678 animation clips
  - 43 minutes
- **Infected**
  - 768 animation clips
  - 43 minutes
- **Animals**
  - 431 animation clips
  - 42 minutes



# NPC Locomotion Total

6050 animation clips

6 hours and 34 minutes of animation data



# Weights Balancing

... can be intimidating



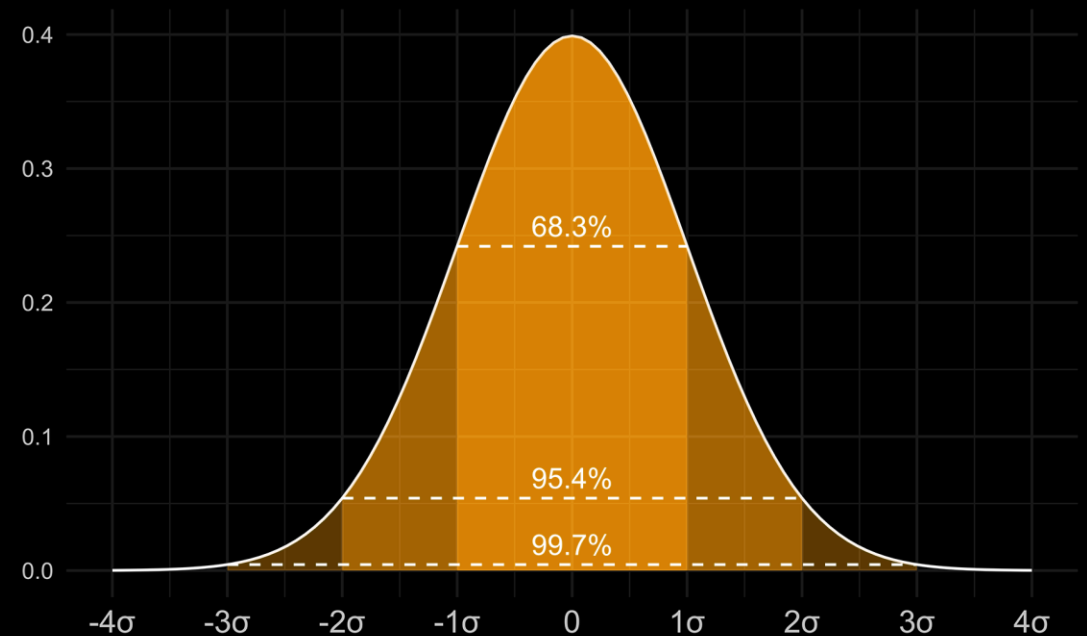


# Weights Balancing

- Balancing weights can be an intimidating process
  - Too many numbers
  - The **numbers change** when the **data change**
- We **group individual weights** into Pose or Goals groups
- Master **multiplier for each group**
- Having a **structure** allows for **faster iteration**

# Data Normalization

- We normalize our data ranges
- Let's us compare features with significantly different value ranges
- Gives us a normal distribution where  $\sigma = 1$
- Typically, velocity values are much larger than positional values
- Much easier to understand when comparing costs



# Grouping & Biasing

In general Motion Matching struggles with differentiating moves of a similar trajectory.

To assist it we introduced ways to help the system differentiate animations within the set.

- Natural Bias
- Core Loops Group
- Moving Group
- Custom User Layers



# Natural Bias

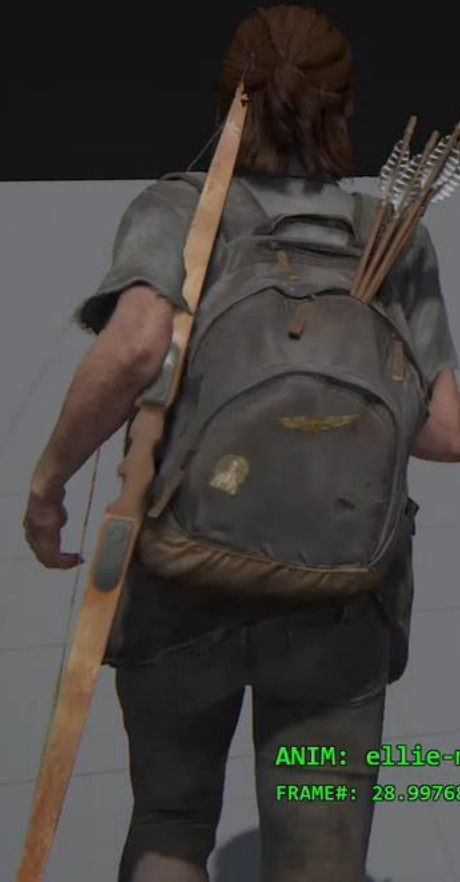
There's a high chance we want to keep playing what we're currently playing

- Biases currently playing animation and frame
- Helps reduce animation skipping
- Cannot be too high otherwise animations feel too “sticky”

# Core Loops Group

- A list of animations that we prefer to play when **input is steady**
  - Loops
  - Idle
- **Prevents** character from **getting stuck** in a stopping animation
- **Prevents** system from **stitching pieces of animation together** for off angles (non-45 degrees)

Bias Off



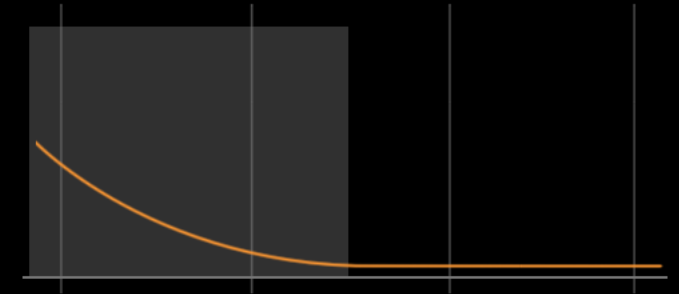
ANIM: ellie-mm-explore-run-fw^arc-45r^run-fw-1-foot  
FRAME#: 28.9976880.2

# Moving Group

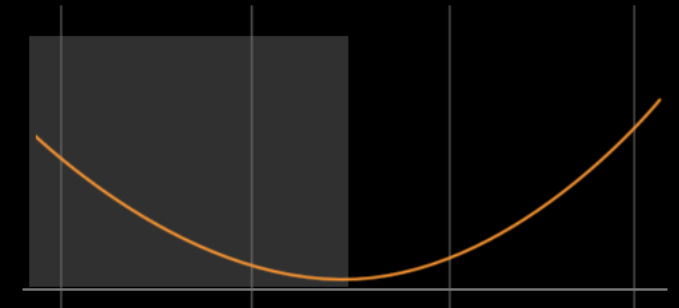
Our system kept confusing stopping and direction changing animations because piece of their trajectory is very similar.

- Added a **list of animations** where character “**wants to be (keep) moving**”
- Other animations are in the default group
- We **switch** between groups
  - **Player** - based on **Motion Model speed** that is further sprung to filter out temporal speed changes
  - **NPCs** — higher logic based on **locomotion state**

Stopping Animation

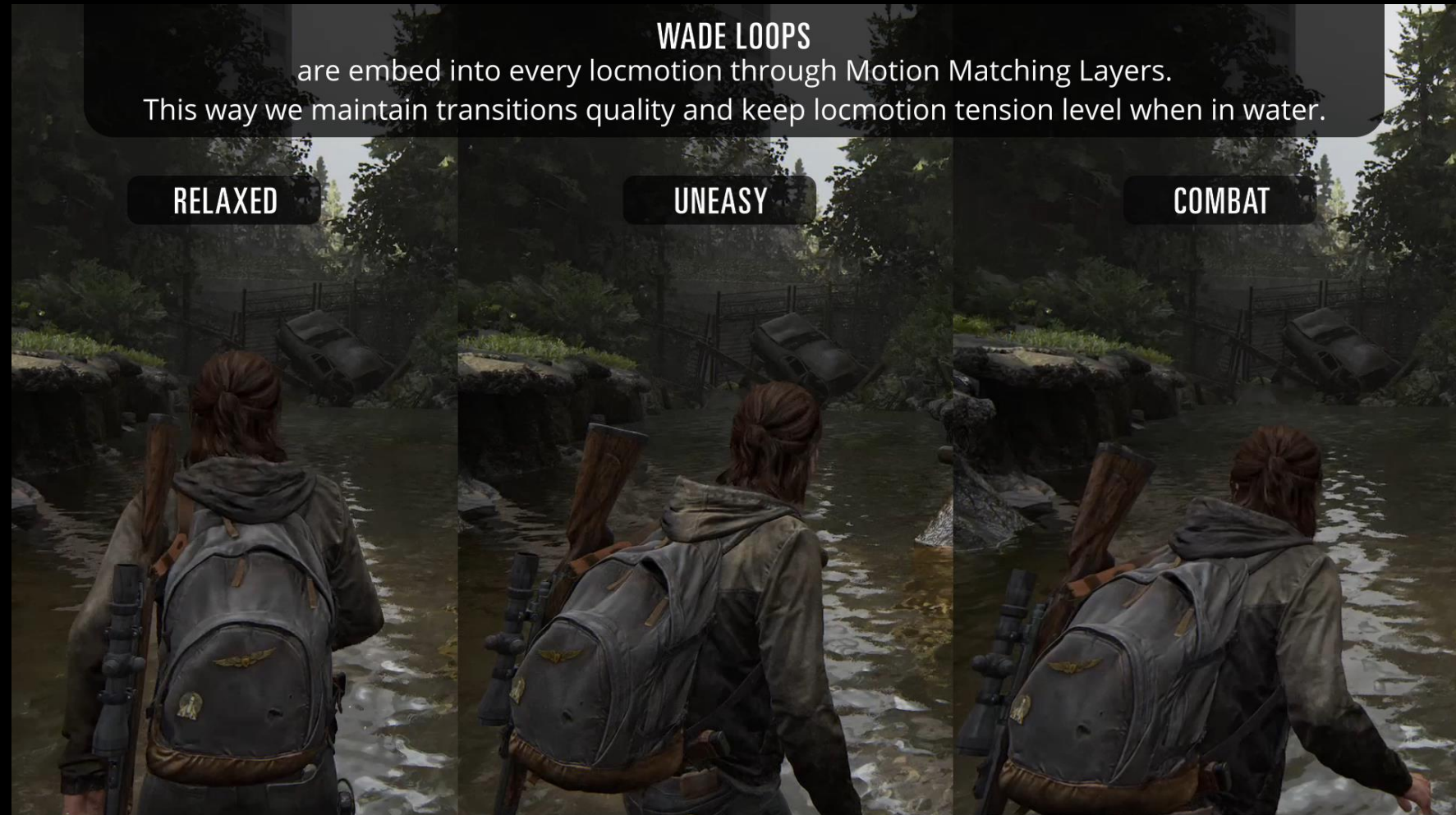


Foot Plant Animation



# Custom User Layers

## Custom User Layers





# Weighting Strategy: Player

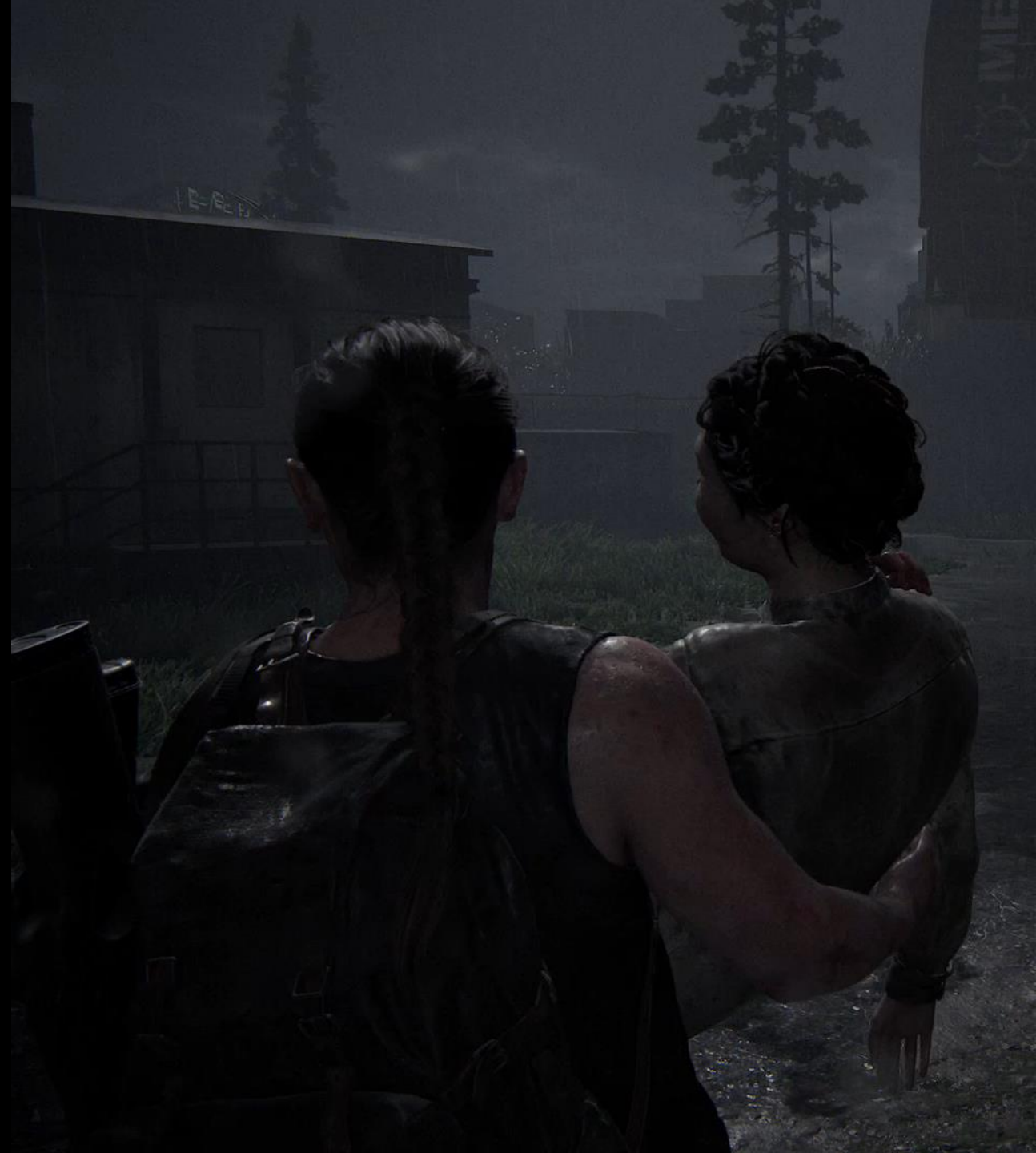
Player specific challenges:

- **Stiff** Motion Model **Springs** by design (acceleration and deceleration happens faster than in real life )
- **Lack of future** trajectory **prediction**
- **No** root motion **offset allowed**
- Close camera placement demands really **solid connectivity** between animations

# Weighting Strategy: Player

Strategy:

- High pose cost (1.3-1.5 times on trajectory cost)
- Compulsory use of previous trajectory goal (0.4-0.7 sec)
- Medium-far future trajectory (1.2-1.8 sec)
- Low current velocity cost
- Low grouping bias, medium continuous playback bias
- Transitions get dropped by absence of future samples, rather than by the cost (that's why we cut them to a specific length earlier in presentation)



# Weighting Strategy: NPCs

## Challenges:

- Generated **paths** are series of **straight segments** therefore quite **different** from **smooth animated trajectories**
- We wanted to keep the **motion** as **realistic** as possible
- We needed the locomotion to be **precise**, but we couldn't **slide the characters around** much
- Players can clearly see the whole character therefore any **motion discontinuities** or **foot sliding** are **obvious**

# Weighting Strategy: NPCs

Strategy:

- Short to medium trajectory length (0.5 – 1.2 sec)
- High trajectory cost (1.2 - 1.5 times the pose cost)
- High directional weight so NPCs face the direction we need
- Low Natural Bias to not hamper the movement precision
- Introduced a few new features
  - Yaw Speed Weight – to differentiate between turning and done turning trajectory goals
  - Interim Directional Weight – to further increase directional stopping precision
  - Stopping Face Distance – when to start rotating the facing vector before reaching the goal



# Animation Blending

Animation blends tend to wash out the character motion therefore trajectory starts falling behind quickly

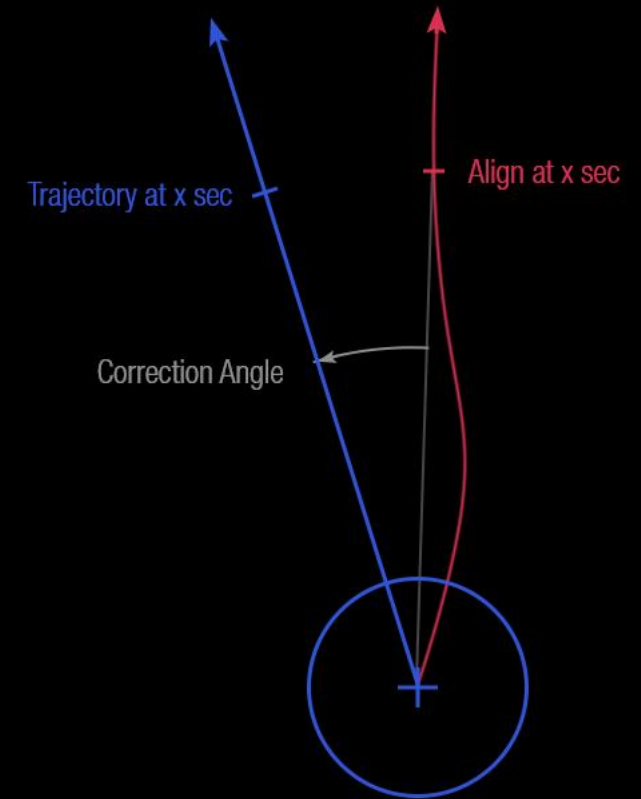
- We can **blend** root motion and skeletal animation **at different rates**
- Motion blend 0.2 - 0.3 sec vs 0.4 - 0.6 sec animation blend
- We can specify **custom blending settings** for every **pair of MM sets**
- We can setup **custom blend time** for any **animation clips** pair on top of that

# Procedural Pass

## Filling in the gaps for free

# Procedural Pass: Steering

- Compares **future** trajectory and Align **positions**
- Rotates Align to put future Align on trajectory
- Rotation error **distributed over time**
- **Configurable** per move set



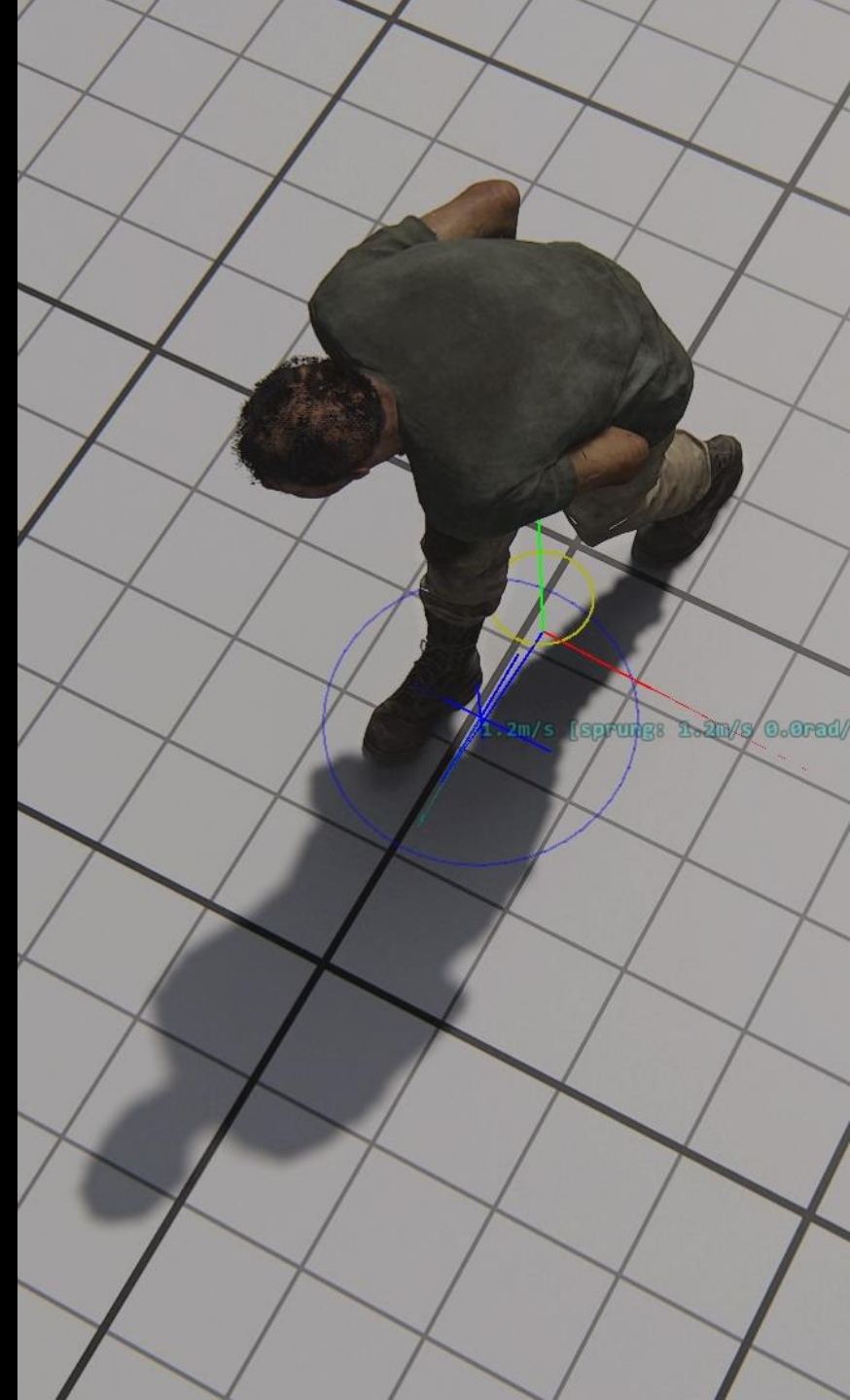
# Procedural Pass: Time Scaling

- We time scale animation clips to **compensate for trajectory differences**
- Normally  $\pm 10 - 15\%$
- Time scale **coefficient is on a spring** which prevents instantaneous changes



# Procedural Pass: Clamping

- Locomotion is **animation driven**
- We allow the Align to **drift away from Motion Model**
- Align is constrained to the clamp distance **radial constraint**
- Basic constraint has a **hard edge**
- **Soft clamp** variant tracks towards center using a **low pass filter**



```

[left-foot ][heel h:0.223, sh:4.211, sv:3.323]
[left-foot ][ball h:0.087, sh:2.449, sv:2.411]
[left-foot ][toe h:0.014, sh:1.560, sv:2.335]
[right-foot][heel h:0.047, sh:10.679, sv:0.455]
[right-foot][ball h:0.100, sh:9.819, sv:1.349]
[right-foot][toe h:0.106, sh:9.649, sv:2.251]
[front-left-foot ][heel jnt doesn't exist]
[front-left-foot ][ball jnt doesn't exist]
[front-left-foot ][toe jnt doesn't exist]
[front-right-foot][heel jnt doesn't exist]
[front-right-foot][ball jnt doesn't exist]
[front-right-foot][toe jnt doesn't exist]
FootPlant, ImplementationMode:BallPlantMode
Blend curve [right-foot]: 0.000, 0.000
Blend curve [left-foot]: 0.500, 0.734

```

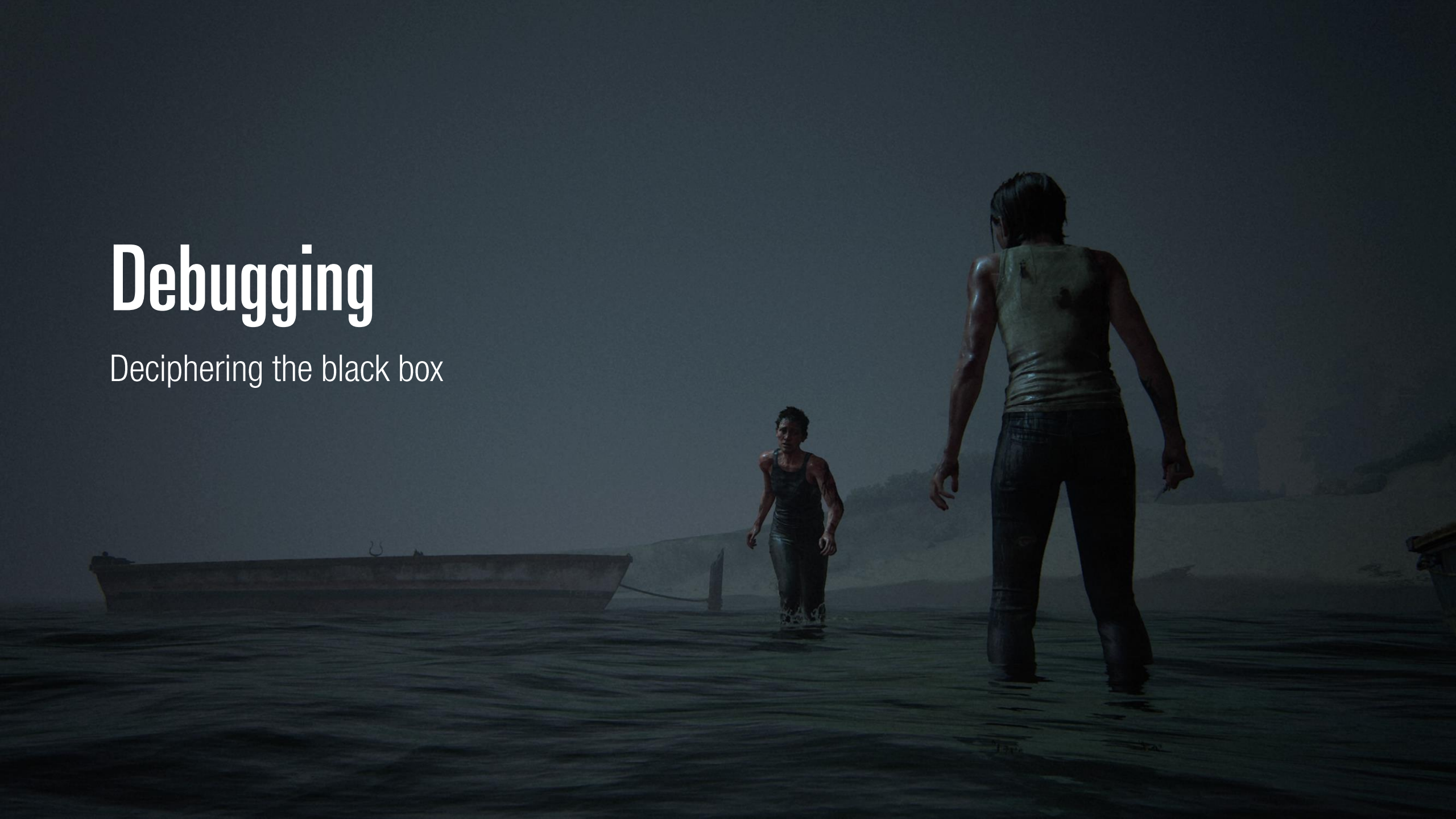
# Procedural Pass: Foot Plant IK

- Post process **running all the time** when locomoting
- Game **tracks ankle** joint positions **every frame**
- We **pin the foot** to its stationary position when below a certain threshold
- **Jacobian IK** solver
- Work for **bipeds** and **quadrupeds**



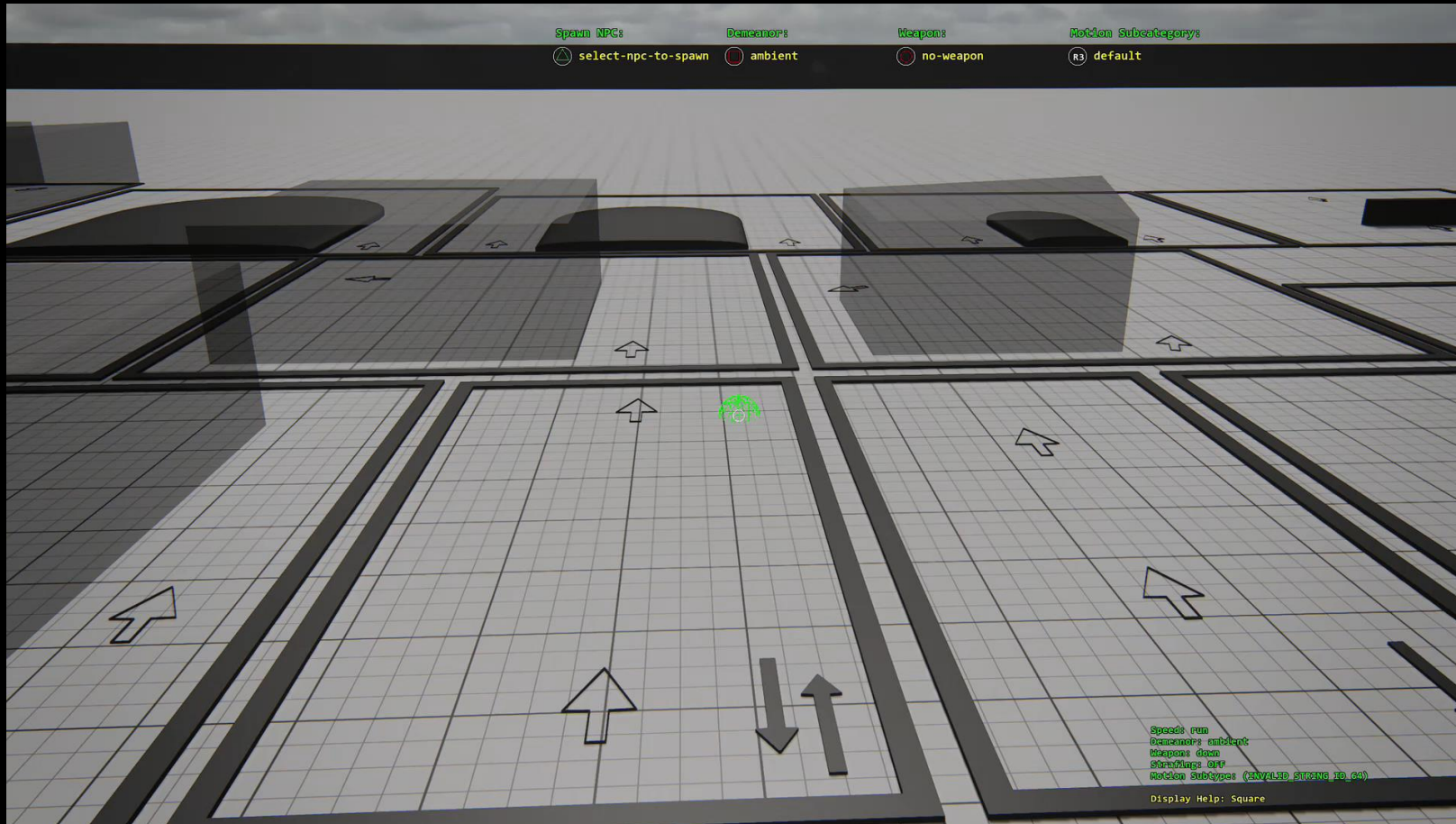
# Debugging

Deciphering the black box



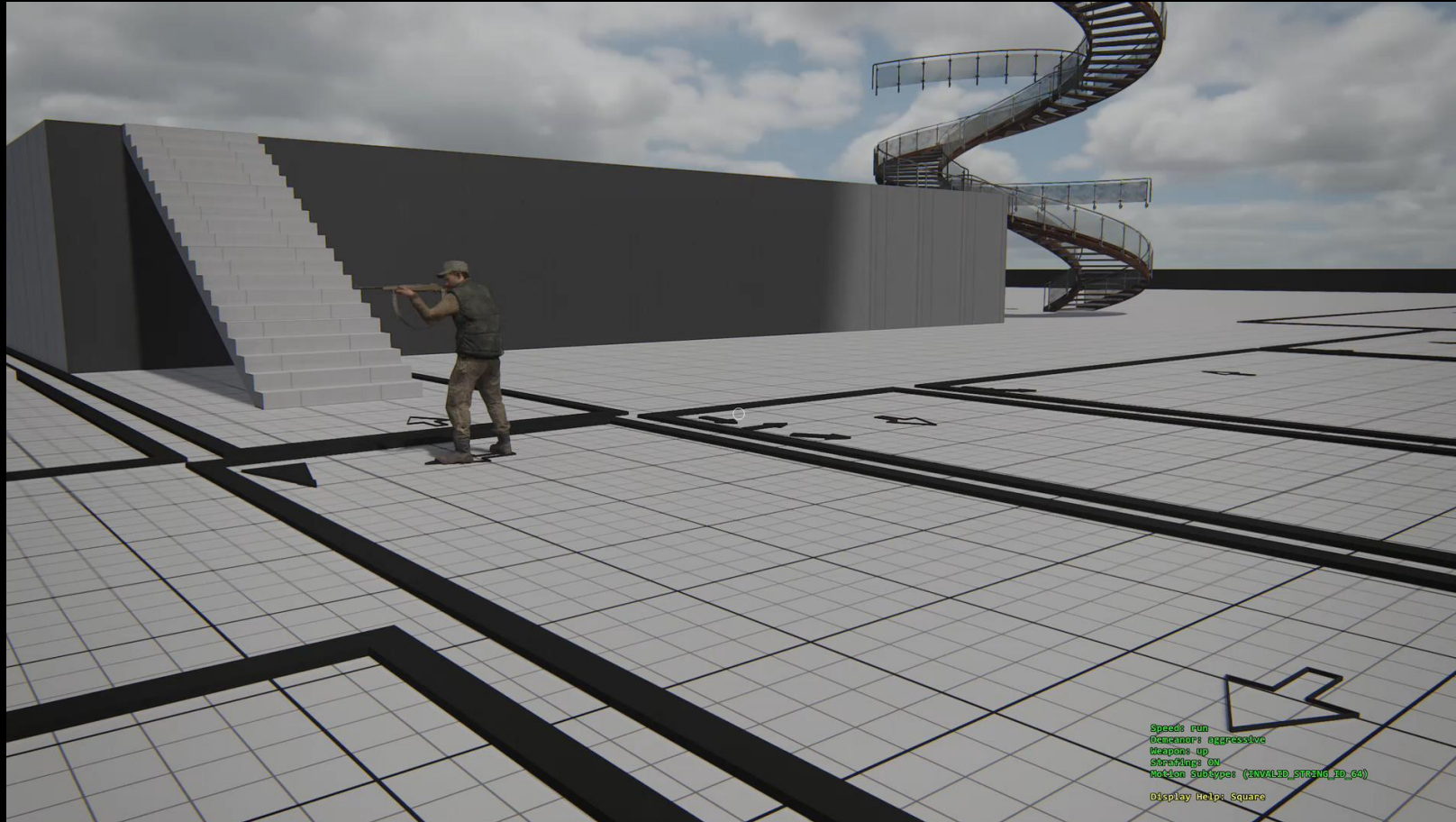


# Motion Matching Test Cases (full screen video)



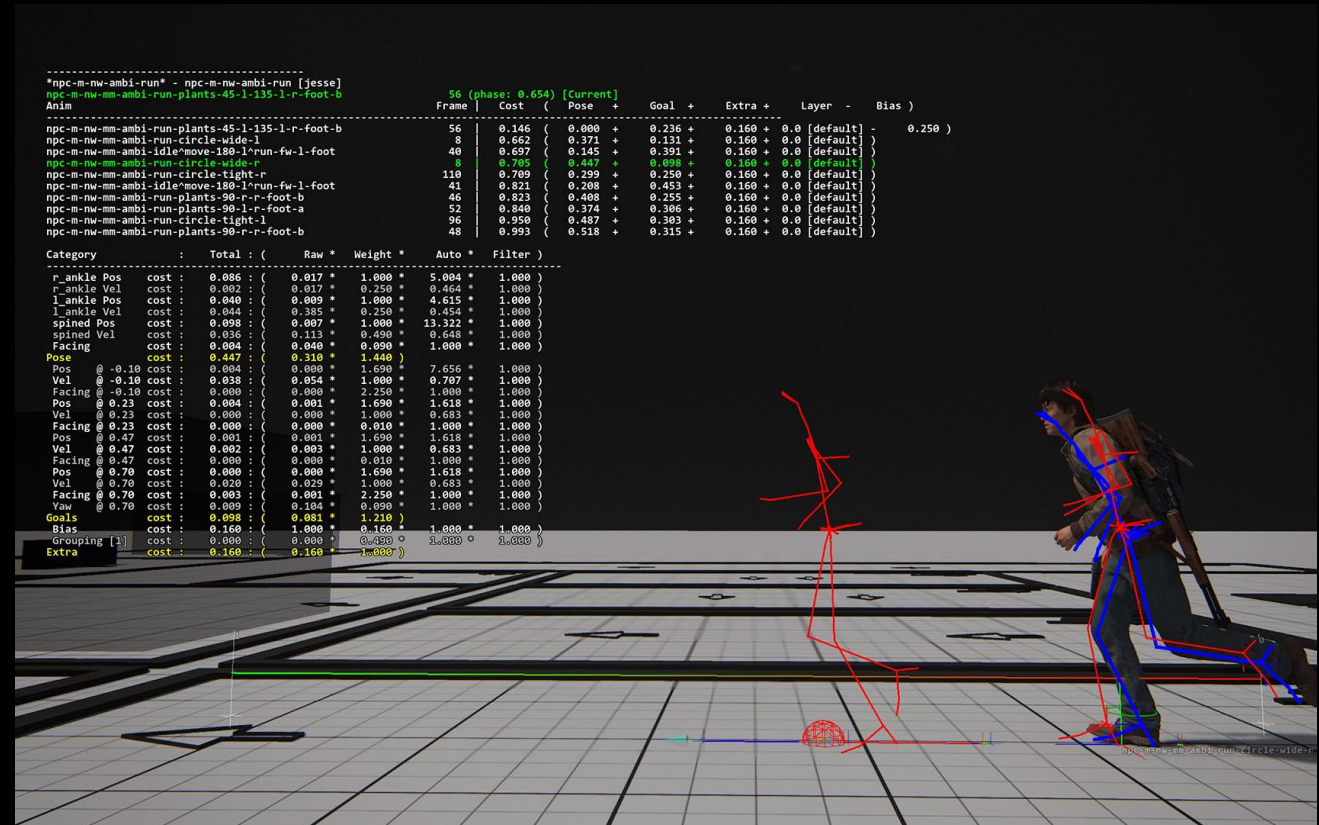


# Motion Matching Test Cases Strafing (full screen video)



# In-Game Motion Matching Debug Draw

- List of best animation samples with their costs
- Cost breakdown for the selected sample
- Current character pose (blue stick figure)
- Stick figure playing selected animation sample (red)
- Animation Trajectory (red)
- Motion Model trajectory (blue)





# Debugging Motion Matching Sets (full screen video)





A man in a grey tank top and dark pants stands with his arms outstretched in a lush, futuristic garden. The garden is filled with green plants and yellow flowers. In the background, there are large, realistic sculptures of whales, a globe, and a building with a curved, modern design. The scene is lit with soft, natural light, creating a serene and inspiring atmosphere.

# Connecting With Other Systems



# MM Idle Recovery



# Player Scripted Move-to

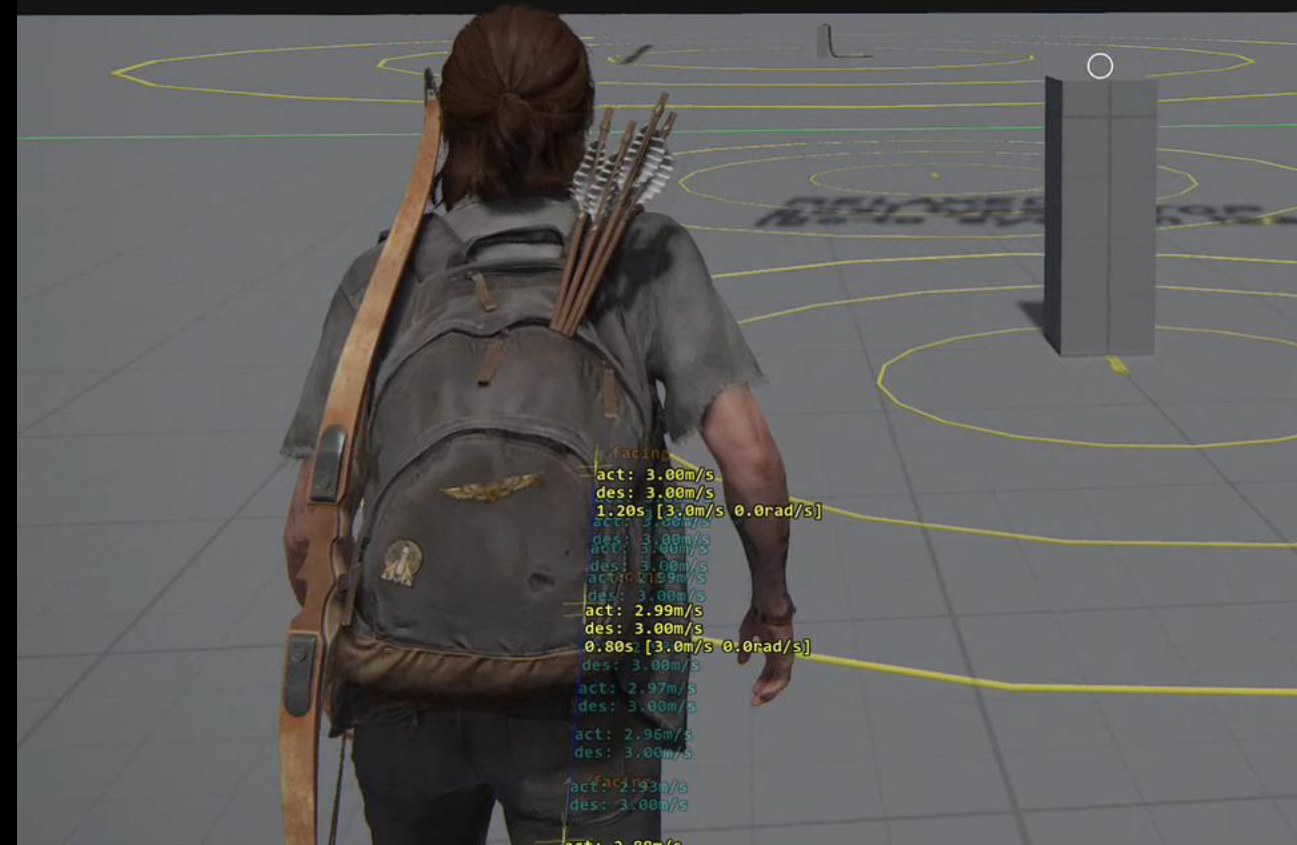
- We have a **strafing** with **free idle camera** locomotion scheme design. It poses quite of a challenge for a move-to
- We wanted approaching interaction target to **look natural** and have humanly appropriate deceleration
- We wanted approaching interaction **to look intentional** in terms of body language
- We still **slightly pull the player** into the target as distance to the goal becomes short

## Player Scripted Move-To: Strafe Run

ANIM: ellie-mm-explore-run-loop-fw  
FRAME#: 69.1934890.2



goal type: STO  
go-to system



facing  
act: 3.00m/s  
des: 3.00m/s  
1.20s [3.0m/s 0.0rad/s]  
act: 3.00m/s  
des: 3.00m/s  
act: 2.99m/s  
des: 3.00m/s  
0.80s [3.0m/s 0.0rad/s]  
des: 3.00m/s  
act: 2.97m/s  
des: 3.00m/s  
act: 2.96m/s  
des: 3.00m/s  
act: 2.93m/s  
des: 3.00m/s  
act: 2.90m/s

# Exiting "Canned" Animations

- There is **no additional setup** on the door animation, except of abort frames
- MM does a pretty good job of capturing pose, speed and current stick request and shuffles in the best animation available in the set
- This behavior allowed us **to use full body animations more confidently** in the context of responsive gameplay without worrying too much about exiting part of the systems

## Transition from "canned" anim to loco

ANIM: ellie-mm-tense-idle^sprint-fw  
FRAME#: 9.5162740.2



Move Stick Forward



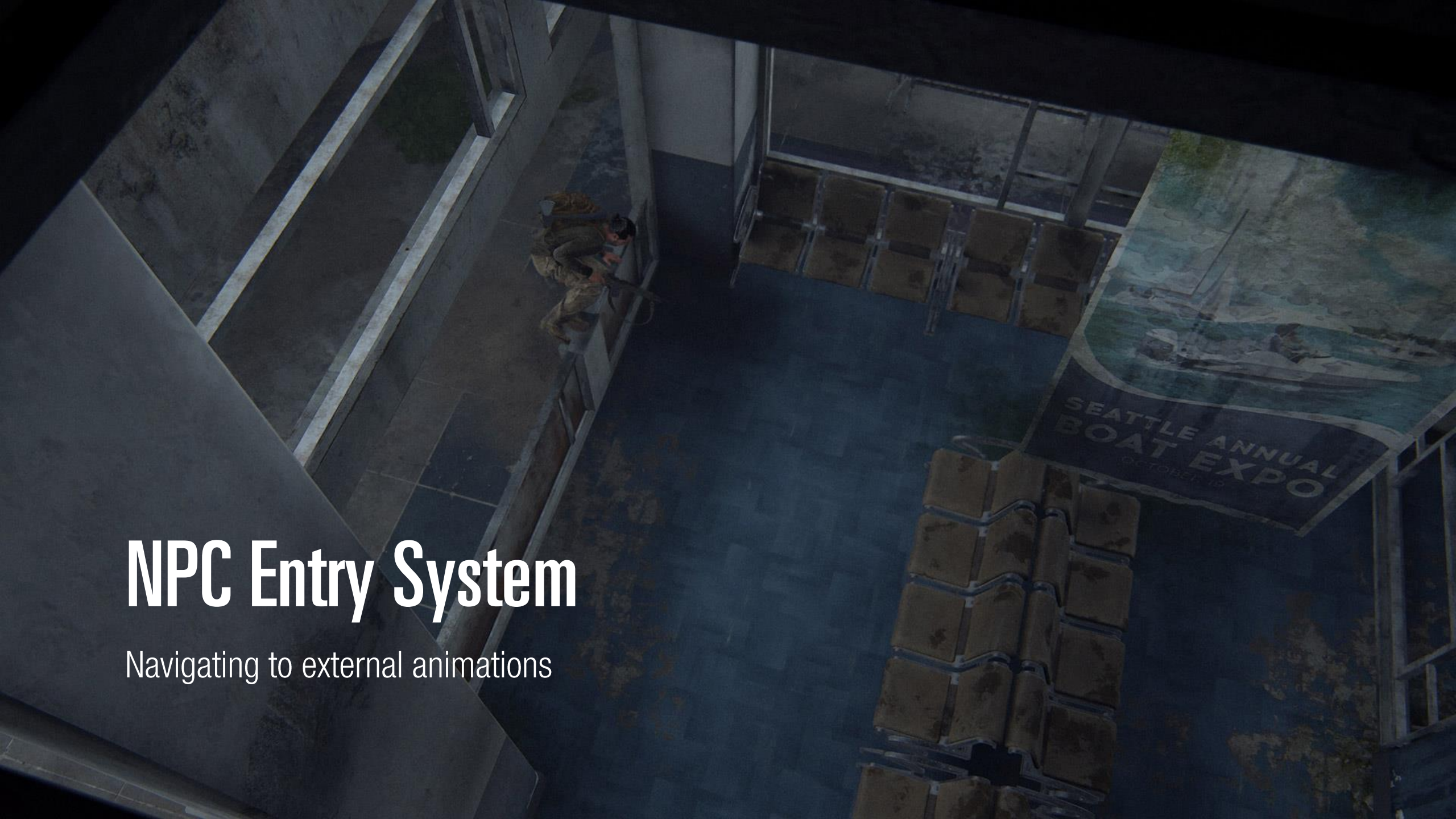
act: 5.35m/s  
des: 5.49m/s  
0.50s [5.4m/s 0.0rad/s]  
des: 5.49m/s  
act: 5.28m/s  
des: 5.49m/s





# NPC Entry System

Navigating to external animations



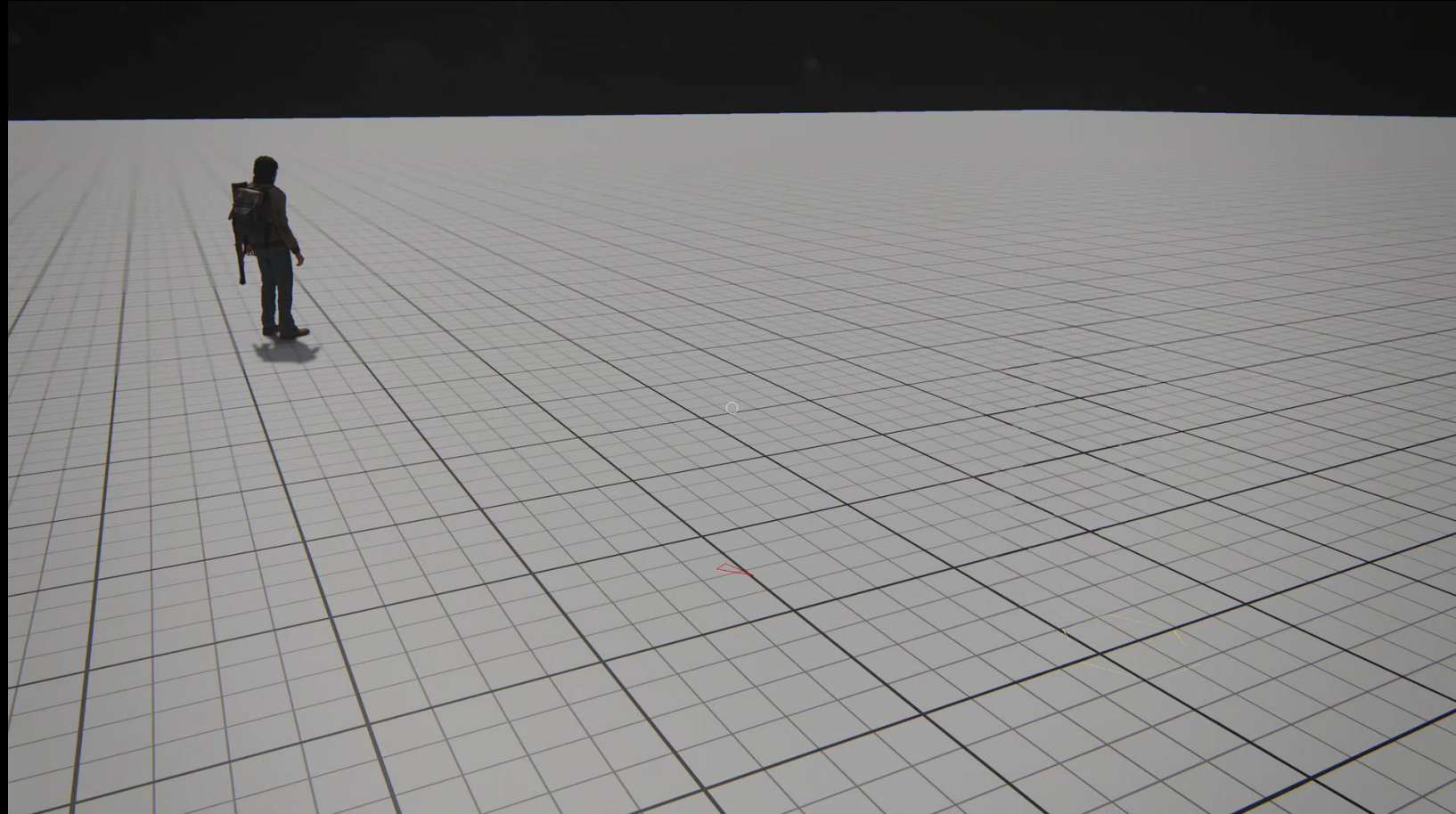


# NPCs Entry System

- Walking used to be simple – **one walk loop animation**
- We used to be able to **scale the stride** to arrive with a correct foot phase
- Motion Matching is a **soup of animation data**
- There's no guarantee that the walk loop is even going to play
- **We HAD to** solve this problem to reach the **Naughty Dog** quality



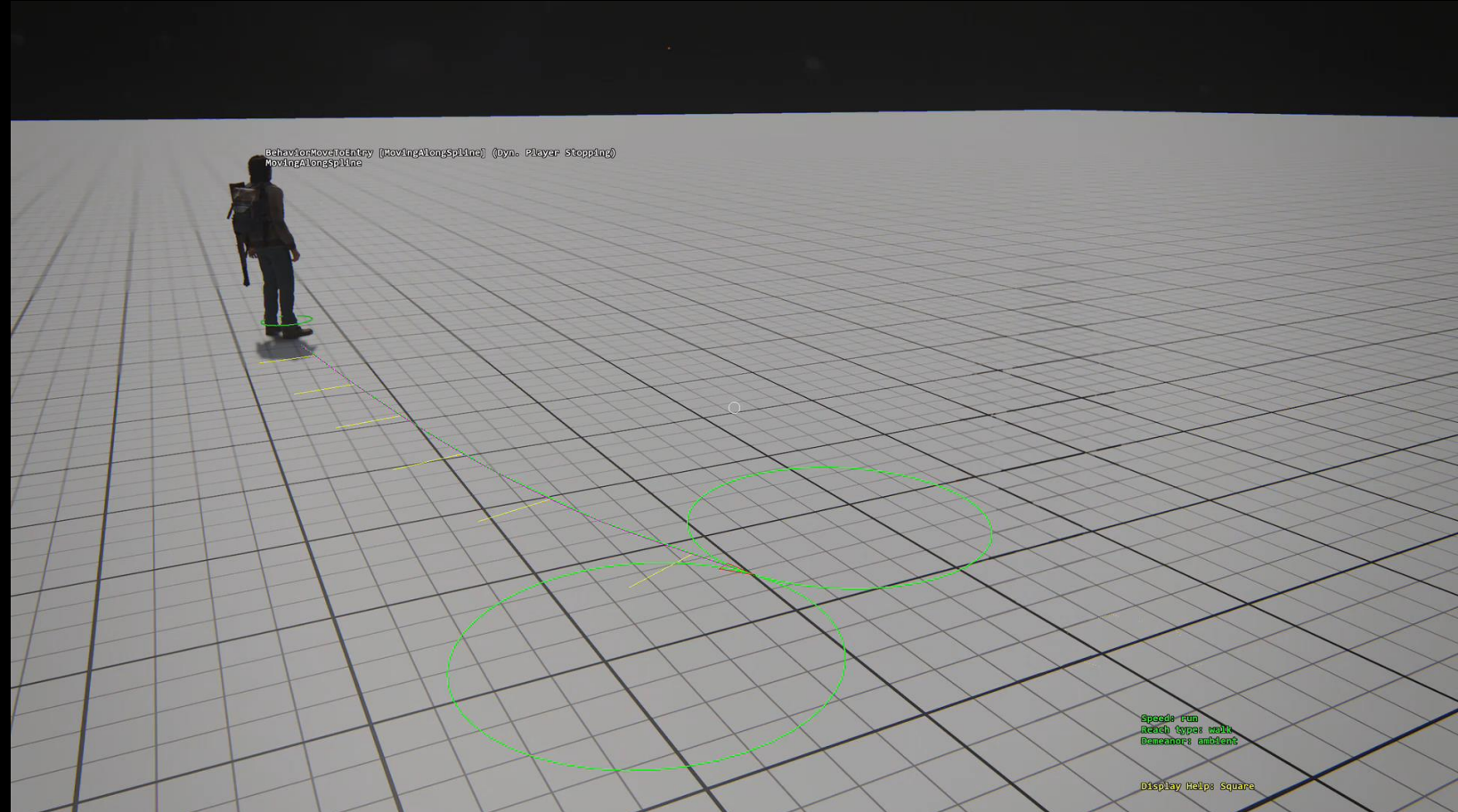
# Entering External Animations (full screen video)



# NPC Entry System

## Solution

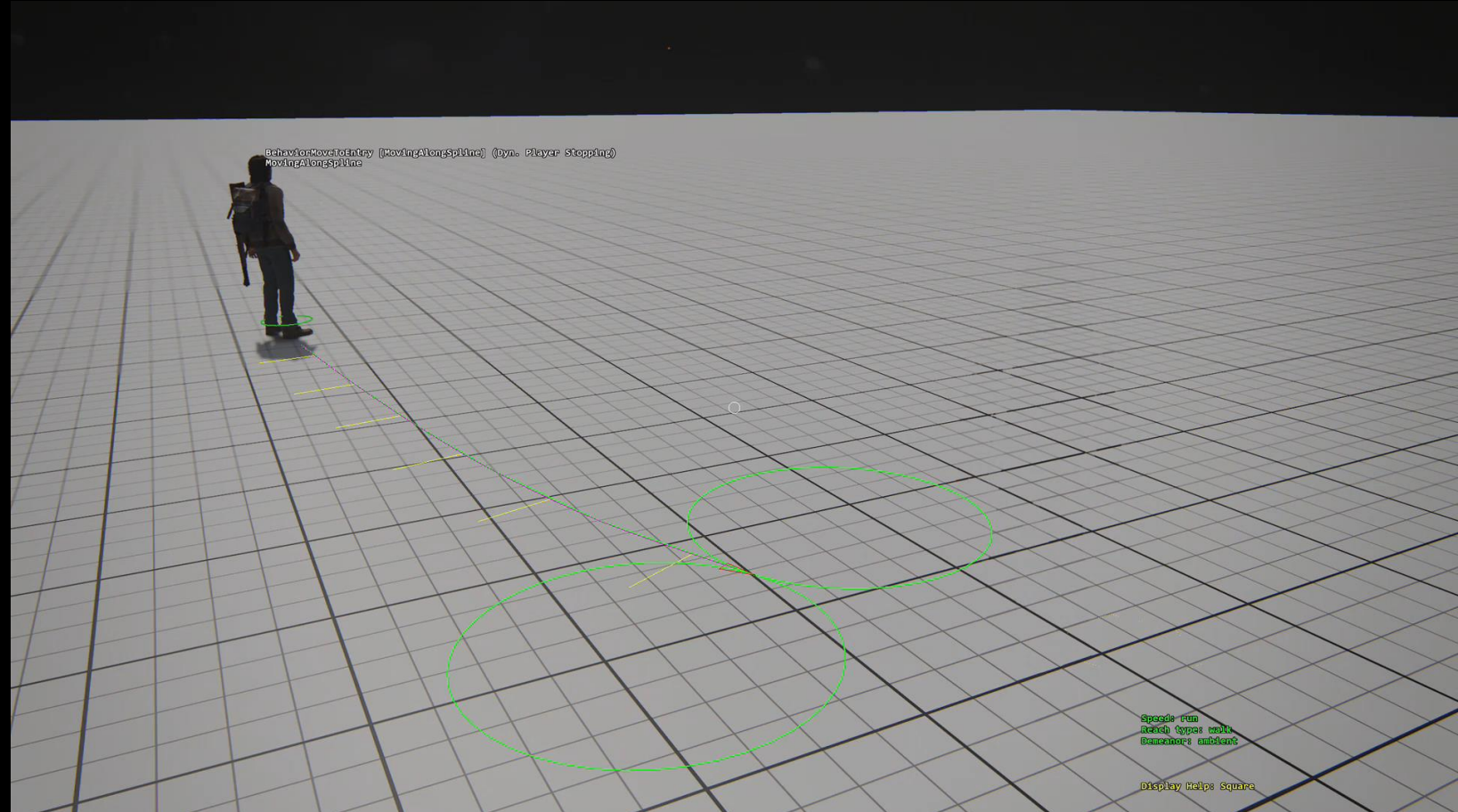
- Spline trajectory from entry vector to NPC
- Movement speed transition distance
- Match the Motion Model speed to the entry Align velocity
- Mark up “matching loop” animation clips in all move sets





# NPC Entry System

- Compute the **closest matching phase** of a loop animation
- Compute **translation error** from the **phase delta**
- **Move the Align** closer to the ideal distance from entry
- Repeat every frame



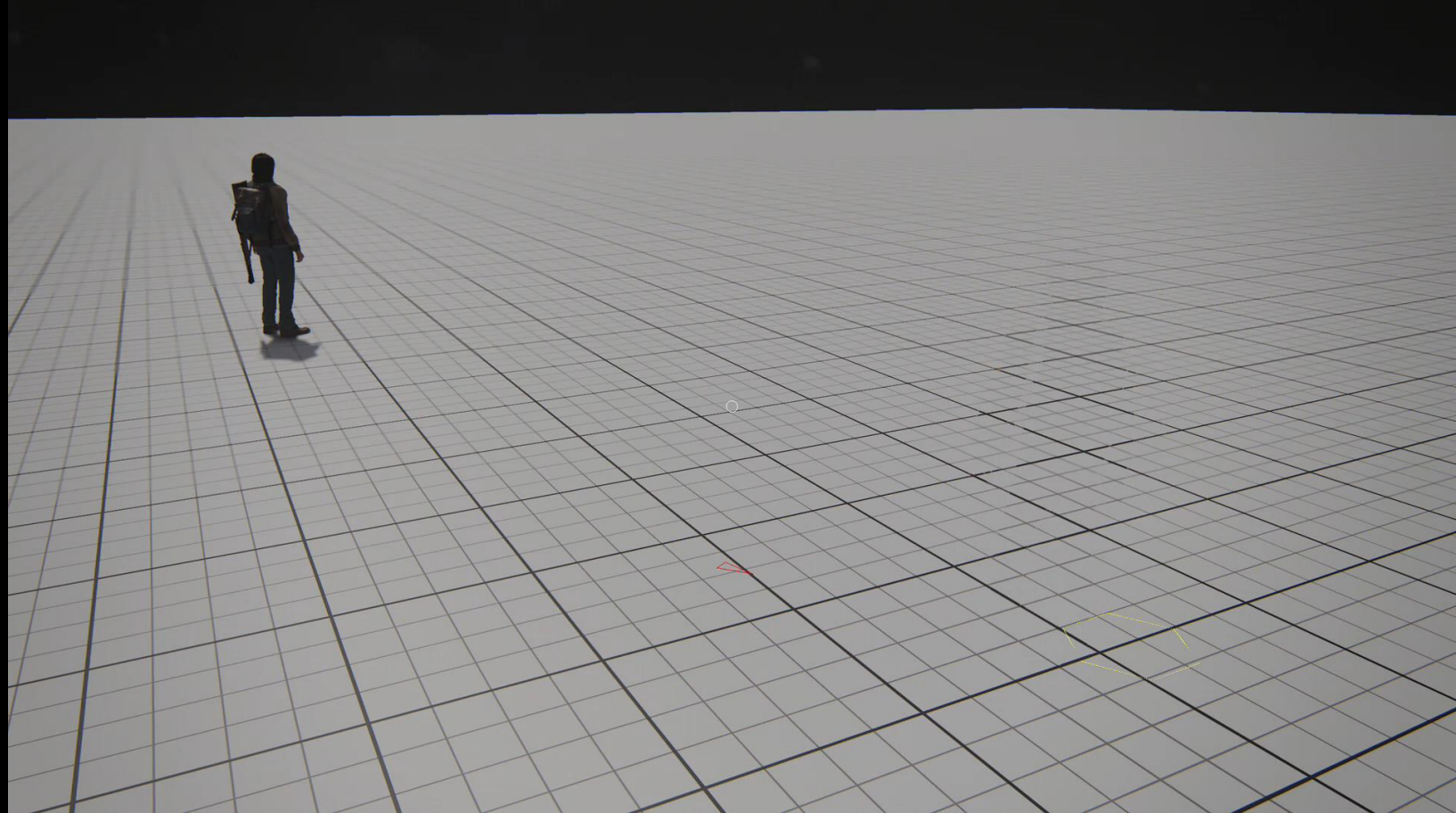


# NPC Entry System

And this is the result

We're using this system when entering

- Cinematics/IGCs
- Cinematic Action Packs
- Traversal Action Packs
- Search Corner Checks





# Preserving Character Weight

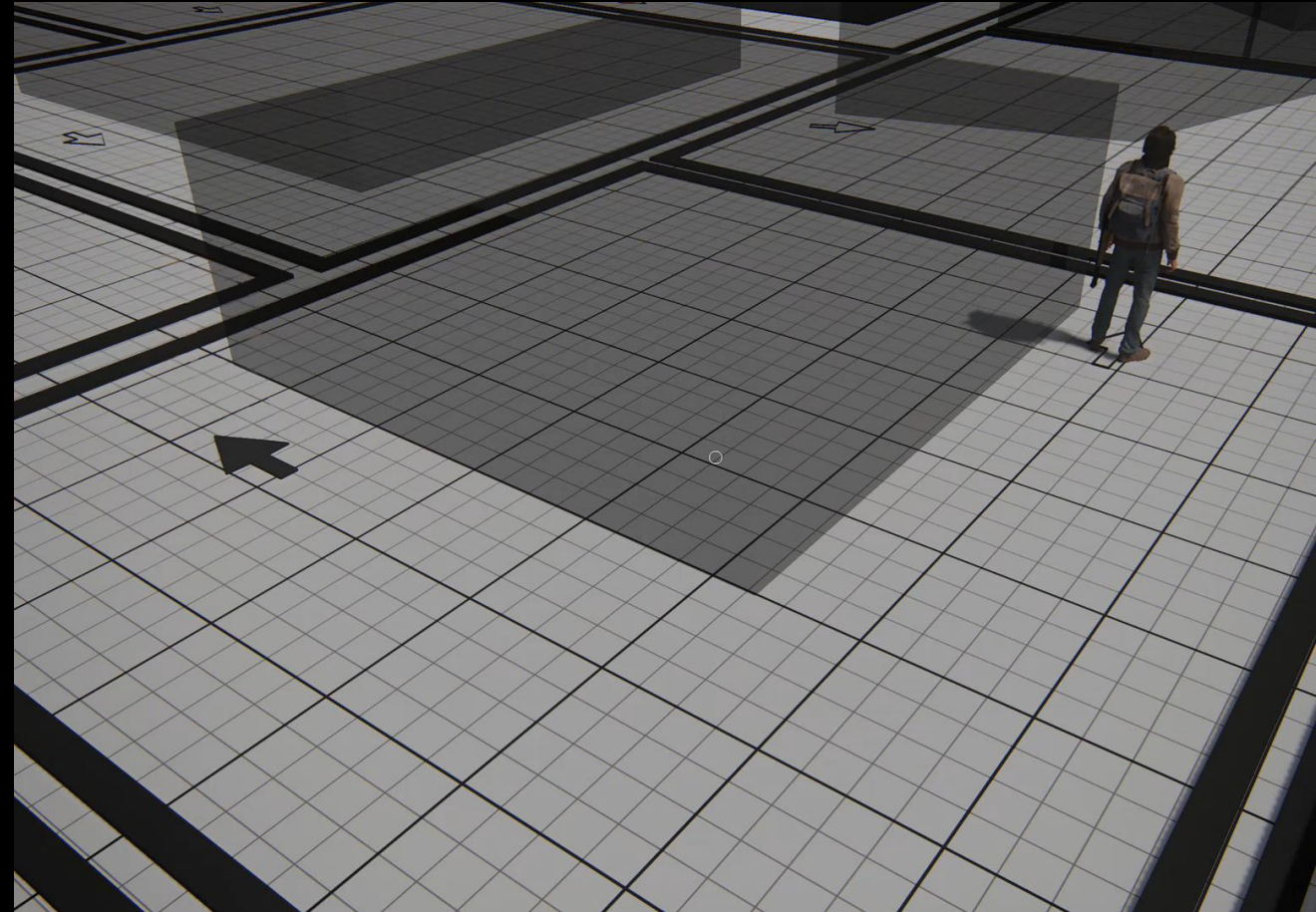
Slowing down at corners



# Slowing Down At Corners

## Problems

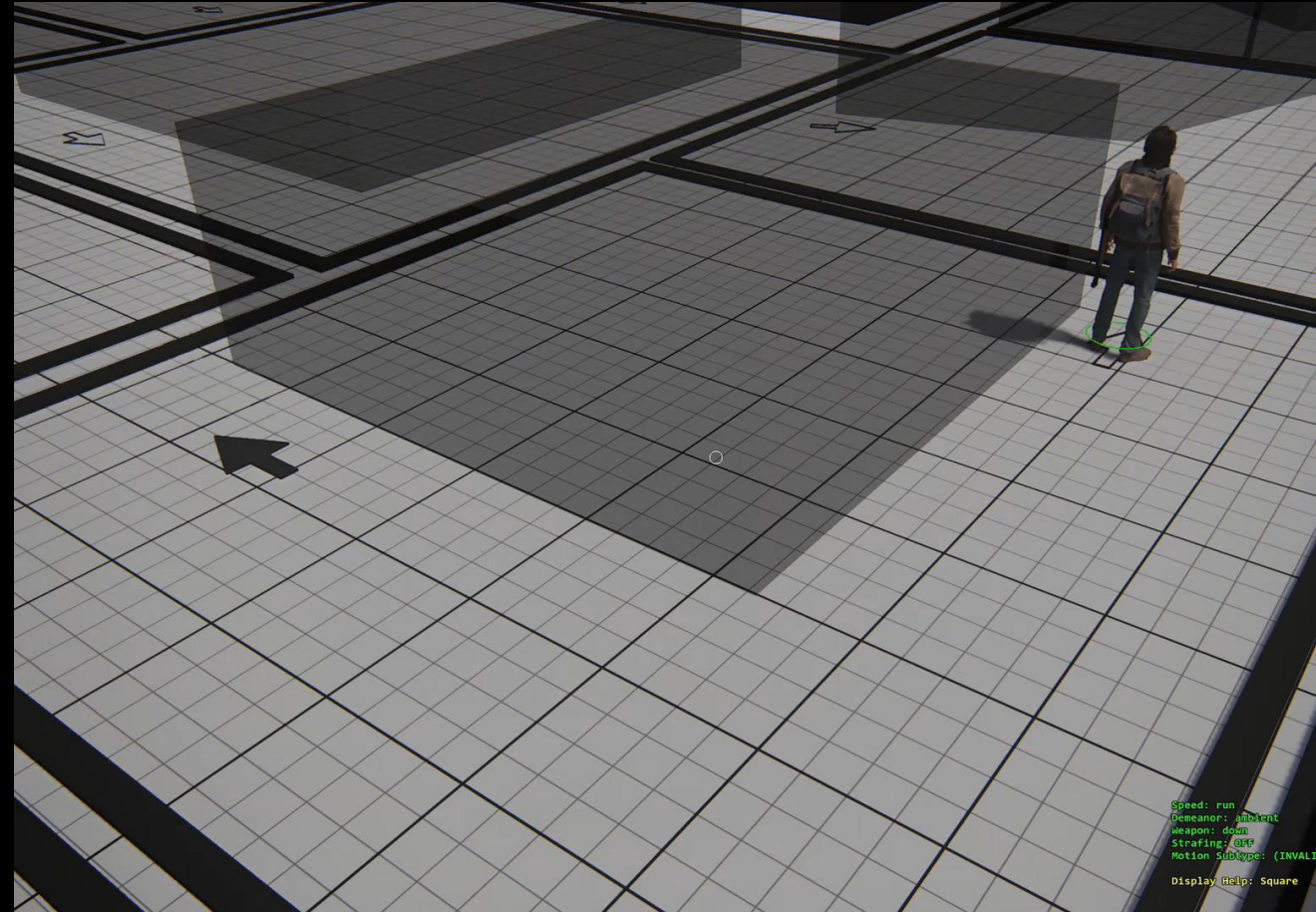
- The NPC whips around corner without slowing down
- Weightless feel
- Increases foot sliding
- The Motion Model deviates from the animation data



# Slowing Down At Corners

## Solution

- Motion Matching Settings
  - Define the **threshold angle** and **corresponding speed** values
  - Define the **slowed down duration**
  - Values read from **Animation Analyzer**
- Runtime
  - **Collect** path **corners** within a radius
  - Calculate the **aggregated angle** value
  - Calculate the slow **down distance** based on **deceleration spring**



Speed: run  
Weapon: silent  
Weapon: down  
Strafing: OFF  
Motion Subtype: (INVALID)  
Display Help: Square



# NPC Traversal Action Packs

Vaulting, climbing, jumping and balance beams



# Traversal Action Packs v1.0

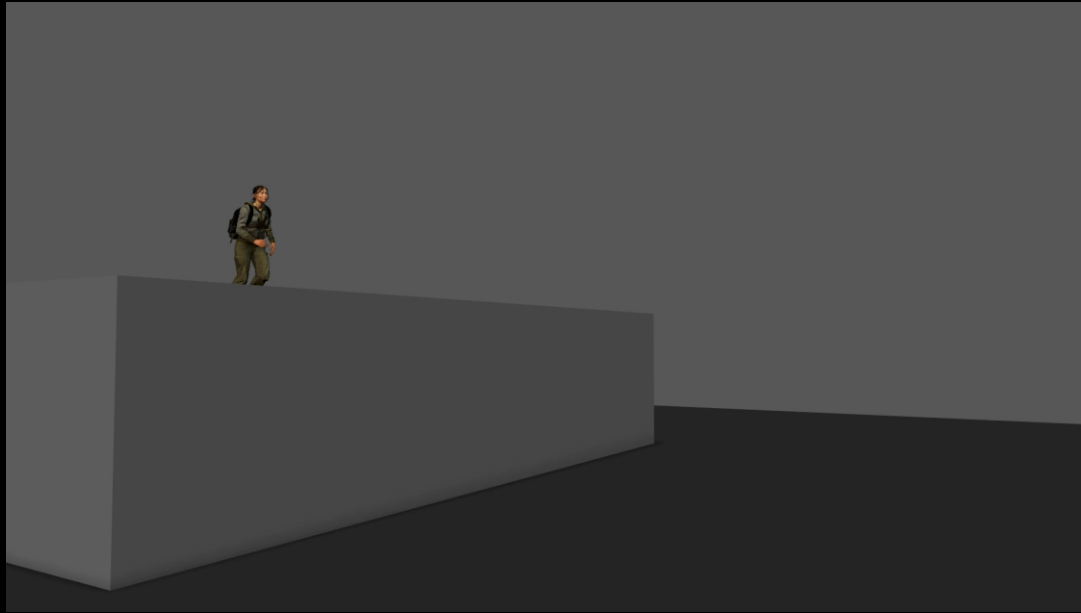
## Pre TLOU2 System

- Set of **Enter**, **Middle** and **Exit** Animations
- **Strict branching points**
- Due to **short blend times**, poses at branching points had to match closely
- **Limited** height or length **flexibility**
- Solved by **crossfading** two instances of the **middle animation**, each anchored to either the enter or exit point

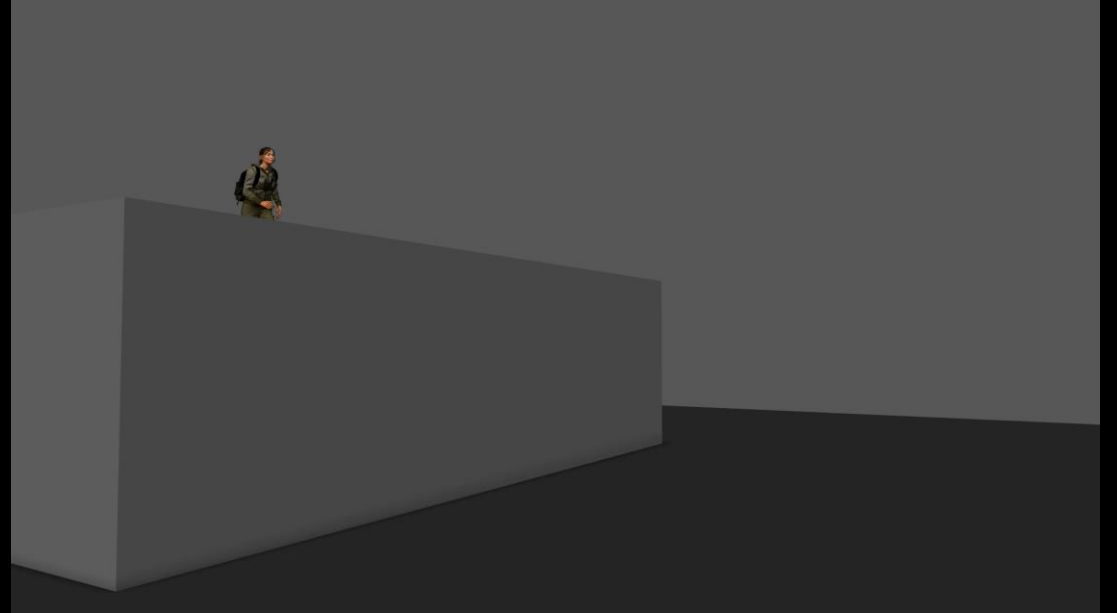


# Traversal Action Packs v1.0

Authored height 2m



Adjusted height 2.4m





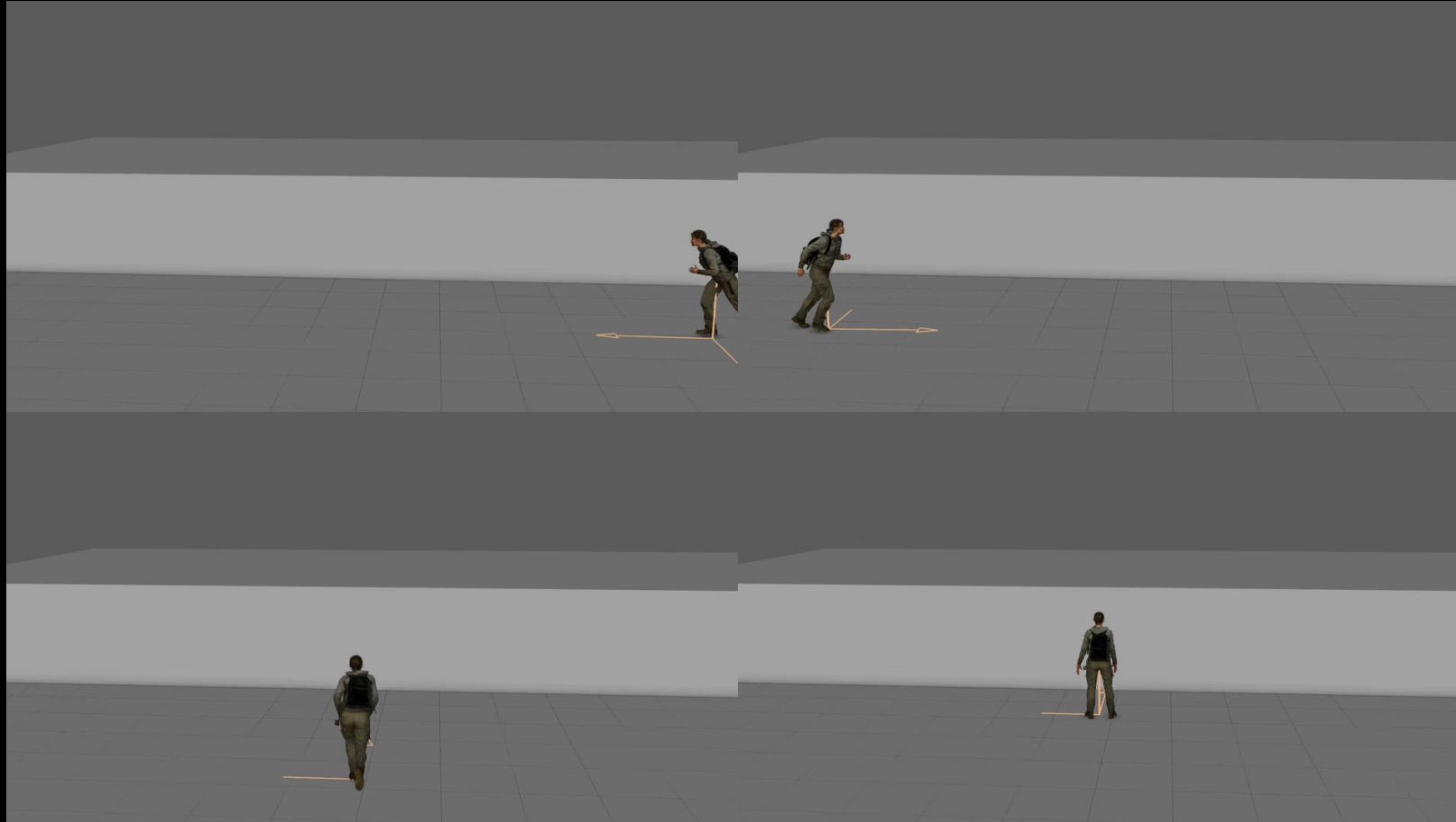
# Traversal Action Packs v2.0

## Improvements

- Leverage **Motion Matching**
- Animations used for generating Motion Model **trajectories**
- Dynamic trajectory shape **preserving momentum**
- Trajectory **intersect points** improvements

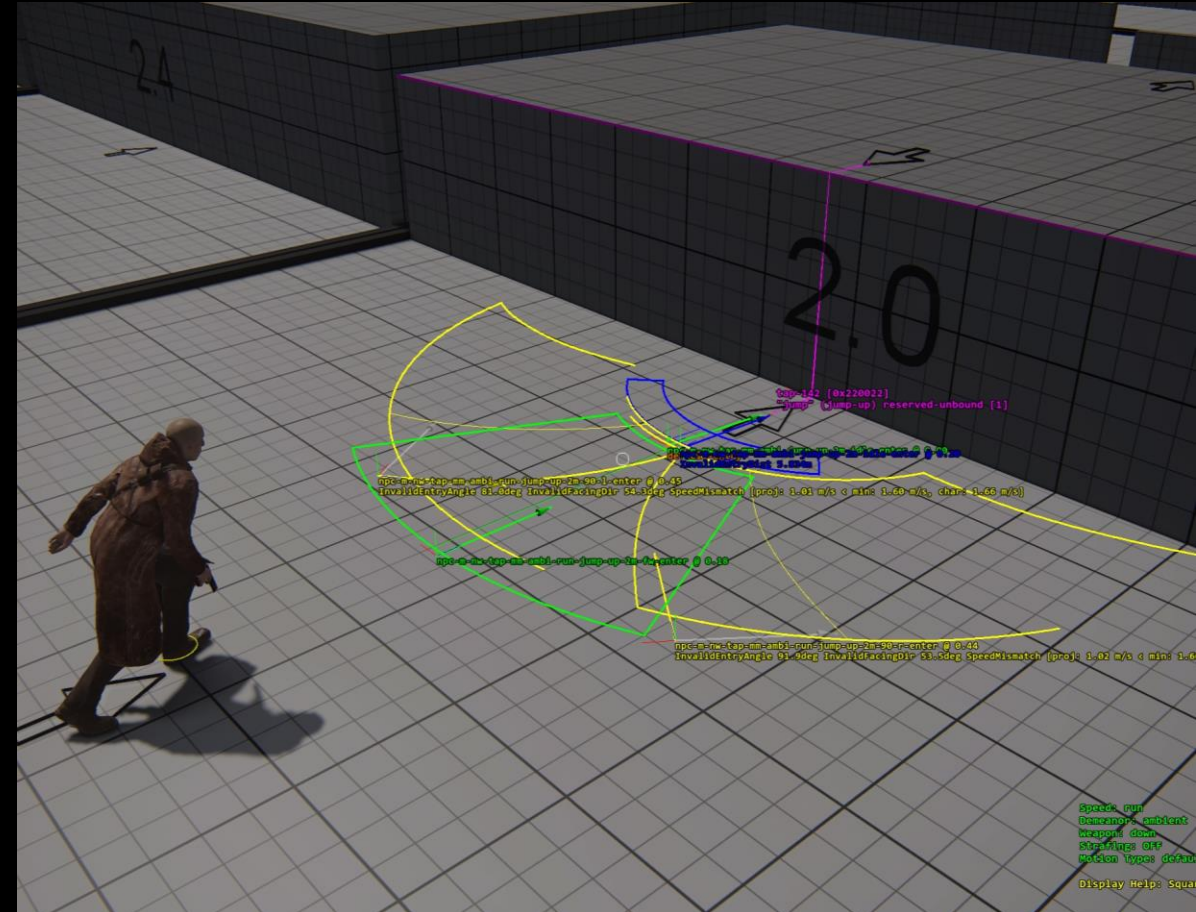


# Traversal Action Packs v2.0: Animations (full screen video)



# Traversal Action Packs v2.0: Trajectories

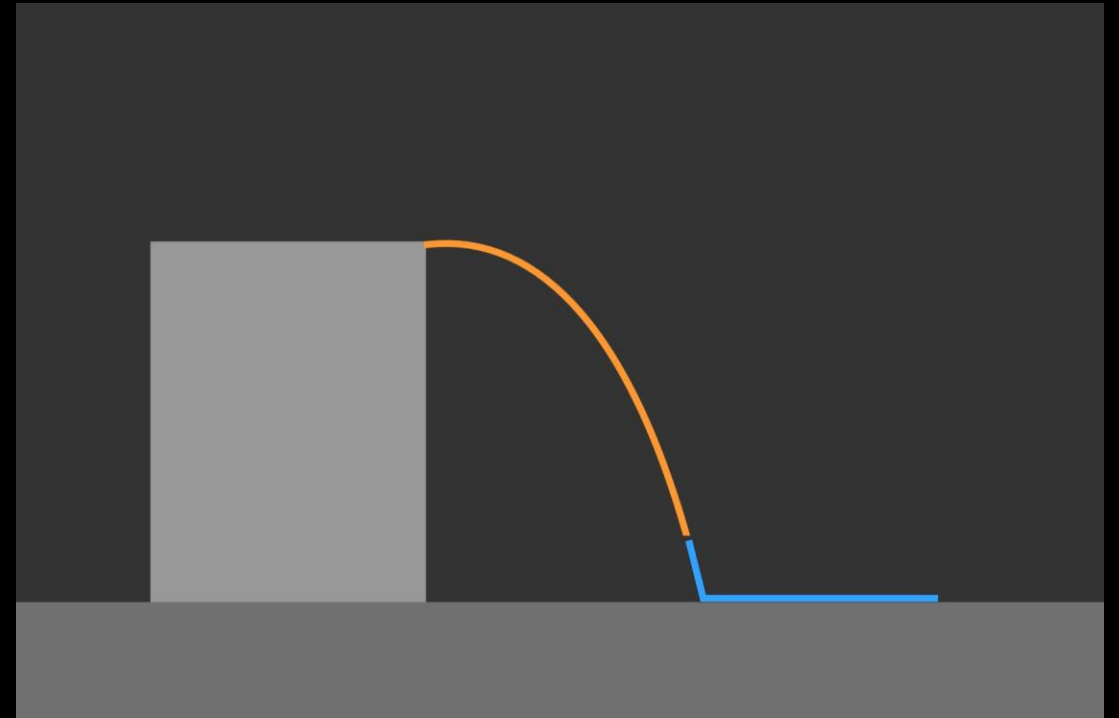
- Constructed using:
  - Idle, Forward, Left, Right Enter Animations
  - 1 middle animation (optionally more)
  - Idle, Forward, Left, Right Exit Animations
- Enter and Exit **animations** can be **procedurally rotated**
- After the procedural rotation is done, we find ideal **intersection points with minimal distortions**
- Generated **trajectory** is used as **source for Motion Model**





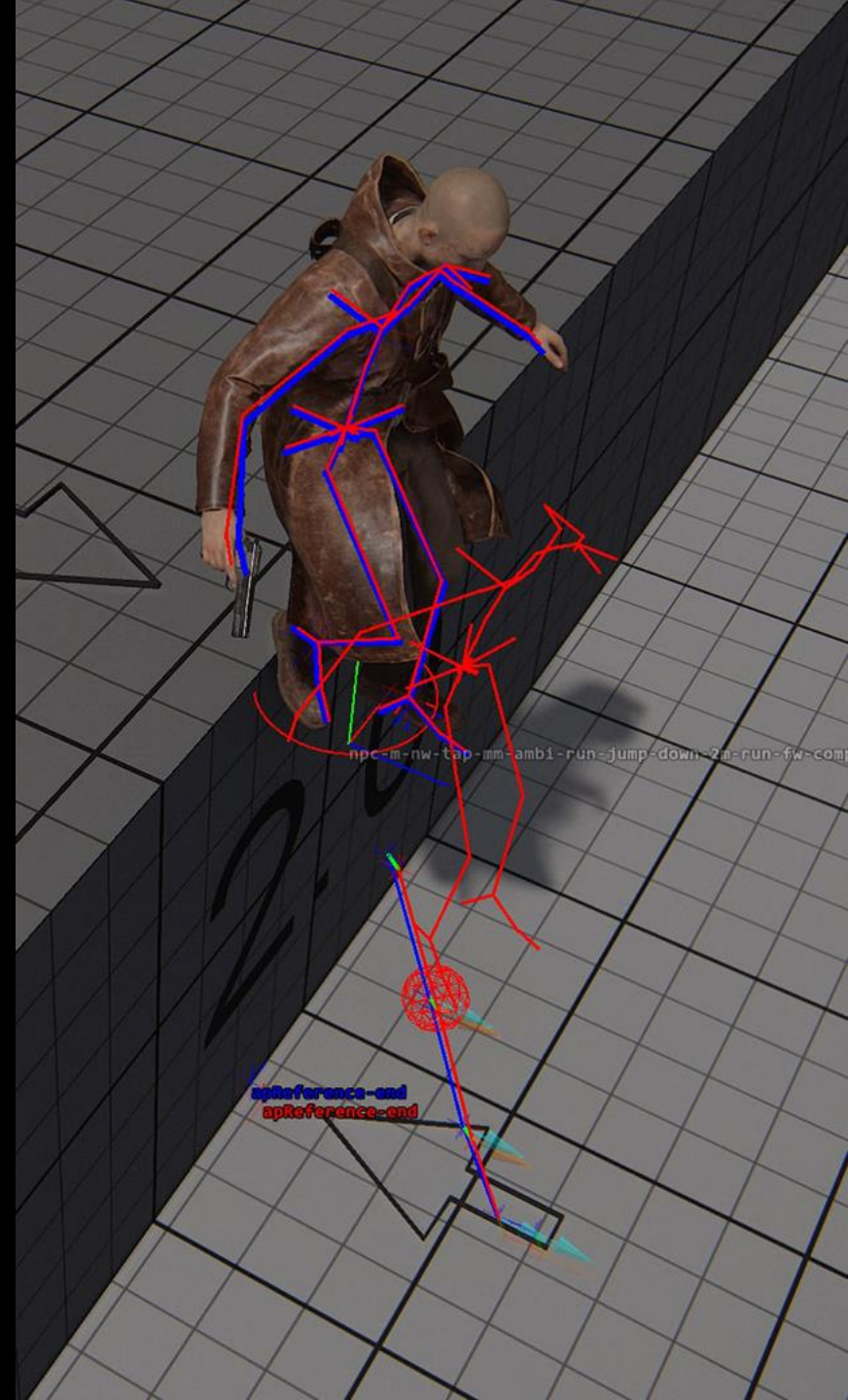
# Traversal Action Packs v2.0: Trajectories

- The **trajectory can self adjust** to the shape of a TAP
- We **trim** the middle animation when the distance is **shorter** than authored distance
- We **extrapolate** the trajectory if the distance is **longer** than authored distance
- Doing that automatically makes the **fall last longer**
- **Exit point moves** so it perfectly connects with the trajectory



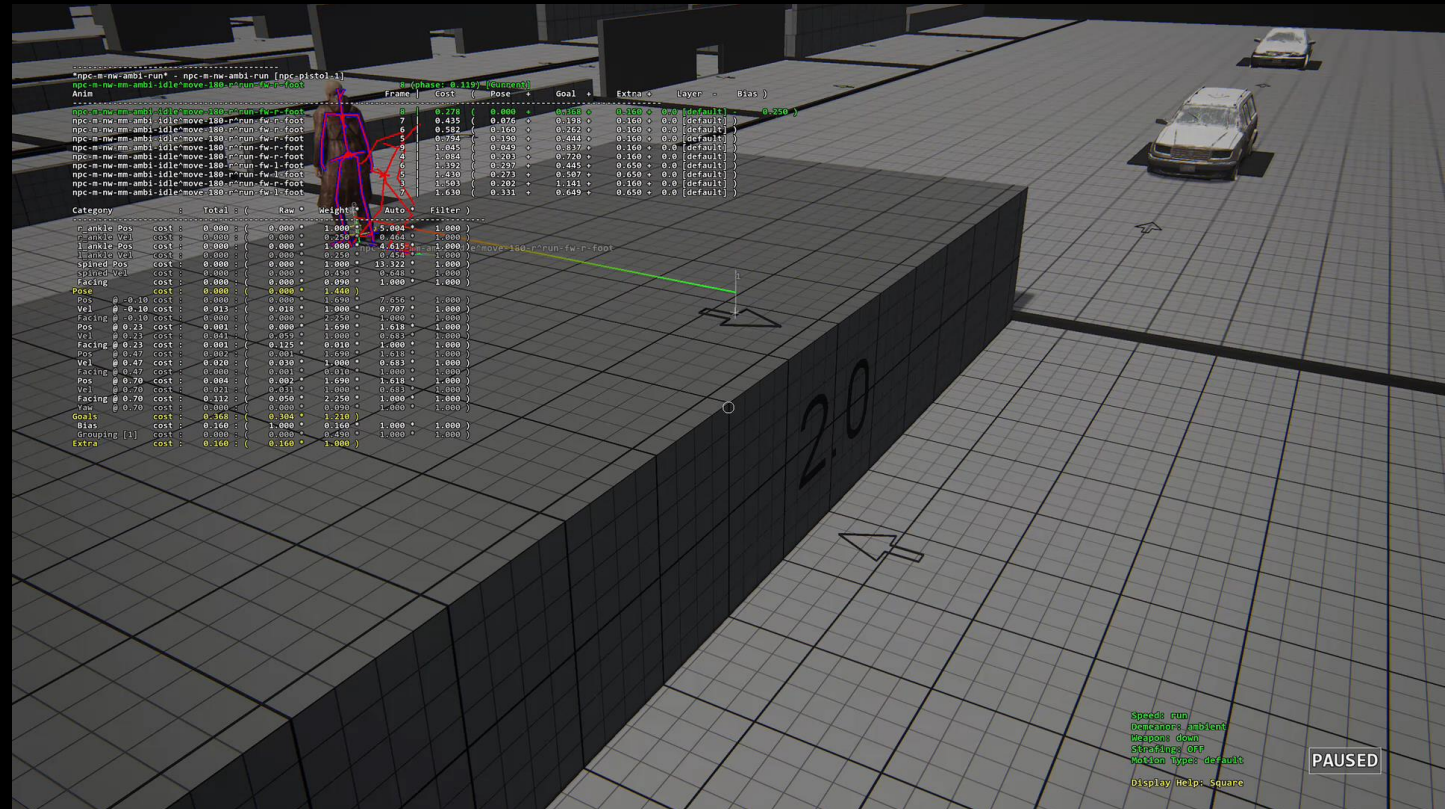
# Traversal Action Packs v2.0: New Features

- **External Goals** in Motion Matching
  - First foray having **world registration** represented in our search logic
  - **AP Locators** as query data (position only)
  - Like AP refs, gameplay code supplies the runtime value
- **Constraints**
  - Handle External **Goals switching**
  - **Move character** in space over time to **minimize distance error** between External Goal and AP ref locator in the animation clip



# Traversal Action Packs v2.0: In-Game

- NPC navigates to an **entry point**
- TAP is **entered**
- We're matching the first **apReference** as an **external goal**
- **Constraint** to **apReference** is active
- Mid-fall we start matching the **second external goal** at the base
- **Constraint** to **apReference-end** is active
- **Exiting** the TAP





A cinematic landscape scene at sunset. In the foreground, tall, golden-brown grasses are in sharp focus, swaying gently. In the middle ground, a person is silhouetted while riding a dark horse, facing away from the viewer towards the horizon. The background features a range of mountains, with the most prominent peak covered in patches of snow. The sun is a large, bright orb on the left side of the frame, creating a strong lens flare and bathing the entire scene in a warm, golden light. A power line tower is visible on the right side of the image.

# Quadrupeds and Motion Matching

Dogs & Horses



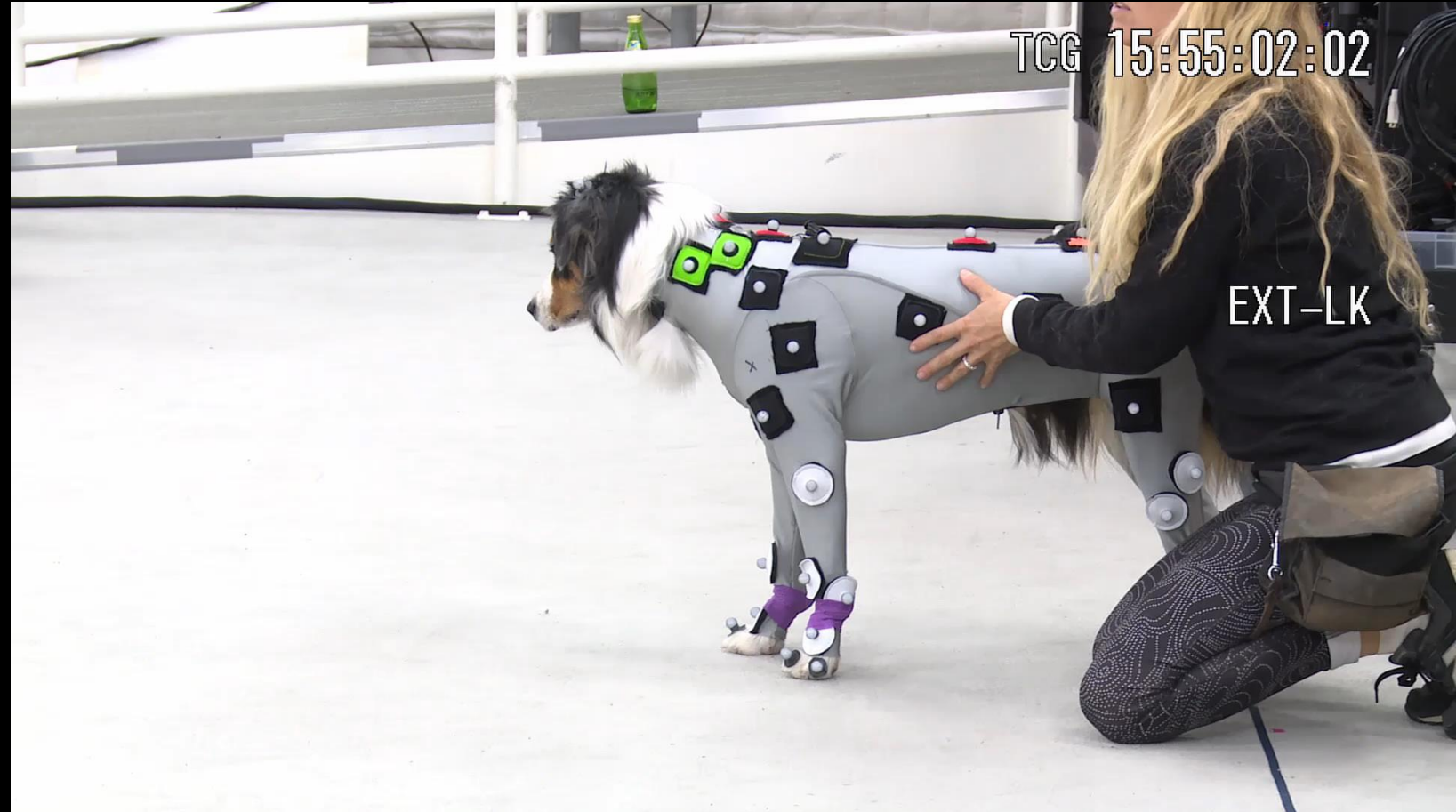
# Dogs Animation Data

- Used **same approach** as for humans
- **Structured clips**
- Tried to get as close to the desired trajectories as possible
- We've **supplied the list of moves ahead of time** so the dogs could be trained to do them



# Dogs Animation Data

- Tracking move set was impossible to shoot as structured data
- We've decided to go the unstructured route
- It worked well enough for our purposes, but it's hard to get full coverage that way



# Dogs: Lessons Learned

- Ambient run and walk worked well
- We were not able to record any aggressive move sets for the dog
- We used a regular run and heavily keyframed over it
- It's incredibly difficult and the results reflect that





# Horse: Motion Model

Horses are large animals and the **human model** pivoting around its center **wasn't suitable**

Additional features for player horse

- **Delayed facing** to simulate realistic turning
- Simulation of **understeering** / **oversteering**
- Custom settings for **riding in circles**
- **Facing momentum** when stopping



# Horses Animation Data

- Horses are much easier to control than dogs
- We were able to obtain decent data for walk, trot and canter
- Gallop was impossible due to limited space and unsuitable floor surface
- Structured vs unstructured data 50:50





# Horses Animation Data

- Horse was the only character **having three locomotion speeds** (walk, trot, canter) **mixed** in one motion matching set
- **Gallop** was still a **separate** set because the riding style is very different
- Motion Matching allows for **flawless transitions** if the set has enough coverage





A person with dark hair, wearing a green jacket and blue jeans, is riding a brown horse up a steep, snow-covered slope. The horse is in motion, with its front legs lifted. The background is a dense forest of tall, thin evergreen trees, some of which are covered in snow. The sky is overcast and grey. The overall scene is a winter landscape.

# Horses On Slopes

Procedural Animation For The Win!

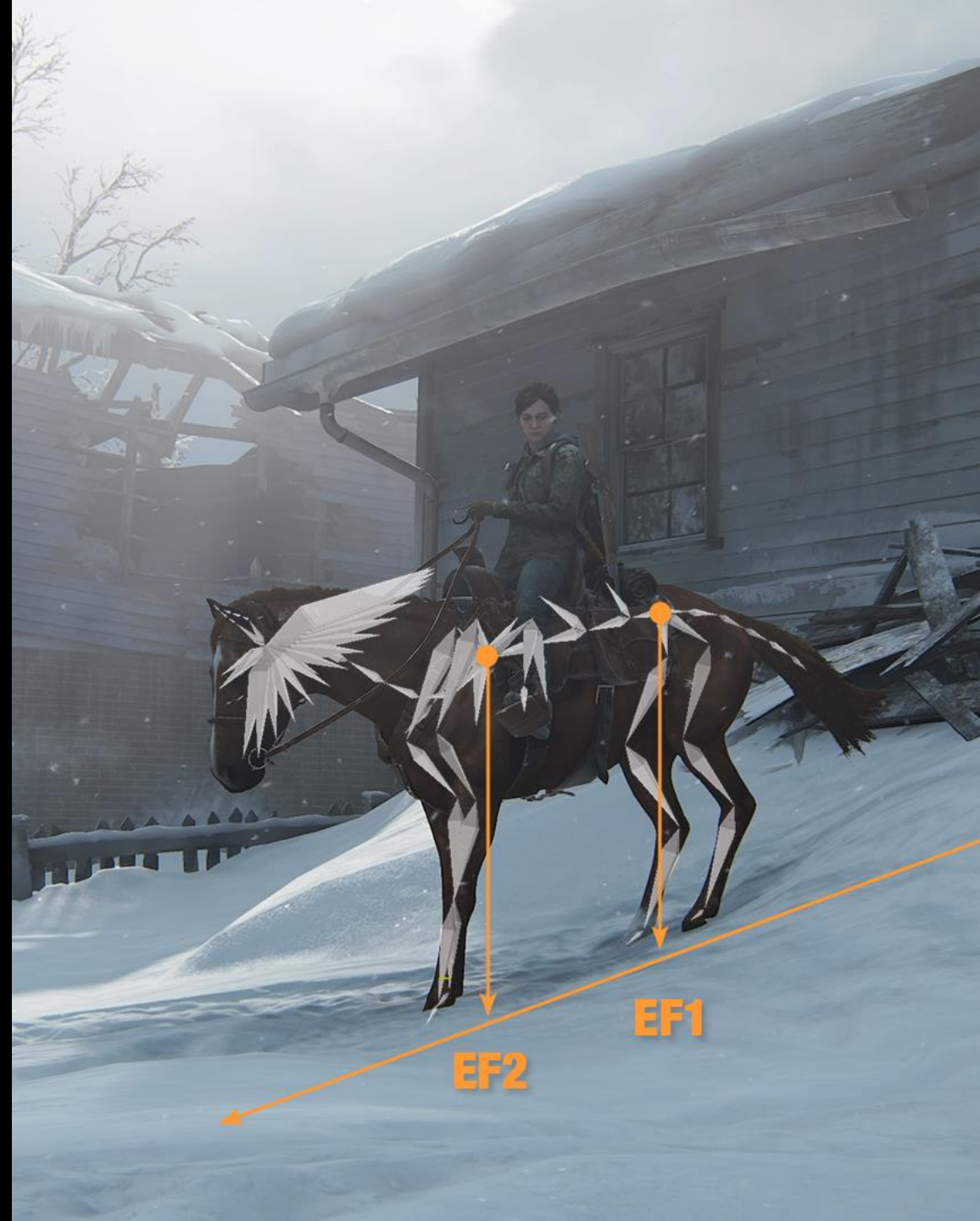


# Horse On Uneven Terrain Video (full screen)



# Full Body Jacobian IK

- Main IK Chain
  - From root joint to chest joint
  - Each end effector tries to stay at an animated height from the ground
  - The vertical position is sprung using critically dampened spring
- Leg IK Chains
  - Each leg solved independently to the ground







# Performance

# Performance

- Index search  $\sim 0.1\text{ms}$
- Complete update  $0.5\text{--}1.0\text{ ms}$  depending on the complexity of the model and trajectory
- The old locomotion system took  $2\text{--}3\text{ ms}$  a frame
- Can be parallelized
- The infected horde NPCs used a move set with limited coverage
- We could easily afford more if we didn't update every frame





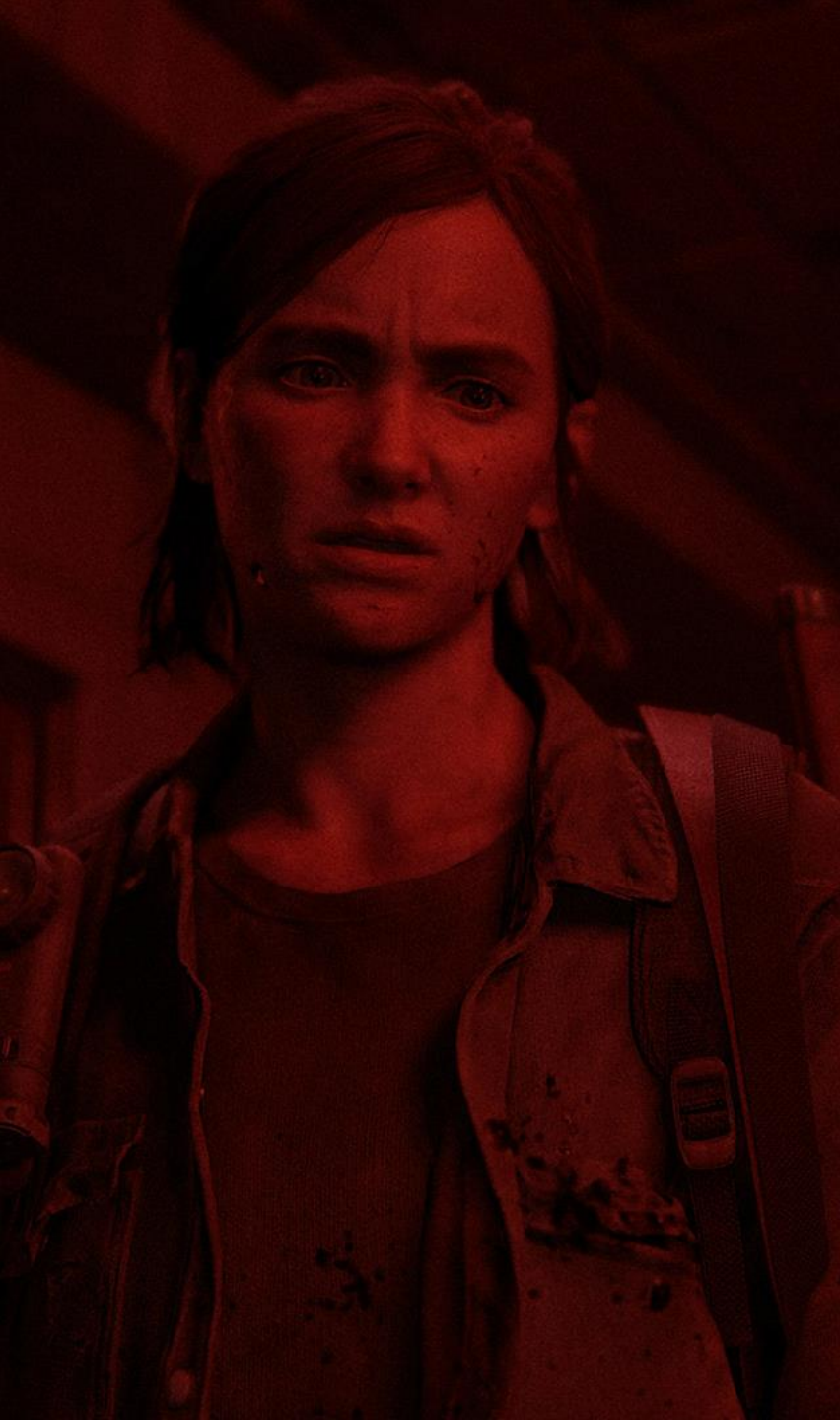
# Summary: Pros

- Very high animation **connectivity** within a single locomotion and between different sets
- Much more **organic feel** thanks to basically **unlimited number of transition options**
- **Transitioning** from “canned” animations into a locomotion set **comes for free**
- **Higher stability** of locomotion sets
- **Faster** in runtime
- Once all-cycle pipeline is **established** and **tutorialized** creating new\* high-quality sets is quite **straight forward**

\*new sets that are **mechanically-similar** to the existing







# Summary: Cons

- Requires technically minded animators
- Rather memory hungry
- High upfront cost of full-cycle technology & pipeline
- Motion Model creation can easily become a bottleneck
- Relies on large MoCap stage access bandwidth
- Many stunts struggle with left foot and right foot versions of all moves while keeping the performance natural

# Special Thanks

Motion Matching in The Last of Us Part II - GDC 2021



# John Bellomy

## Principal Programmer

@cowbs





Programmers

Eli Omernick

Ian Jones

Animators

Troy Slough

Ari Flesch

Laura Swartz

Morgan Earl

Jason Lei

A cinematic still from the video game The Last of Us Part II. The character Ellie is shown from the waist up, positioned on the left side of the frame. She has short, reddish-brown hair tied back and is looking off to the right with a serious expression. She is wearing a grey button-down shirt over a dark t-shirt and has a backpack on. She is holding a wooden rifle with both hands. The background is a dark, misty forest with tall, thin trees and some foliage. The lighting is low and atmospheric.

# We are hiring!

<https://www.naughtydog.com/careers>