

Advanced Screenspace Antialiasing

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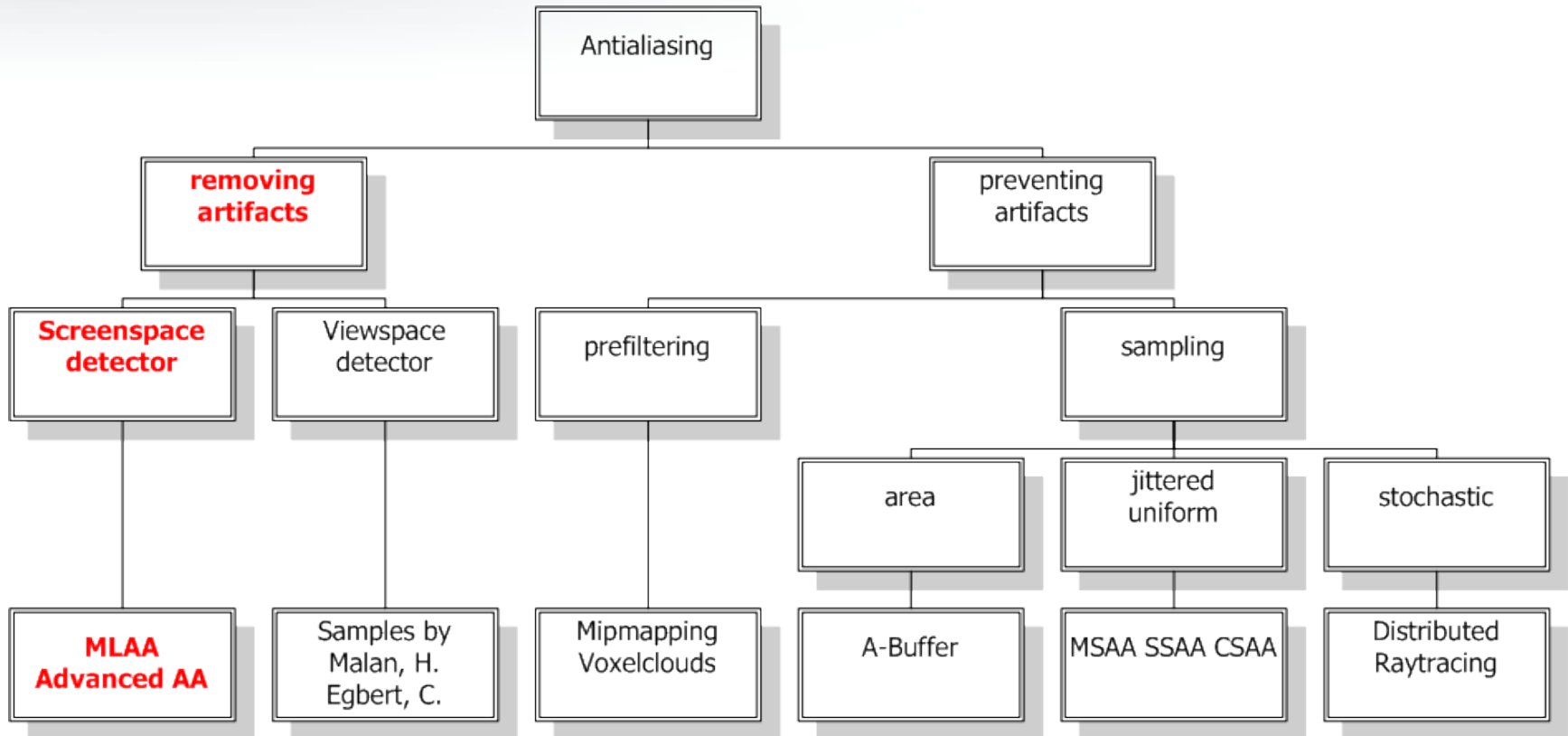
- Antialiasing Techniques
- What types of artifacts can be removed?
- Morphological Antialiasing
- Advancements in the implementation
 - Discontinuity detector
 - Richards counting optimization
 - Calculating coverage
 - Advanced coverage calculation
- Implementation details
 - Overview
 - Blending optimizations
 - Linear textures on Xbox360
 - Synchronization
 - Counting on the GPU



ANTIALIASING TECHNIQUES



Antialiasing Techniques

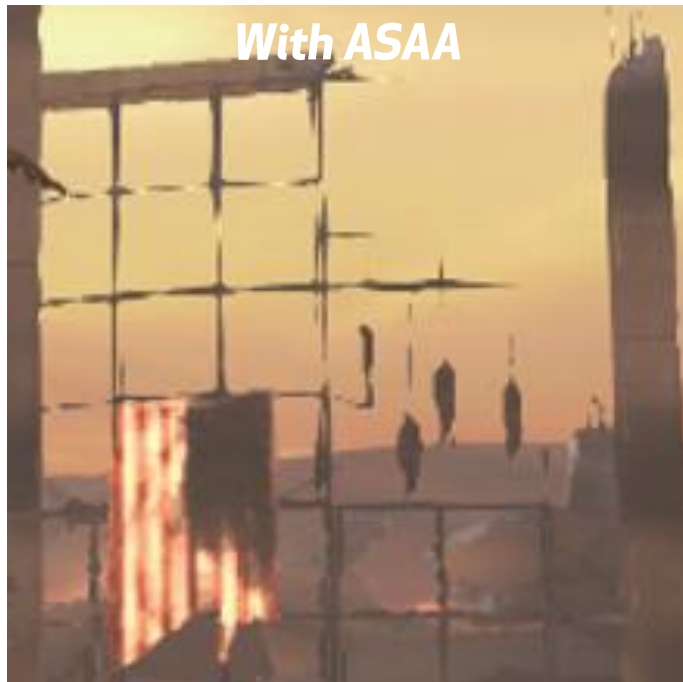


**WHAT TYPES OF ARTIFACTS CAN
BE REMOVED?**



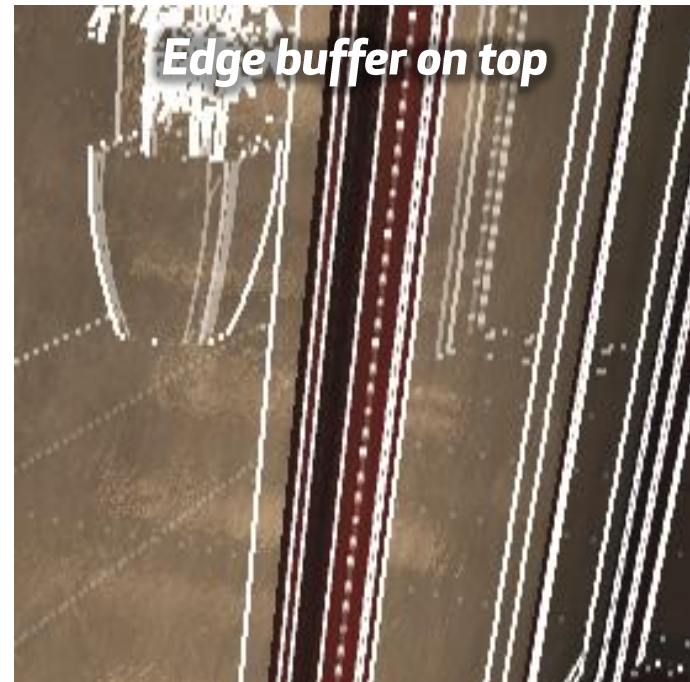
What types of artifacts can be removed?

- Information that has been lost cannot be recovered!
 - under sampling artifacts cannot be removed



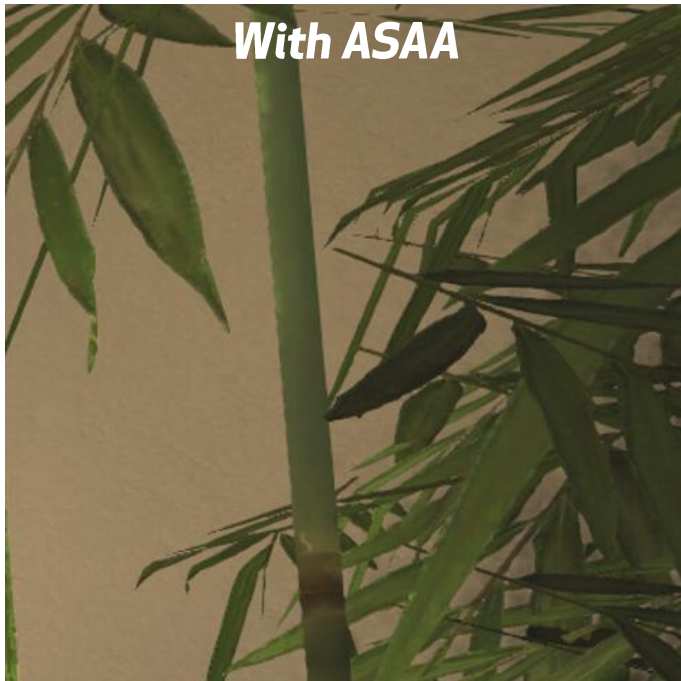
What types of artifacts can be removed?

- Transparencies are not handled in our implementation
 - depth peeling or a stencil routed K-buffer might fix this
 - avoid intersection of transparent geometry (window & frame)
 - add an opaque edge where transparencies occur



What types of artifacts can be removed?

- Alpha Test geometry as well as geometry edges are handled



MORPHOLOGICAL ANTIALIASING



Morphological Antialiasing

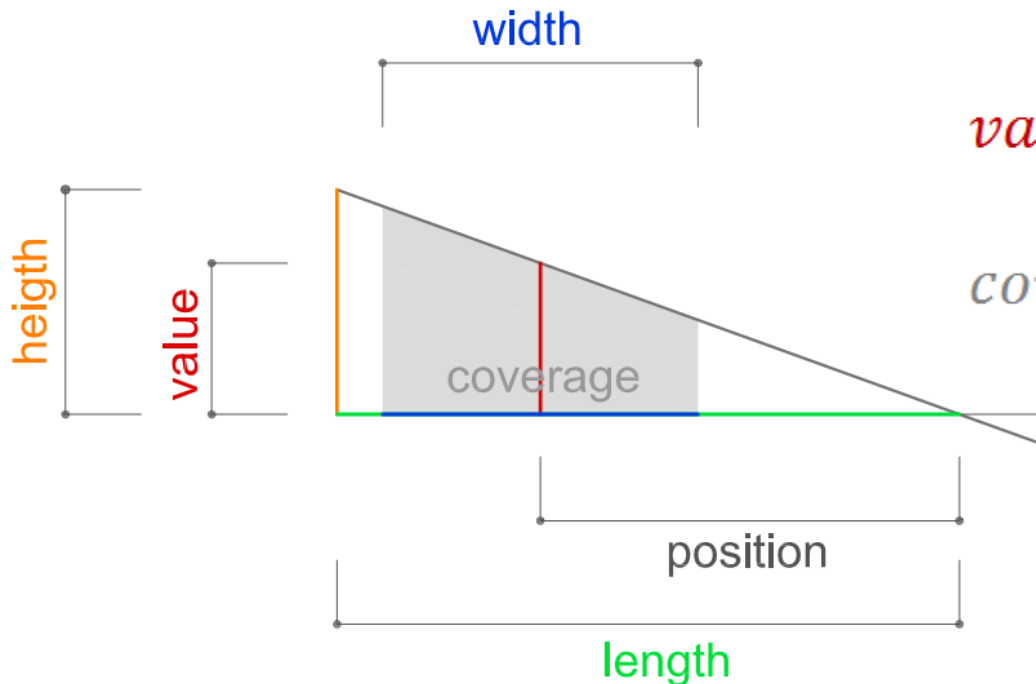
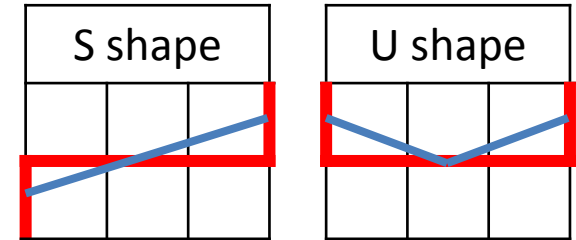
- Original idea from Reshetov, A. (HPG 2009)
- GPU implementation available from Biri, V. (Siggraph 2010)
 - <http://igm.univ-mlv.fr/~biri/mlaa-gpu/>
- Uses a color discontinuity detector
 - ☹ Might miss important edges (where the difference in color is small)
 - ☹ Might be overly sensitive (detects texture details)
 - ☺ Will detect transparencies
 - ☺ no need of extra buffers (e.g. normal, texcoord & depth)
- Edge detection convolution kernels

vertical		
0	0	0
0	1	0
0	-1	0

horizontal		
0	0	0
0	1	-1
0	0	0

Morphological Antialiasing

- Detect various types of line segments
 - S shapes & U shapes composed of 2 L shapes
- Actual length and pixel position needed
 - Coverage can be determined using the Intercept theorem



$$value = \frac{height * position}{length}$$

$$coverage = value * width$$

Horizontal counting

- 2 additional buffers for the edge detection (only one shown)

grayscale image							

vertical discontinuities							

- Counting technique with 4 additional buffers (\leftarrow , \rightarrow , \uparrow , \downarrow)

\rightarrow counting buffer							
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

\leftarrow counting buffer							
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

Horizontal counting

grayscale image							

vertical discontinuities (edges)							

- Always **reject** all pixels not in the vertical discontinuity buffer

→ counting buffer & edges							
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

← counting buffer & edges							
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

Horizontal counting

→ counting buffer & edges							
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

← counting buffer & edges							
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

- start with **level = 1**: let **x** = lookup **level** pixel to the left or right and only set **value** to (**level + x**) when **ceil(level / 2)** pixels to the left or right has not been rejected else **reject**

→ counting buffer & edges							
0	0	0	1	1	1	0	0
0	1	0	0	0	0	0	0
0	0	0	0	0	0	0	0

← counting buffer & edges							
0	0	1	1	1	0	0	0
1	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

Horizontal counting

- continue with level *= 2 (level is now 2):

→ counting buffer & edges							
0	0	0	1	2	3	0	0
0	1	0	0	0	0	0	0
0	0	0	0	0	0	0	0

← counting buffer & edges							
0	0	3	2	1	0	0	0
1	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

- do this repeatedly until no further pixels are drawn or maximum precision is reached
- the maximum number of needed passes will be:
$$\text{maxPasses} = \log_2(2^{\text{numBits}})$$
- which is in fact the number of bits per counting value used

Morphological Antialiasing

→ counting- & horizontal discontinuity buffer							
0	0	0	1	2	3	0	0
0	1	0	0	0	0	0	0
0	0	0	0	0	0	0	0

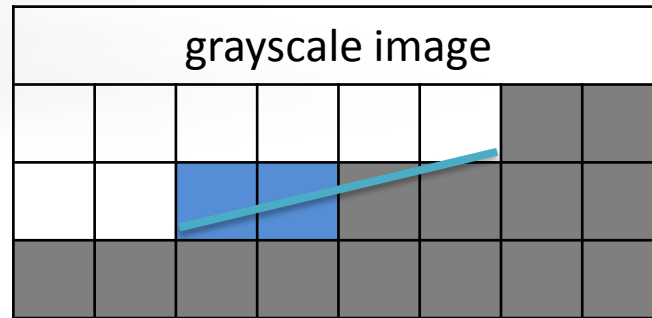
← counting- & horizontal discontinuity buffer							
0	0	3	2	1	0	0	0
1	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

- The length of a L-shape and position on that shape can be determined:

$$position = \frac{|left - right|}{2} \quad length = \frac{left + right + 1}{2}$$

- The blending value is **rejected** when in the left case $left + 1$ pixel to the left or in the right case $right$ pixel to the right is not marked in the **horizontal** discontinuity buffer

Special Case: downside of S-Shapes



- for blending of the blue pixels there are no immediate values therefore we have to look **one line above**

→ counting- & horizontal discontinuity buffer							
0	0	0	1	2	3	0	0
0	1	0	0	0	0	0	0
0	0	0	0	0	0	0	0

← counting- & horizontal discontinuity buffer							
0	0	3	2	1	0	0	0
1	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

- If we have more than one blending value → use the maximum

Morphological Antialiasing

- ☺ The Algorithm handles U shapes always in an unambiguous way
- ☹ The implementation of Biri, V. uses a lot of memory
 - 2 ARGB counting buffers
 - 1 ARGB blending buffer
 - 1 RG discontinuity buffer
 - 1 512x512px float Lookup Table for coverage calculations
- ☹ With clever packaging and buffer sharing the overall memory consumption could be reduced significantly (at additional computational costs)
- ☹ The algorithm uses a lot of conditional branching in the pixelshader
- ☹ The algorithm uses a lot of passes with no stencil early outs
- ☹ Therefore it is unsuitable for the current console generation



ADVANCEMENTS IN THE IMPLEMENTATION



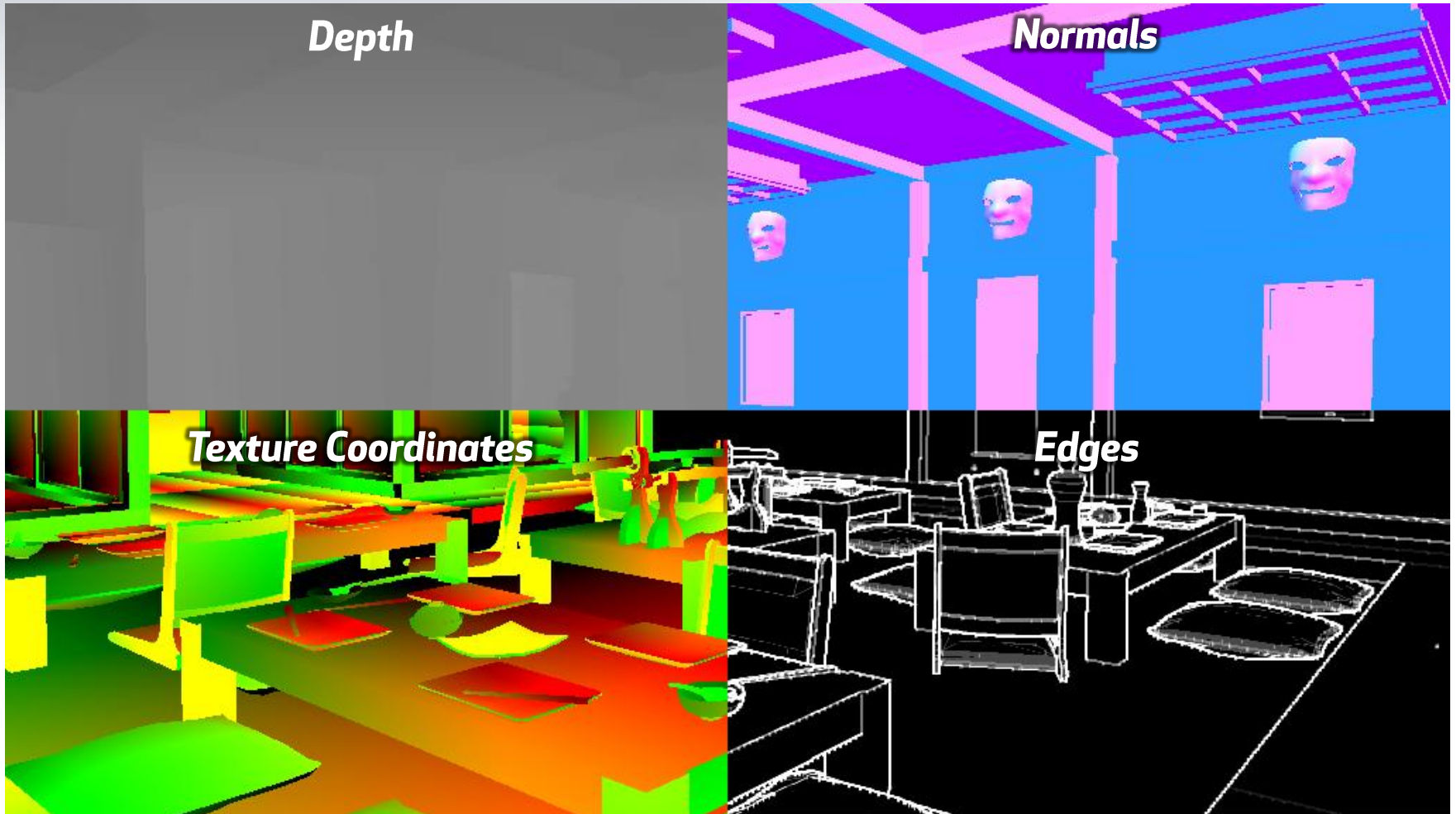
Discontinuity detector

- Our implementation did not use color for discontinuity detection because we thought depth would be more precise
- Depth revealed not all edges and fine grained detail was lost
- Added normal and texture coordinates as additional edge detection hints
 - These two additional buffers could be safely shared with the scene color for the time they are being used
- A laplacian convolution kernel was used for discontinuity detection → detects discontinuities on both sides of an edge

vertical		
0	-1	0
0	2	0
0	-1	0

horizontal		
0	0	0
-1	2	-1
0	0	0

Edge detection buffers



Discontinuity detector

grayscale image							

- The resulting discontinuity buffers using a laplace convolution

vertical discontinuity buffer							

horizontal discontinuity buffer							

Richards counting optimization

- Original 4 counting buffers (\leftarrow , \rightarrow , \uparrow , \downarrow)

\uparrow counting- & vertical discontinuity buffer							
1	1	0	0	0	0	3	3
0	0	0	0	0	0	2	2
0	0	1	1	1	1	1	1

\rightarrow counting- & horizontal discontinuity buffer							
1	2	3	4	5	0	0	1
1	0	0	1	2	3	4	5
1	2	3	4	5	6	7	8

\downarrow counting- & vertical discontinuity buffer							
1	1	0	0	0	0	1	1
0	0	0	0	0	0	2	2
0	0	1	1	1	1	3	3

\leftarrow counting- & horizontal discontinuity buffer							
5	4	3	2	1	0	0	1
1	0	0	5	4	3	2	1
8	7	6	5	4	3	2	1

Richards counting optimization

- Combined results of ($\downarrow\uparrow$) and ($\rightarrow\leftarrow$) counting using the minimum operator

$\downarrow\uparrow$ counting- & vertical discontinuity buffer							
1	1	0	0	0	0	1	1
0	0	0	0	0	0	2	2
0	0	1	1	1	1	1	1

$\rightarrow\leftarrow$ counting- & horizontal discontinuity buffer							
1	2	3	2	1	0	0	1
1	0	0	1	2	3	2	1
1	2	3	4	4	3	2	1

Calculating coverage

horizontal edges		
0	nxt	0
0	this	0
0	nxt	0

vertical edges		
0	0	0
nxt	this	nxt
0	0	0

- Intercept theorem for calculating the coverage between 2 pixel:

$$length = \frac{this + nxt + 1}{2} \quad position = \frac{nxt - this}{2}$$

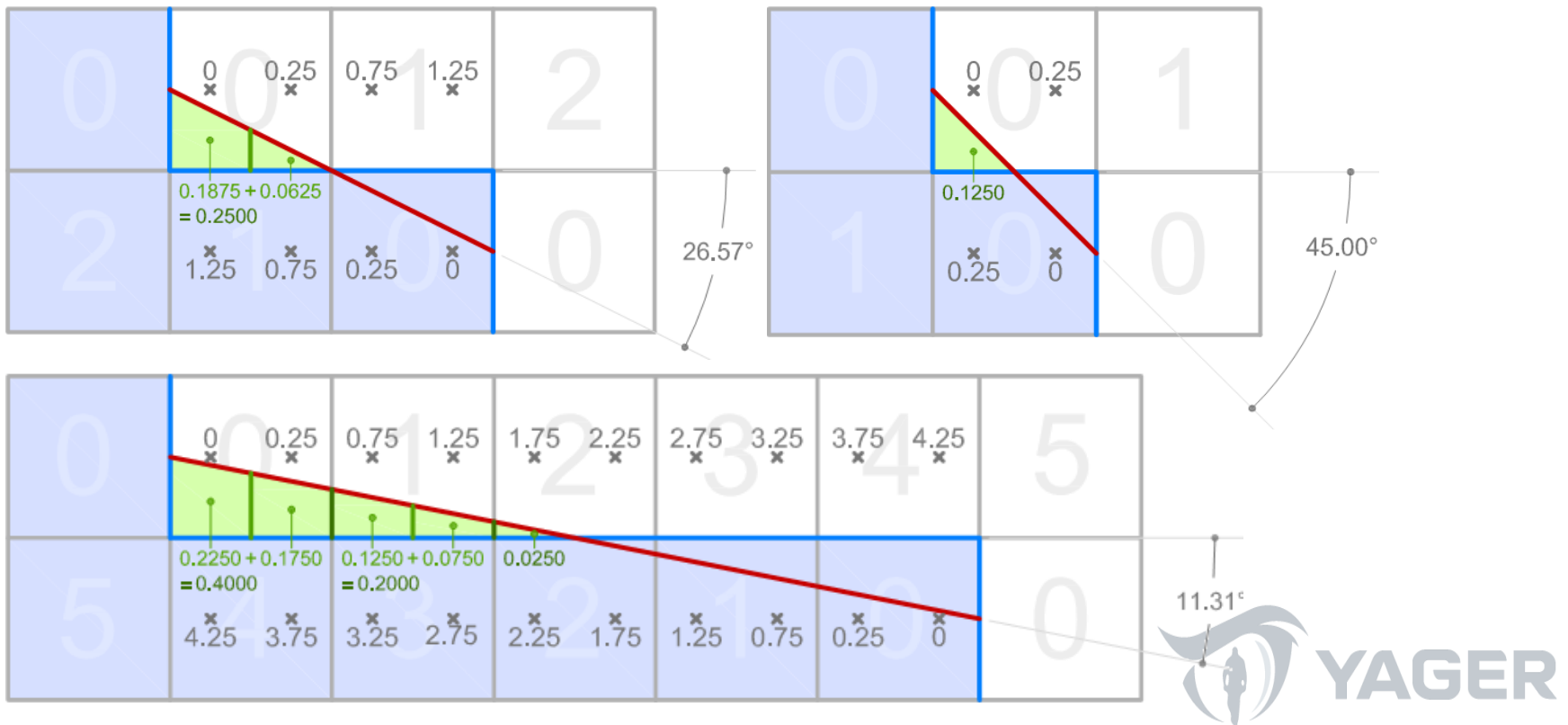
$$coverage = saturate\left(\frac{position}{2length}\right)$$

- Calculating coverage this way on 45° angles will result in no coverage at all ☹️

Advanced coverage calculation

- Use linear interpolation and calculate coverage for half-pixel

$$\text{coverage} = \text{saturate} \left(\frac{2\text{position} + \text{frac}(2\text{length})}{4\text{round}(2\text{length})} \right)$$



Advanced Screenspace Antialiasing

☹️ Ambiguous handling of U shapes

$$\lim_{nxt \rightarrow \infty} \text{satuate} \left(\frac{nxt - this}{2(this + nxt + 1)} \right) = 0.5$$

→← counting & shape					
∞	∞	∞	∞	∞	∞
0	0	1	1	0	0
1	2	3	3	2	1

😊 The memory usage is moderate

- 1 RGB buffer for counting and discontinuities (lower than 2xMSAA)
- 2 G16R16F buffer for normal and texture coordinates
 - Could be shared in our case
 - I recommend compressing these values because the edge detection shader is texture bound

😊 The algorithm uses no conditional branching

☹️ On the Xbox360 and PS3 the counting could be offloaded to the CPU

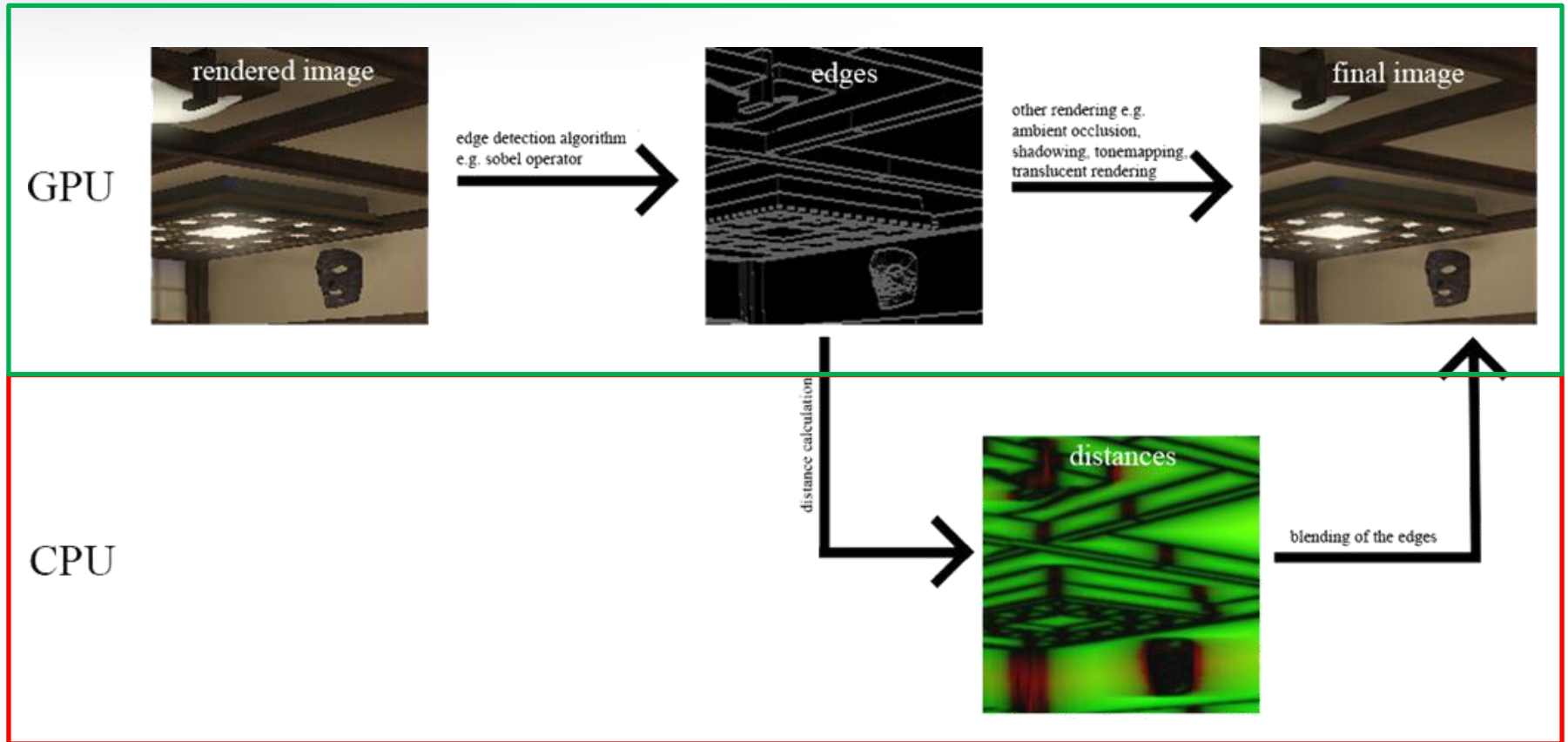
😊 Therefore it is suitable for current consoles



IMPLEMENTATION DETAILS



Overview



Blending optimization

- Blending of horizontal and vertical edges is done separately
- A stencil prepass guaranteed that the expensive blending shader would only be executed on the edges
- The blending itself can be calculated this way:

$$\begin{aligned} \text{minus} &= 1 - c0 - c1 \\ \text{upper}' &= \text{upper} * c0 \quad \text{lower}' = \text{lower} * c0 \\ \text{final} &= \text{center} * \text{minus} + \text{upper}' + \text{lower}' \end{aligned}$$

- To save one resolve operation between horizontal and vertical blending use alpha blend:

$$\begin{aligned} \text{DestAlpha} &= \text{minus} \quad \text{SrcAlpha} = \text{ONE} \quad \text{AlphaOp} = \text{ADD} \\ \text{SrcColor} &= \text{upper}' + \text{lower}' \end{aligned}$$



Linear textures on Xbox360

- Use MEMEXPORT in the pixelshader to write linear textures
 - Saves the resolve operation
- To save the expensive transpose operation on the CPU we pre-transposed the horizontal discontinuity buffer on the GPU
 - Exporting 4bytes per pixel was very expensive → ?cache line stalls?
 - Therefore we exported 48bytes per pixel 64bytes were not effective due to register spilling

```
int2 IntOffsets = round(InUV.xy * TexelOffset.xy);
int Stride = round(TexStrideWithPadding);
int offset = IntOffsets.y * Stride + IntOffsets.x;
asm
{
    alloc export=2
    mad eA, offset, const01, streamConstant
    mov eM0, OutValue.x
    mov eM1, OutValue.y
    mov eM2, OutValue.z
    mov eM3, OutValue.w
};
```



Counting on the GPU (for XNA)

- Initialize the counting buffer with the maximum value

↓↑ counting- & vertical discontinuity buffer							
F	F	F	F	F	F	F	F
F	F	F	F	F	F	F	F
F	F	F	F	F	F	F	F

→← counting- & horizontal discontinuity buffer							
F	F	F	F	F	F	F	F
F	F	F	F	F	F	F	F
F	F	F	F	F	F	F	F

- Zero where there is a discontinuity and mark the pixel for stencil rejection in subsequent passes
- Where there is no edge in the other discontinuity buffer mark the pixel for stencil rejection in subsequent passes

↓↑ counting- & stencil buffer							
F	F	0	0	0	0	F	F
0	0	0	0	0	0	F	F
0	0	F	F	F	F	F	F

→← counting- & stencil buffer							
F	F	F	F	F	0	0	F
F	0	0	F	F	F	F	F
F	F	F	F	F	F	F	F

Counting on the GPU

↓↑ counting- & stencil buffer							
F	F	0	0	0	0	F	F
0	0	0	0	0	0	F	F
0	0	F	F	F	F	F	F

→← counting- & stencil buffer							
F	F	F	F	F	0	0	F
F	0	0	F	F	F	F	F
F	F	F	F	F	F	F	F

- Start with **level = 1** and lookup **level** pixels in both directions (texture border will count as 0) and take the minimum of these values if the resulting **value** is not equal the **maximumValue = F** the current pixel is updated with **result = value + level** and **mark the pixel for stencil rejection** in subsequent passes else **reject the pixel**

↓↑ counting- & stencil buffer							
F	F	0	0	0	0	1	F
0	0	0	0	0	0	F	F
0	0	F	F	F	F	F	F

→← counting- & stencil buffer							
F	F	F	F	1	0	0	F
1	0	0	1	F	F	F	F
1	F	F	F	F	F	F	F

Counting on the GPU

↓↑ counting- & stencil buffer							
F	F	0	0	0	0	1	F
0	0	0	0	0	0	F	F
0	0	F	F	F	F	F	F

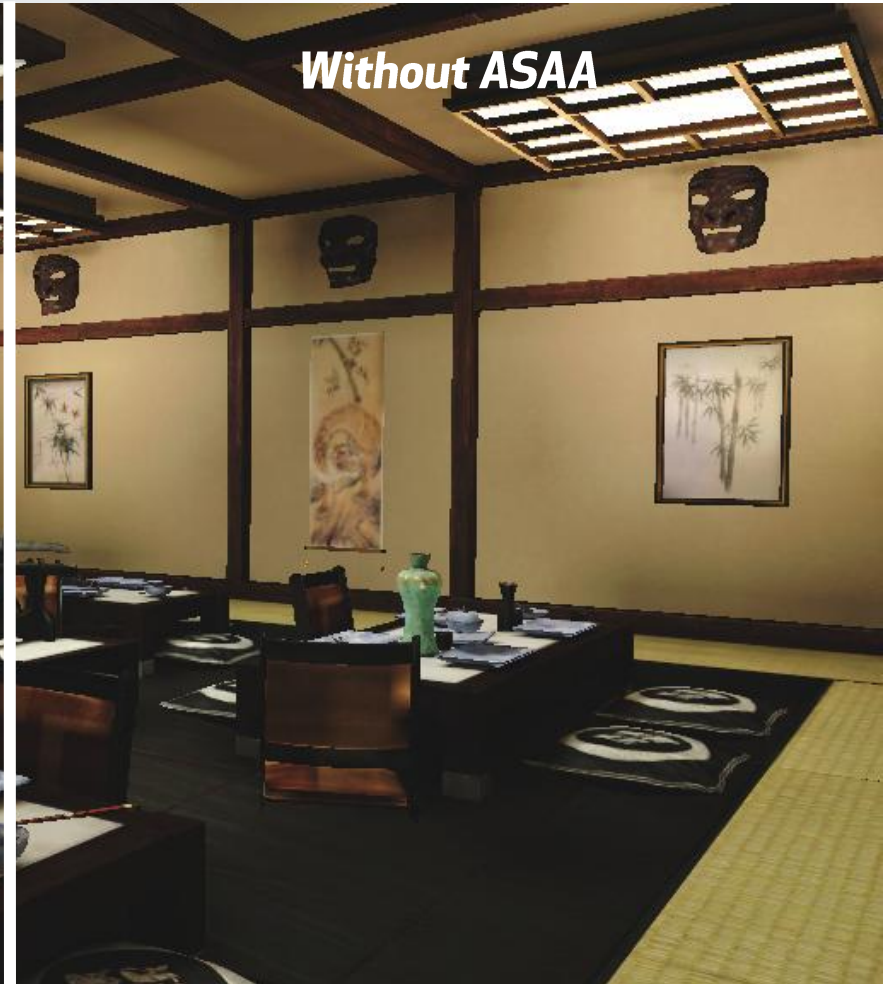
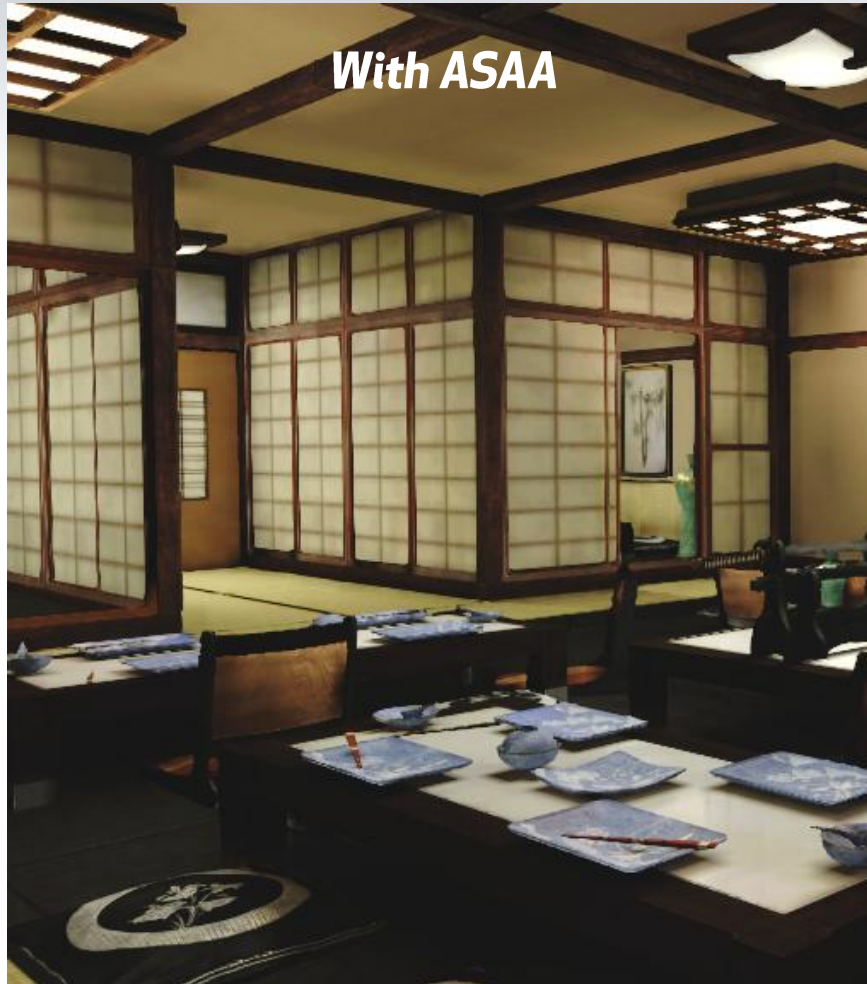
→← counting- & stencil buffer							
F	F	F	F	1	0	0	F
1	0	0	1	F	F	F	F
1	F	F	F	F	F	F	F

- continue with level *= 2 (level is now 2):
- do this repeatedly until no further pixels are drawn or maximum precision is reached
- Remember the maximum number of passes is equal to the number of bits used per counting value

↓↑ counting- & stencil buffer							
F	F	0	0	0	0	1	F
0	0	0	0	0	0	F	F
0	0	F	F	F	F	F	F

→← counting- & stencil buffer							
F	F	3	2	1	0	0	F
1	0	0	1	2	3	F	F
1	2	F	F	F	F	F	F

Demo



"If you can't make it good, at least make it look good."

Bill Gates



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