

### **Evolving Mixed Reality** Designing on the Real World

**Ran Gal Microsoft Research** 

> **Brian Schwab** Magic Leap

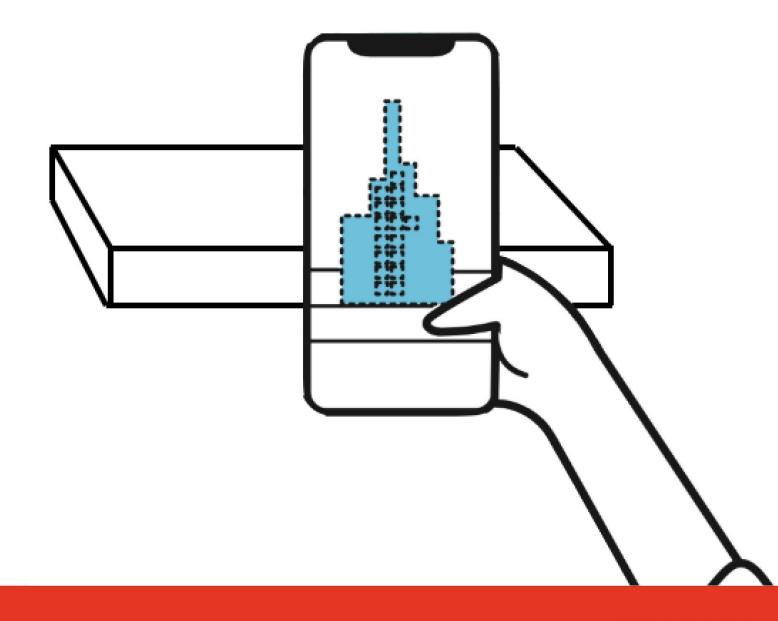
Samantha Gorman **Tender Claws** 

> **Jono Forbes** Unity



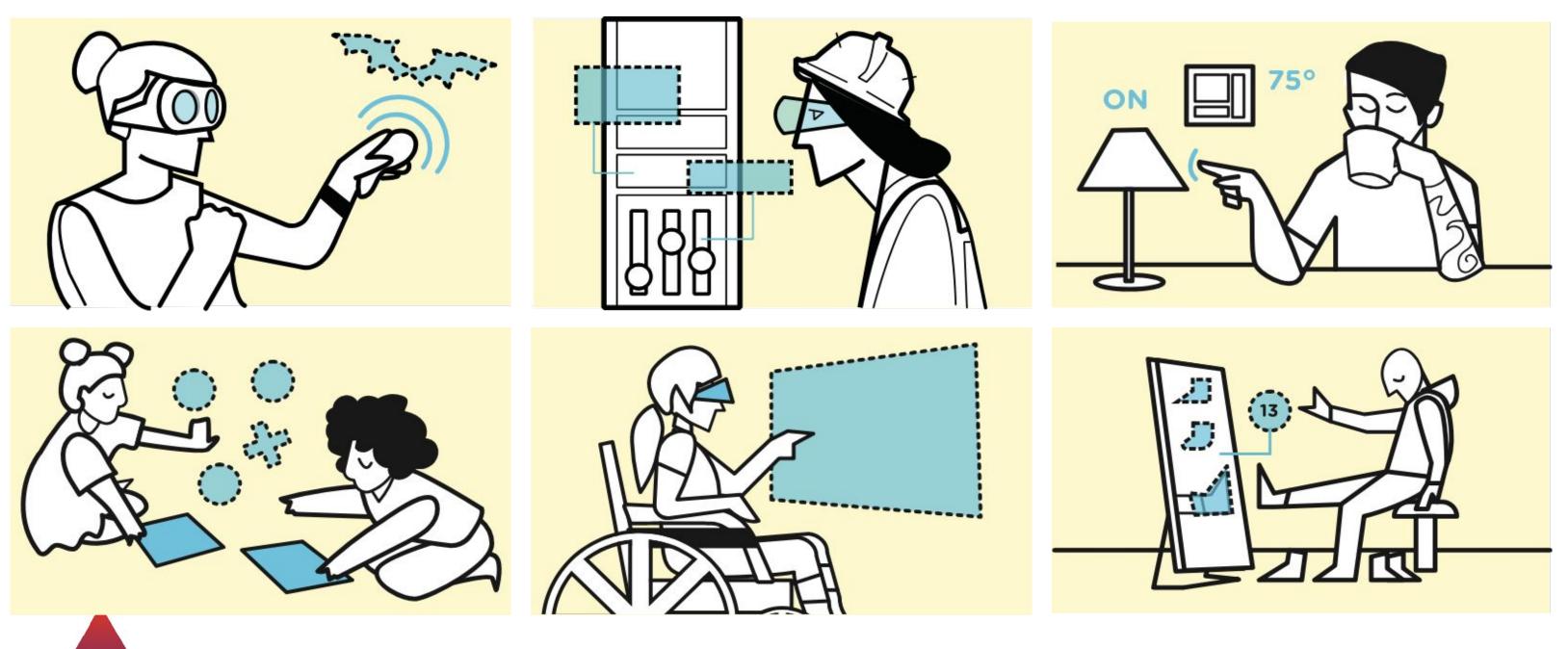


## Where We Are Today



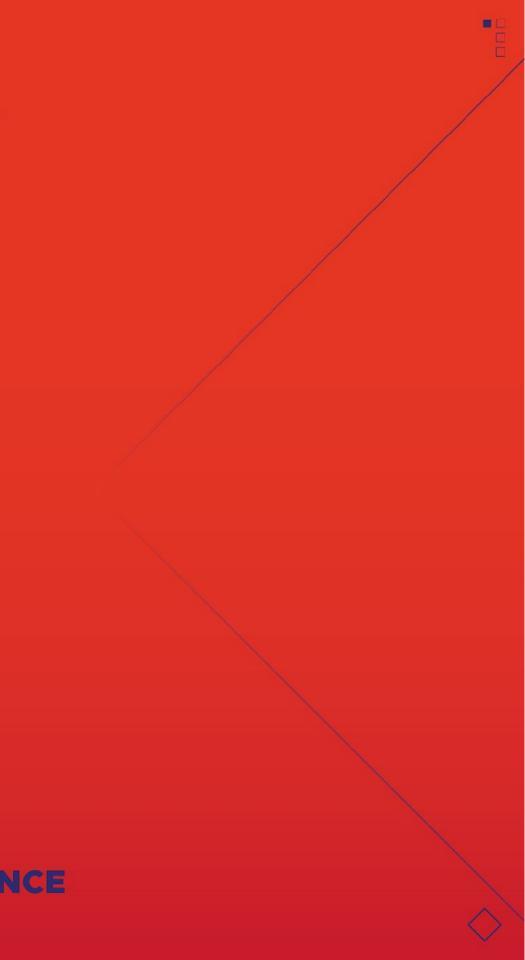


## Where We're Going





### Ran Gal Microsoft Research



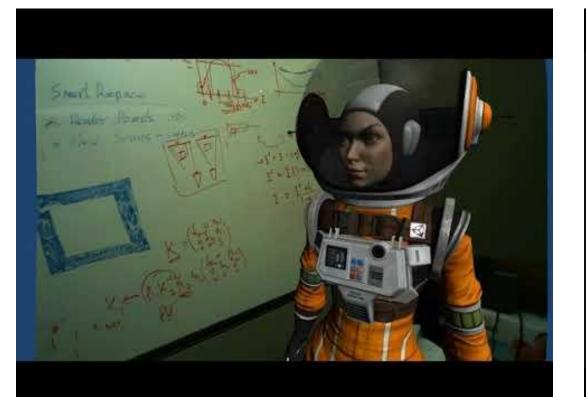
## FLARE

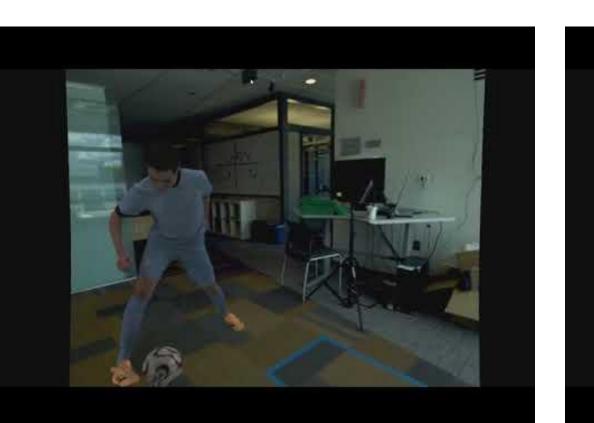






## More Examples









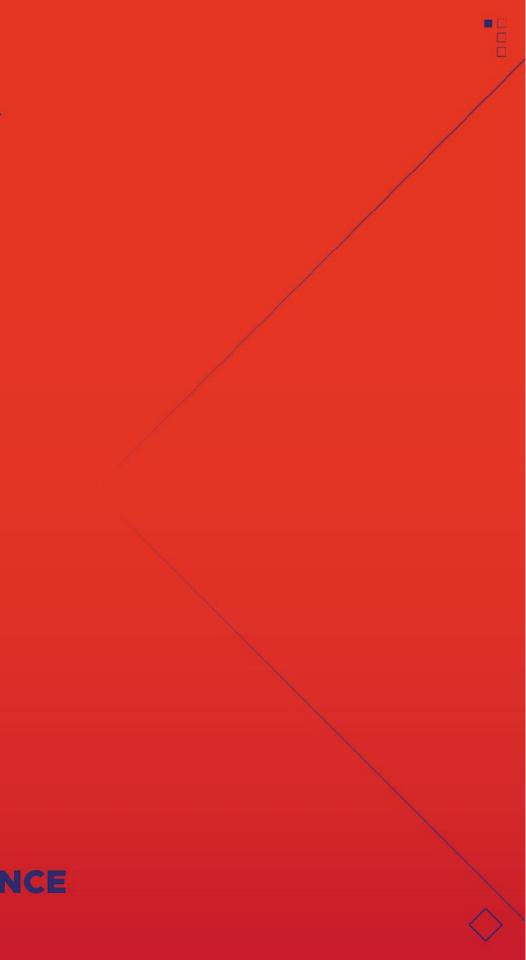








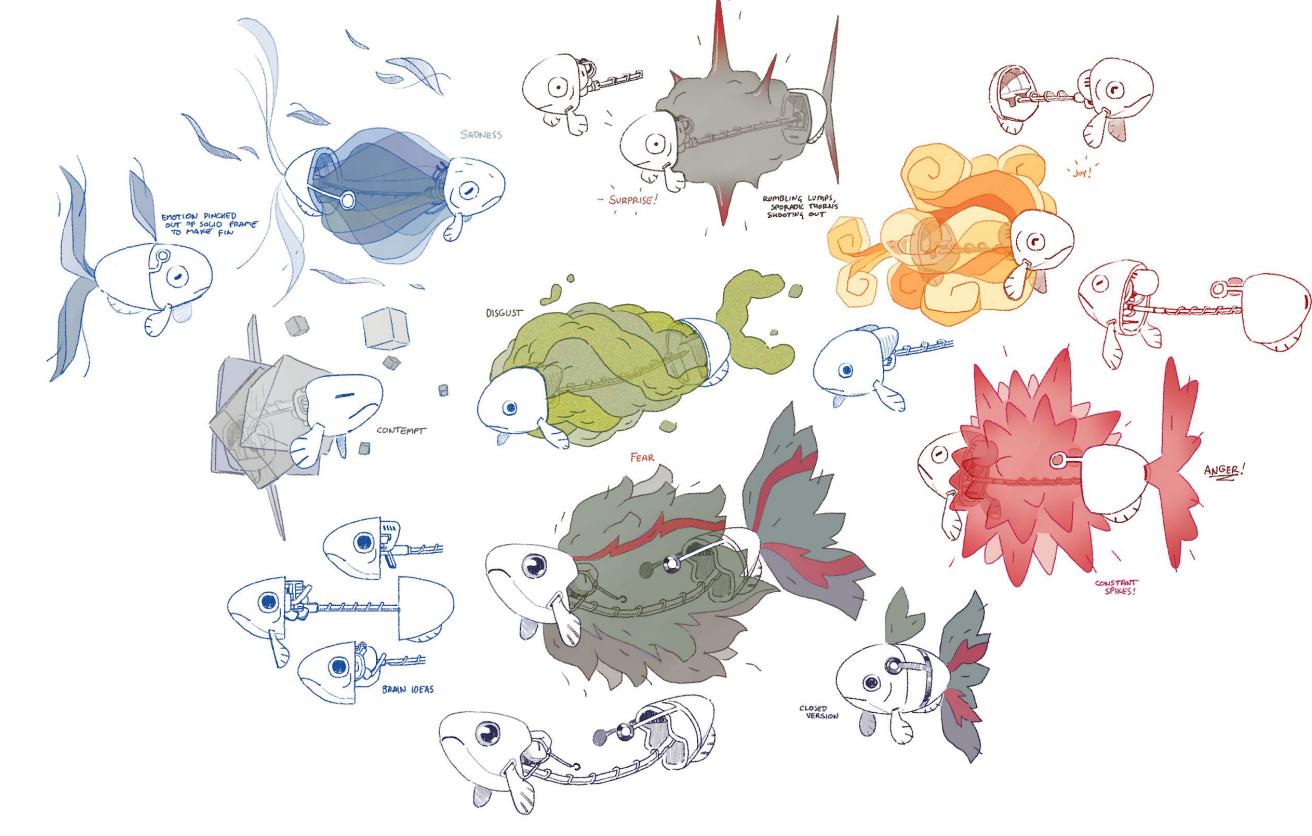
### Samantha Gorman Tender Claws













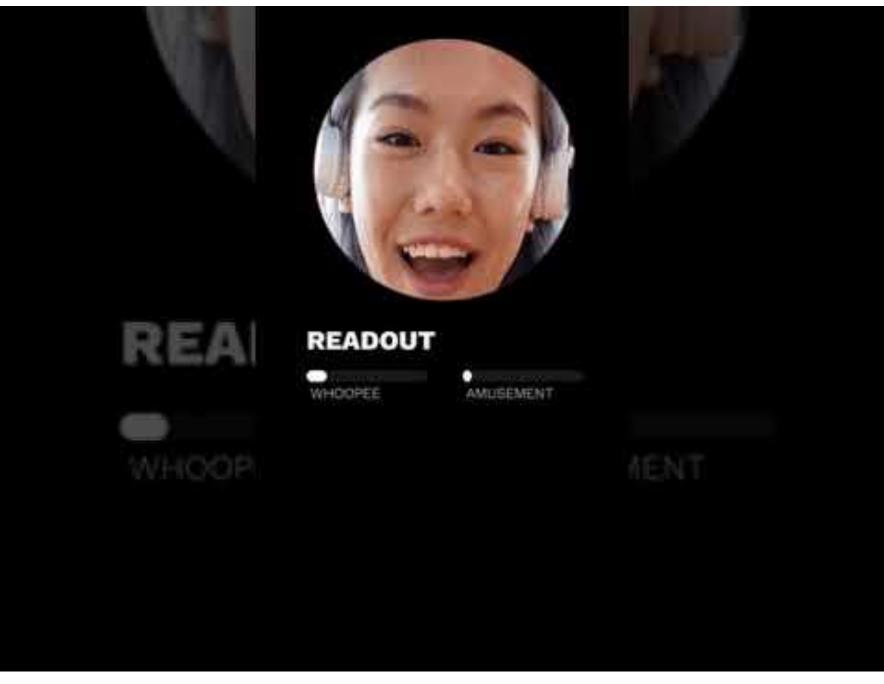






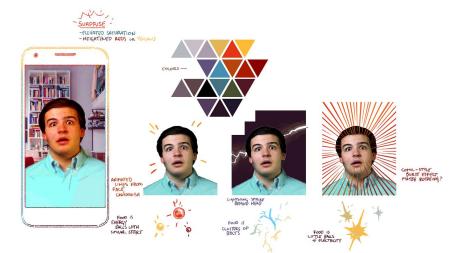


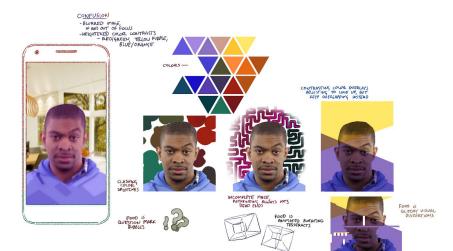
## World Context Independent

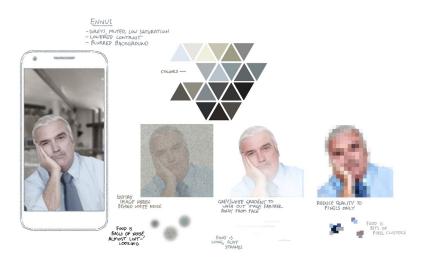


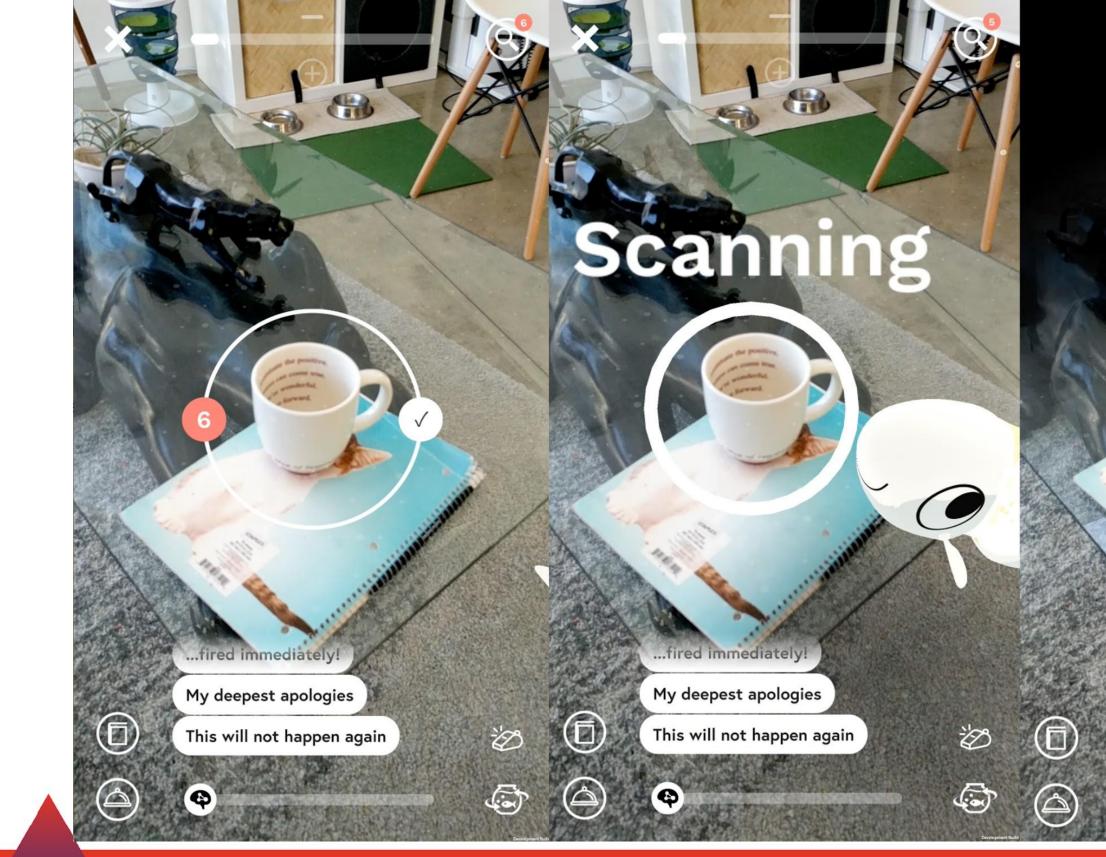














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B

S

# object learned

#### ADD TO INVENTORY

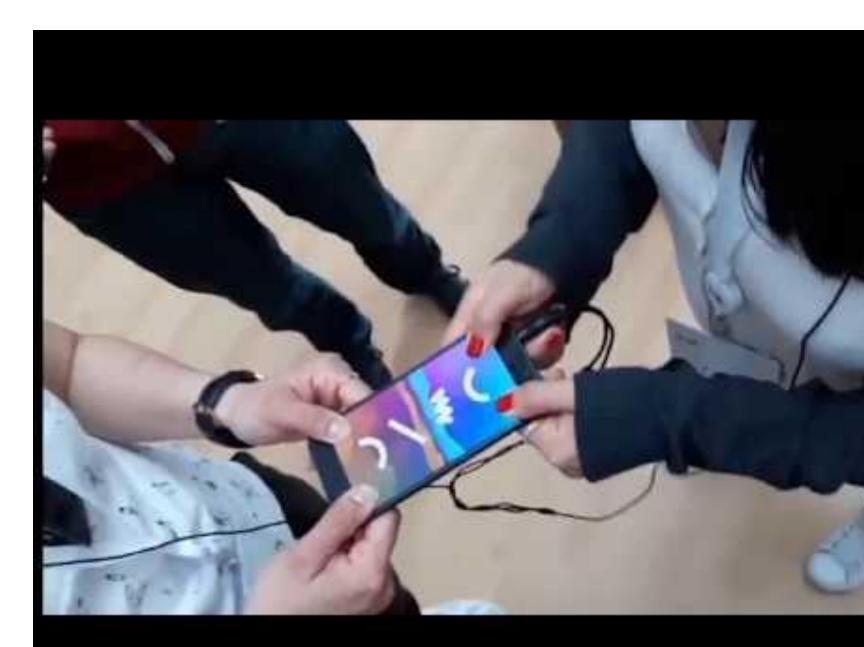
#### This will not happen again

My deepest apologies

Oh look a cup!!

\$

## Meaningful Social Play









### **Brian Schwab** Magic Leap - Interaction Lab





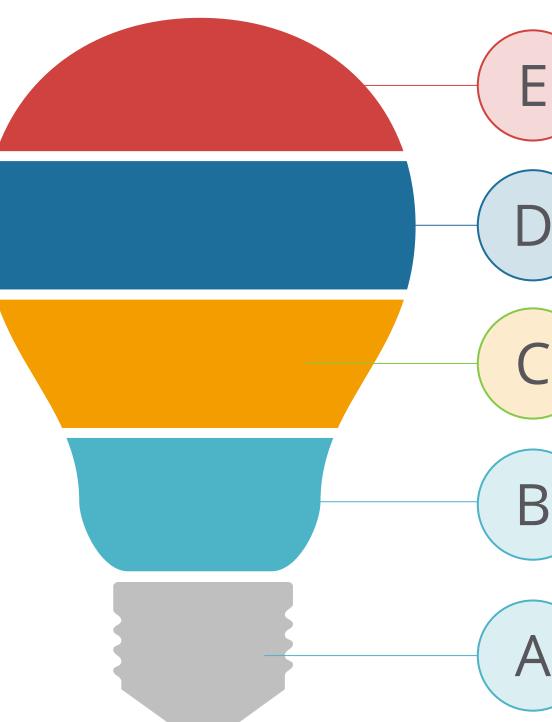
### Interaction Lab



## What is the Lab?

Small team, mostly engineers, rapid prototypers.

Sit between hardware/perception and the SDK group.





Documentation & Best Practices

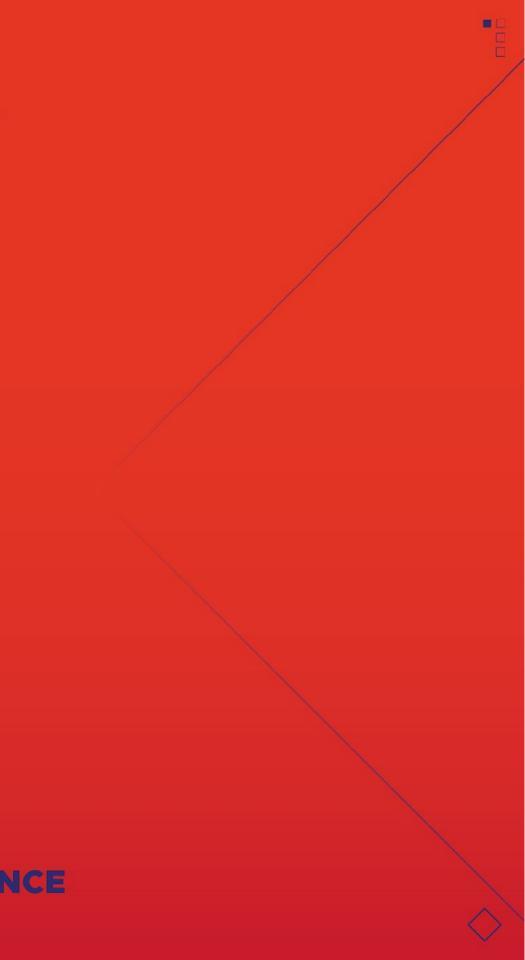
Pre-SDK API iteration

Feature guidance and exploration

First Turn On



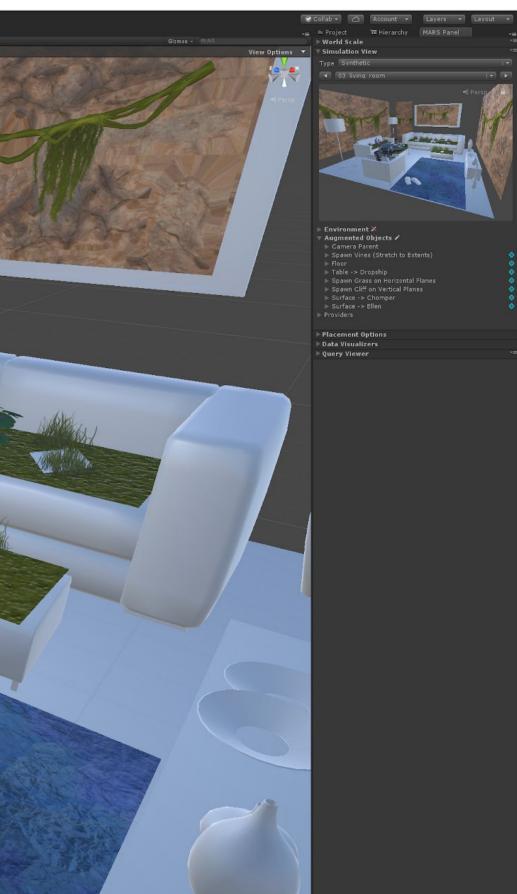
### Jono Forbes Unity Labs - MARS

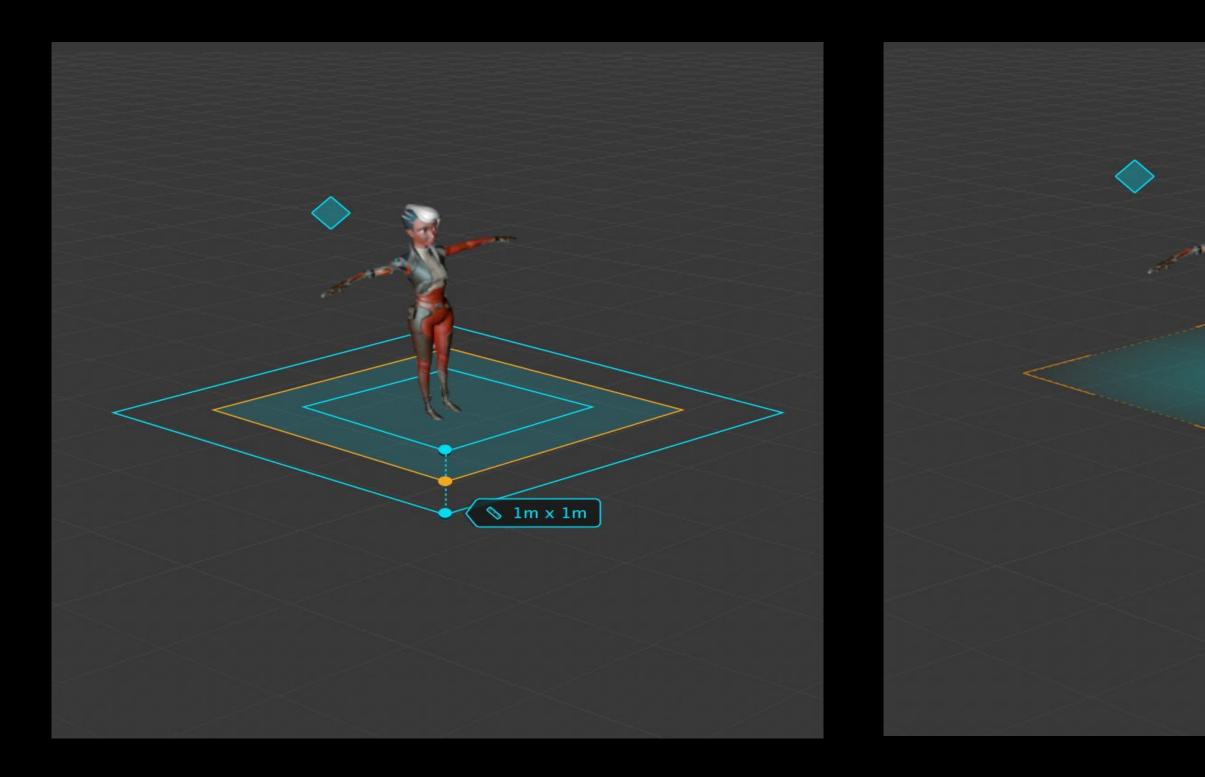


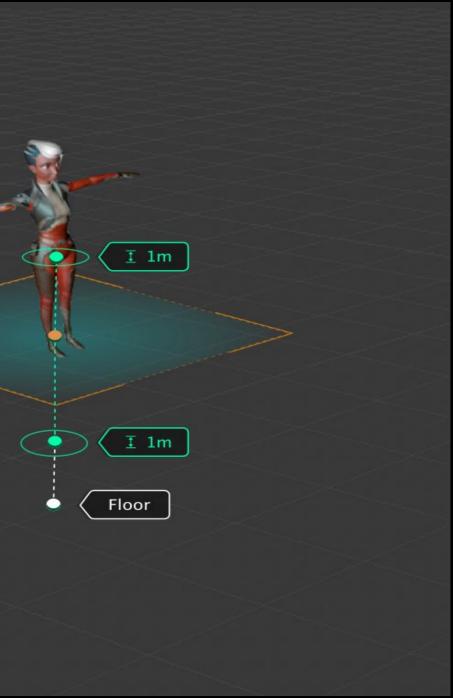
File Edit Assets GameObject Component ARTools MARS Window Help 한 + S 또 미 () ㅋㅋPivot OGlobal #Scene Simulation Vier ⊕ Sim Device Shaded - 2D 💥 +1) 📼 ⊡

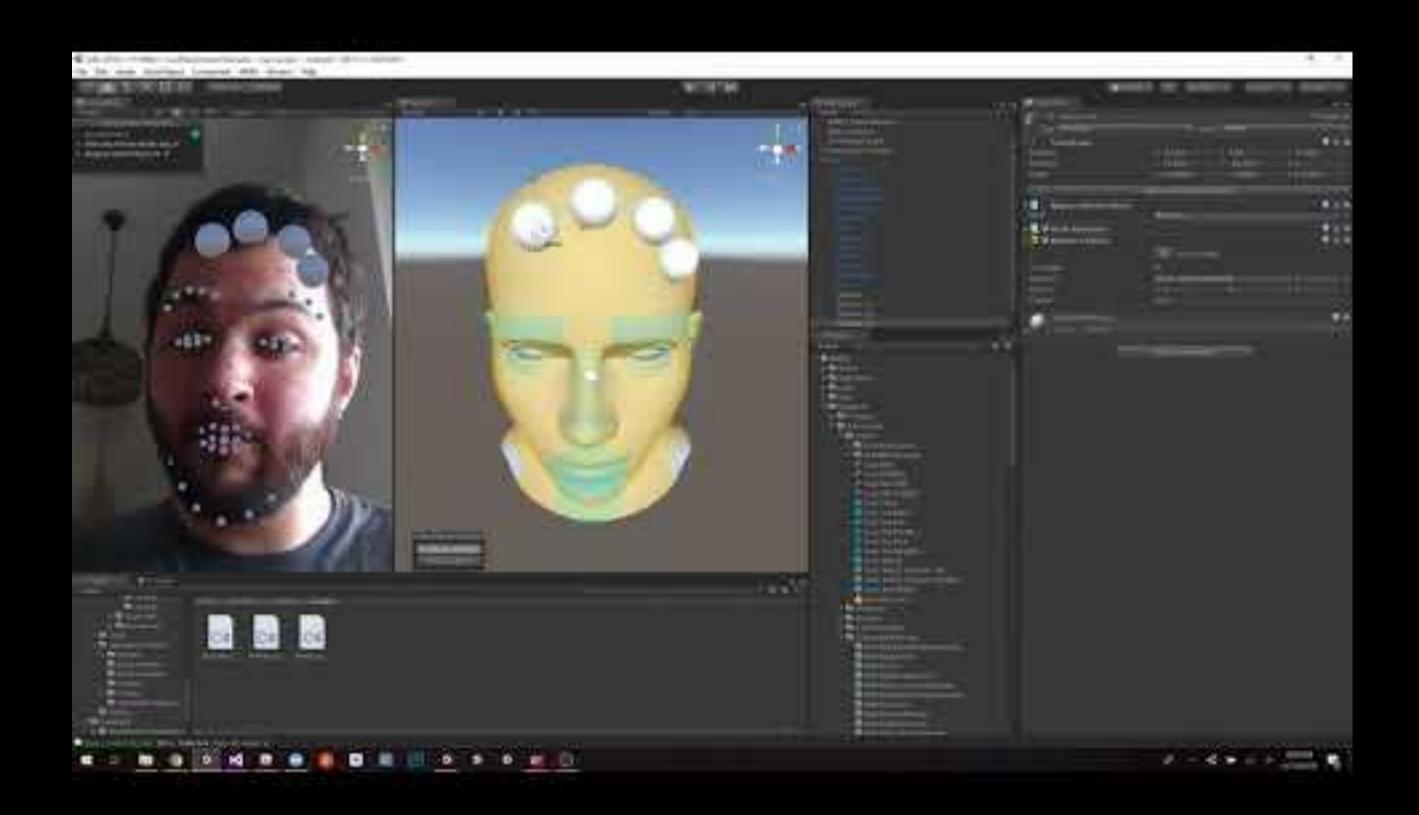


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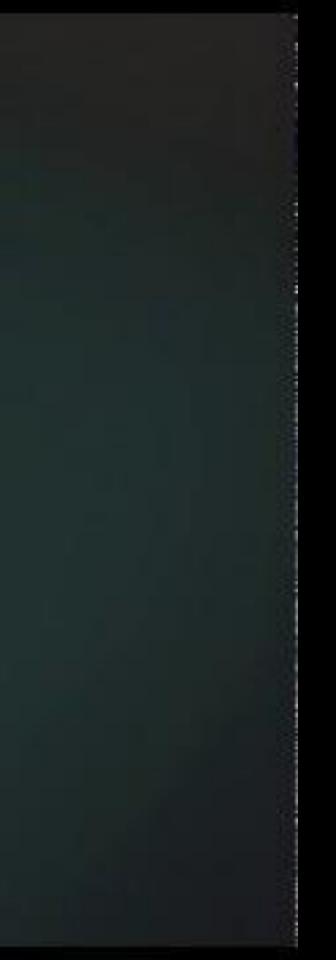






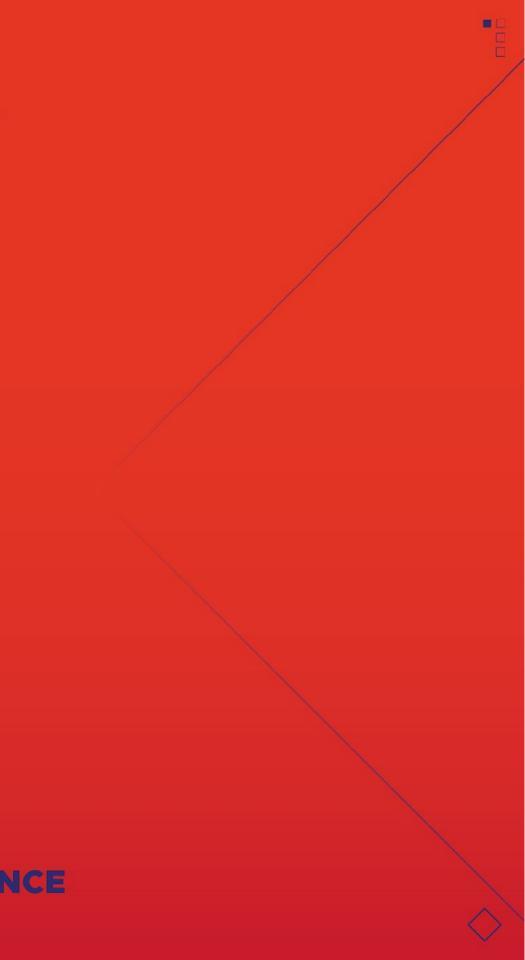








### Challenges of AR



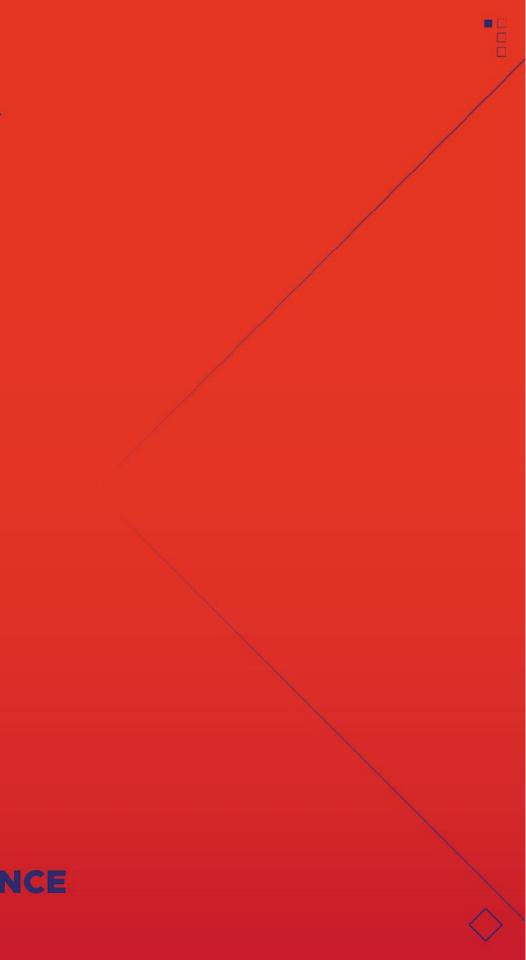


### The Unknown Real World

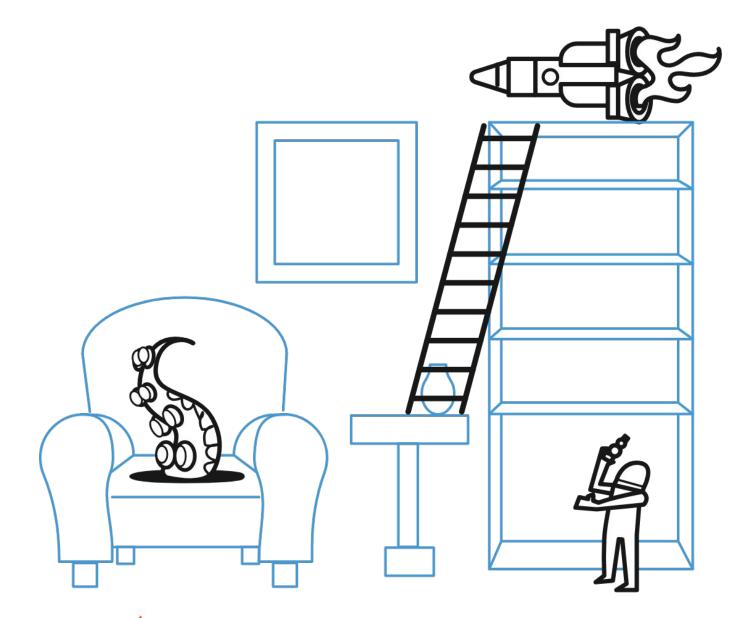


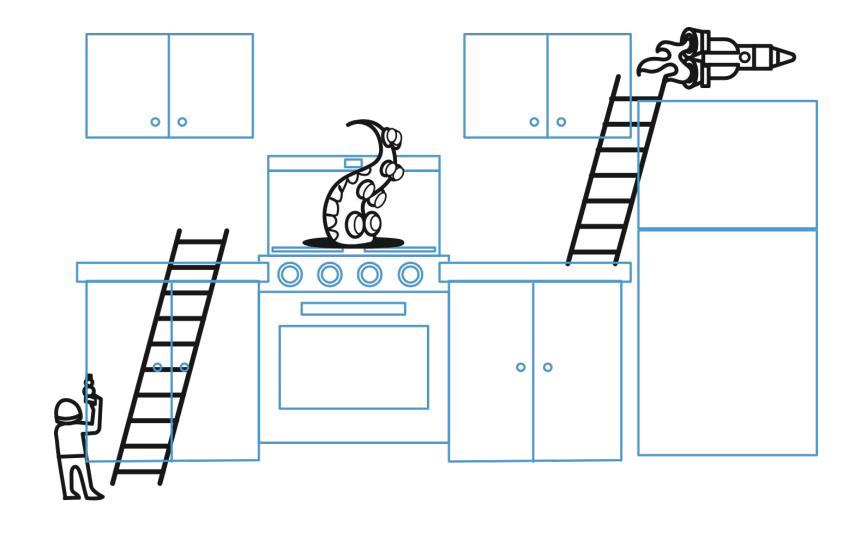


### Rules, Constraints, Conditions, Fallbacks



## Responsive Design



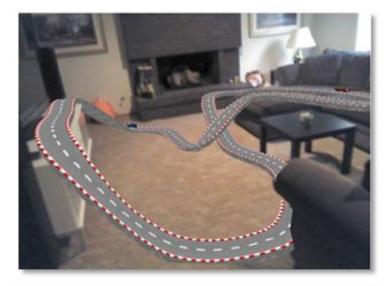




# Reality is Complex

- Challenges
  - Layout consistency
    - With Other Virtual Content
    - With the Physical Environment
  - Handling Several Application in the same space
  - Handling Several Users in the same space





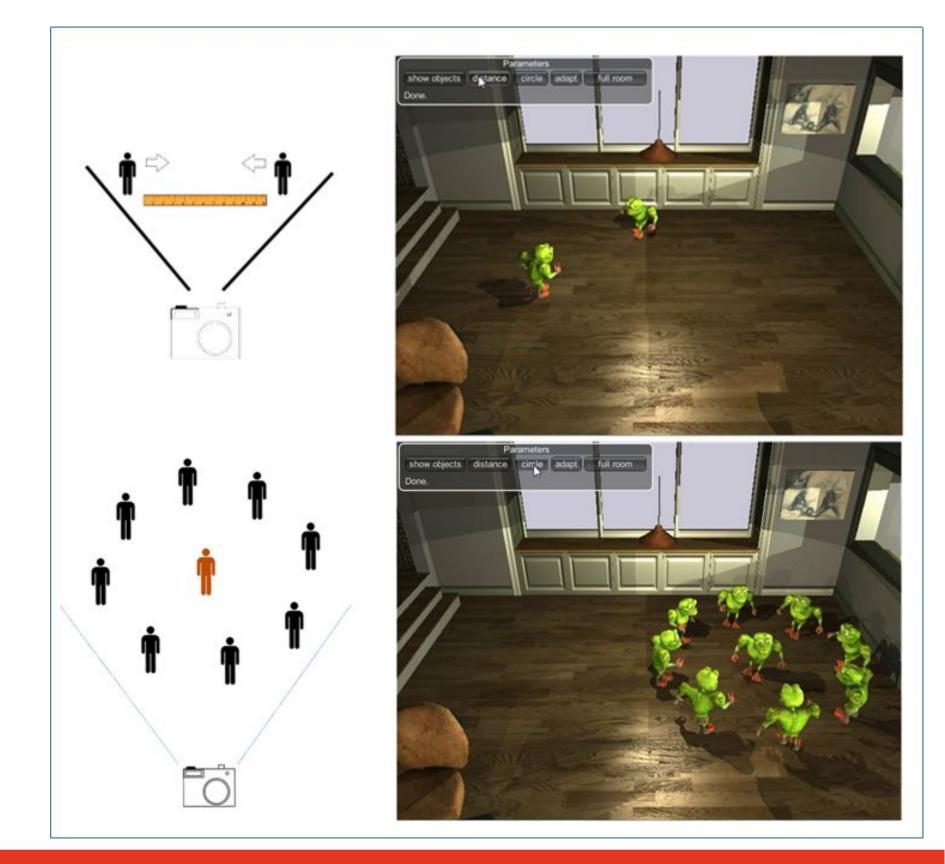




## FLARE

### • Use Declarative Rules

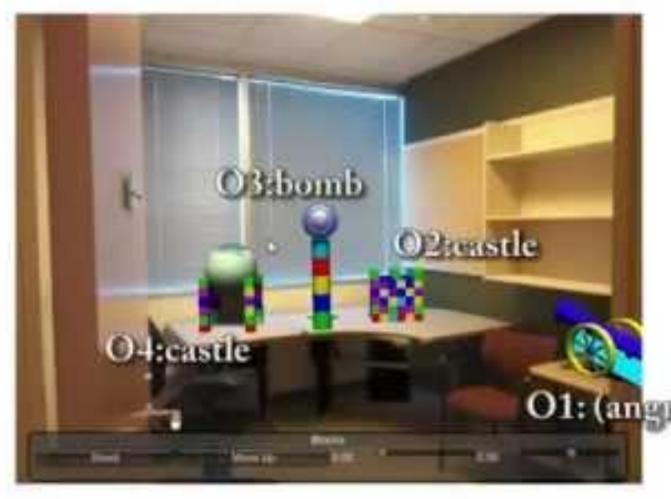
- Constraining Elements **Properties using Cost Functions**
- Solve as a constraint satisfaction problem
  - Solution's quality depends on allocated cycles





## Race Track







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## Race Track

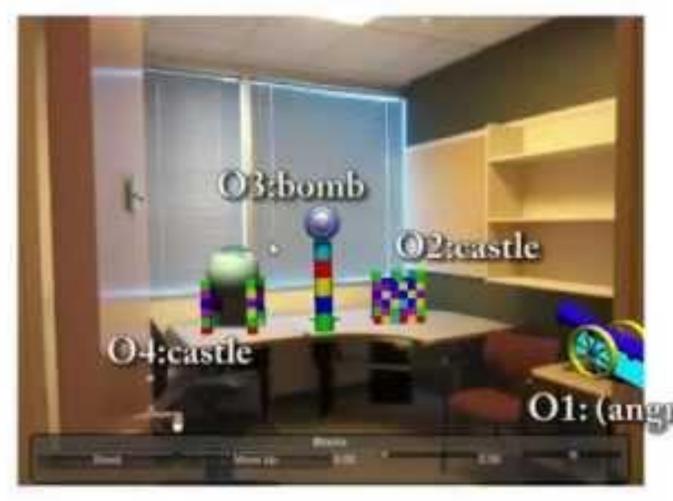






## Graceful Adaptation







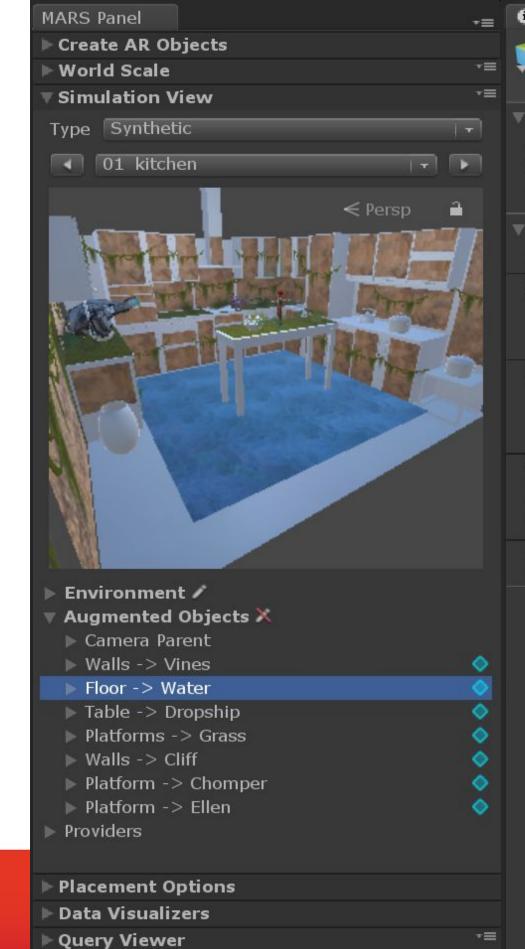
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## MARS

- Real World Objects
- Conditions
- Rules
- Fallbacks





Inspector			<b>-</b> =
Floor Tag Untagged		Layer Defa	Static ▼
L Transform			🕅 🗔 🔅
Position	хо	Y 0	Z 0
Rotation	X 0	Y 0	Z 0
Scale	X 1	Y 1	Z 1
🗟 🔽 Real World	Object (Sci	ript)	🕅 ⊒! \$,
Components			
🗸 Tag Condition			*≡
Trait Name Match Rule	floor Exclud	le	÷
🗸 Alignment Cor	ndition		*≡
Alignment	Horizo	ntal	
Set Rotation:		Horizontal	Vertical Default
🗸 Plane Size Cor	dition		*=
🗸 🛛 Minimum Size	X 0.5	Y 1	
🗸 🛛 Maximum Size	X 2	Y 4	
	Add MARS Cor	mponent	)
	Add Compo	onent	

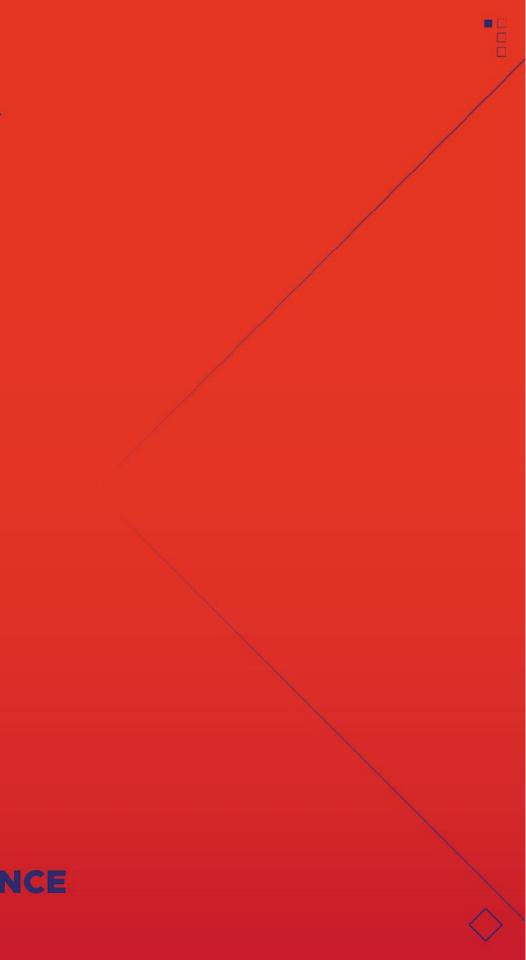
# The "generic" AR rules pipeline

- Sensing depth, RGB, IR, motion, acceleration, audio, lighting, etc.
- Analysis
  - Room structure, Hole filling, Detection and Classification.
  - More semantic information leads to more intelligent layouts.
- Layout the experience in the current environment
- Apply the Experience's logic
- Continue sensing and responding to environmental events
  - Allowing for Graceful Adaptation



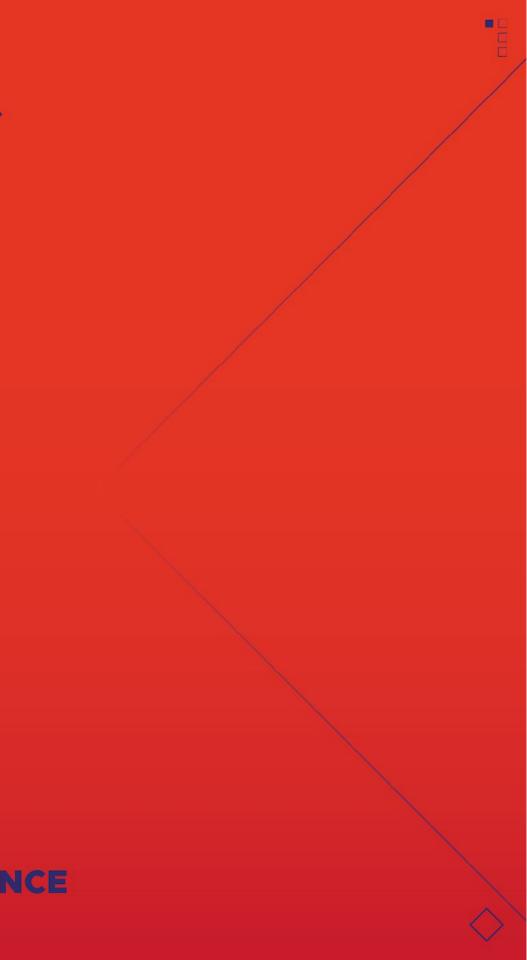


### Machine Learning



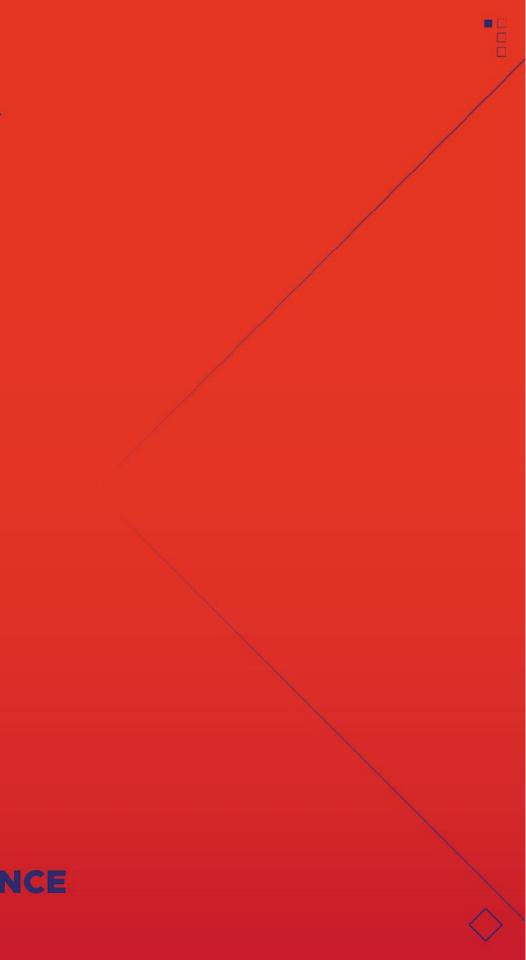


### User Input & Intent



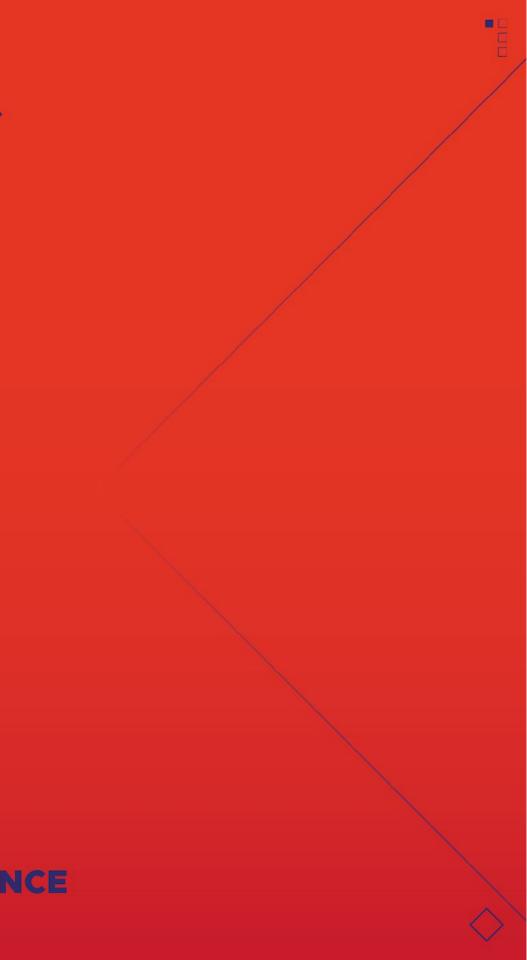


### **Going Procedural**





### **Tools & Workflows**



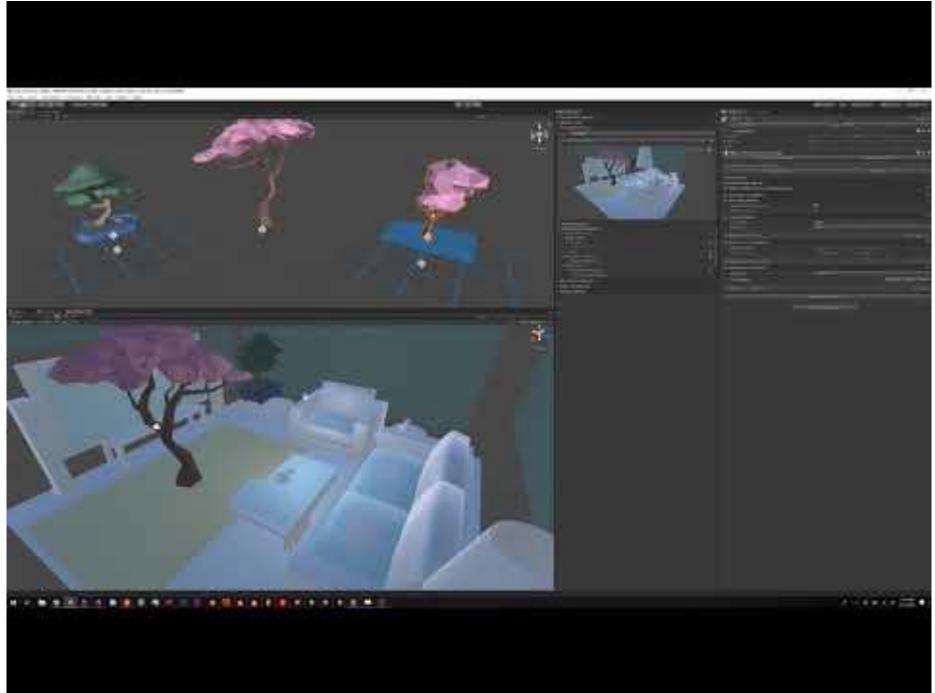
## Simulation





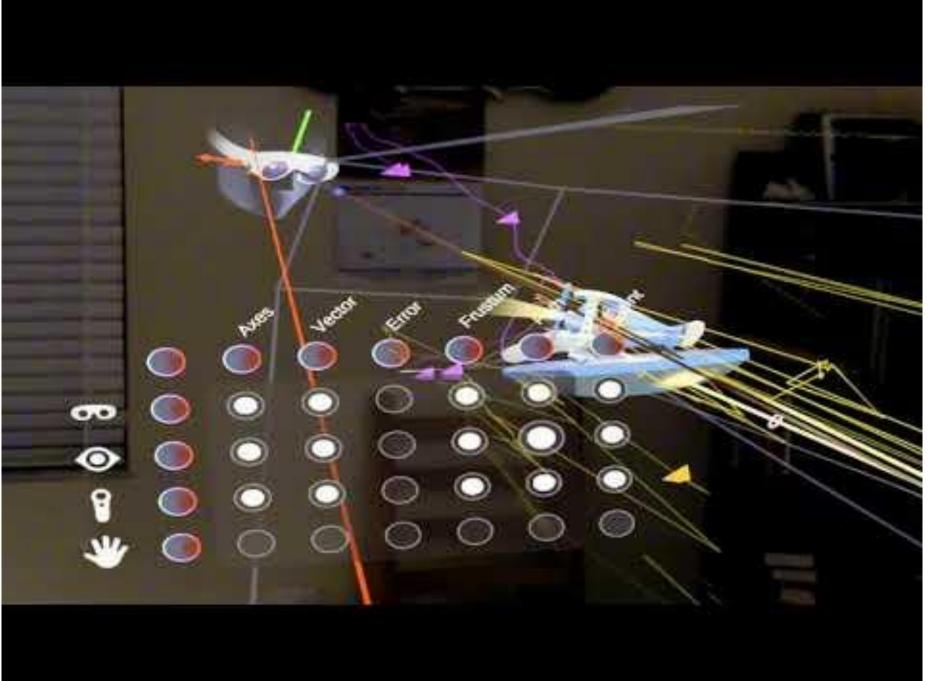


## In Editor Debugging



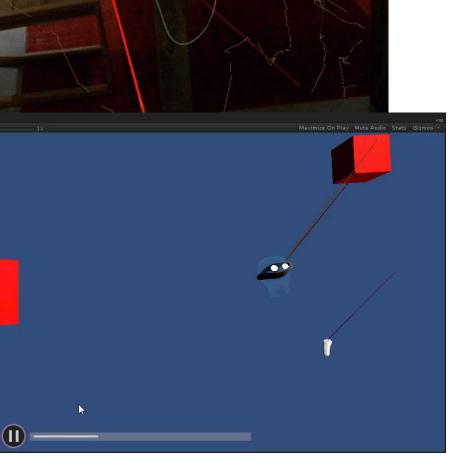


# In Experience Debugging





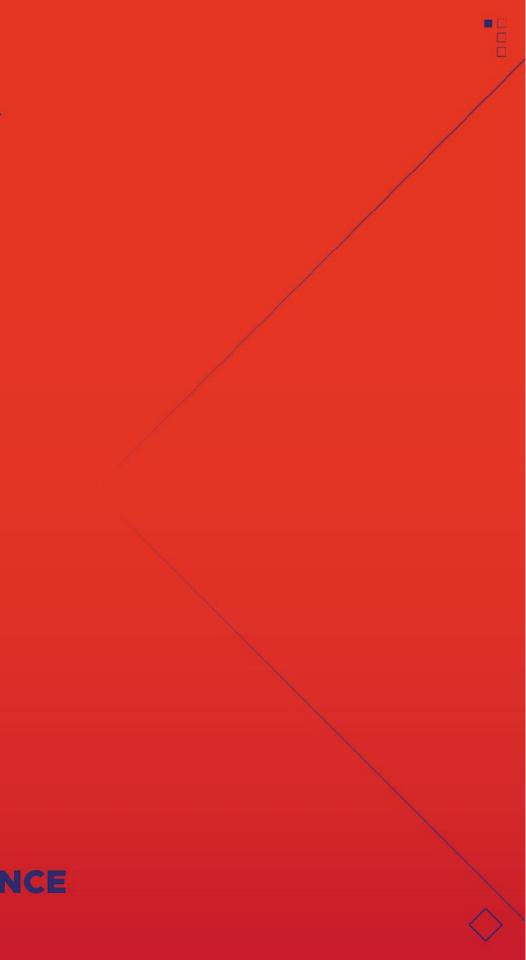








### XR Ecosystem



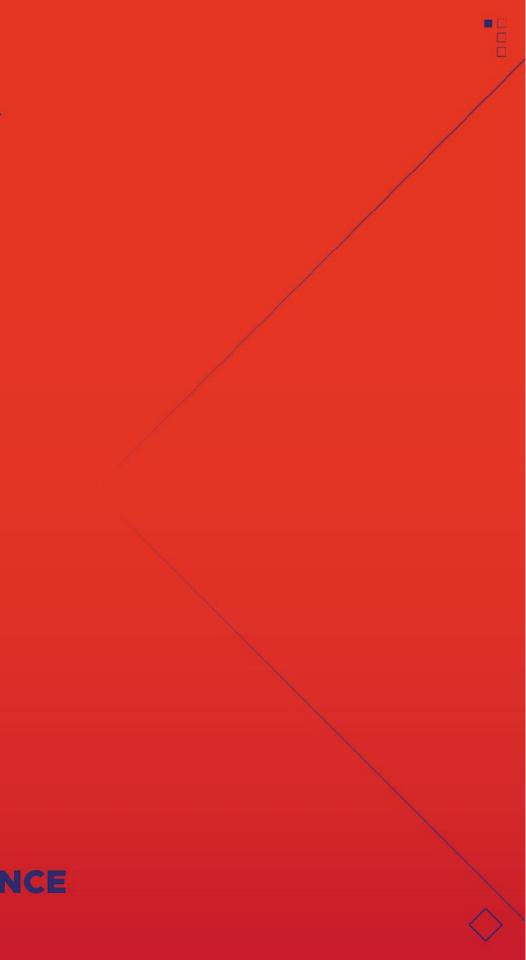
## Many Moving Targets

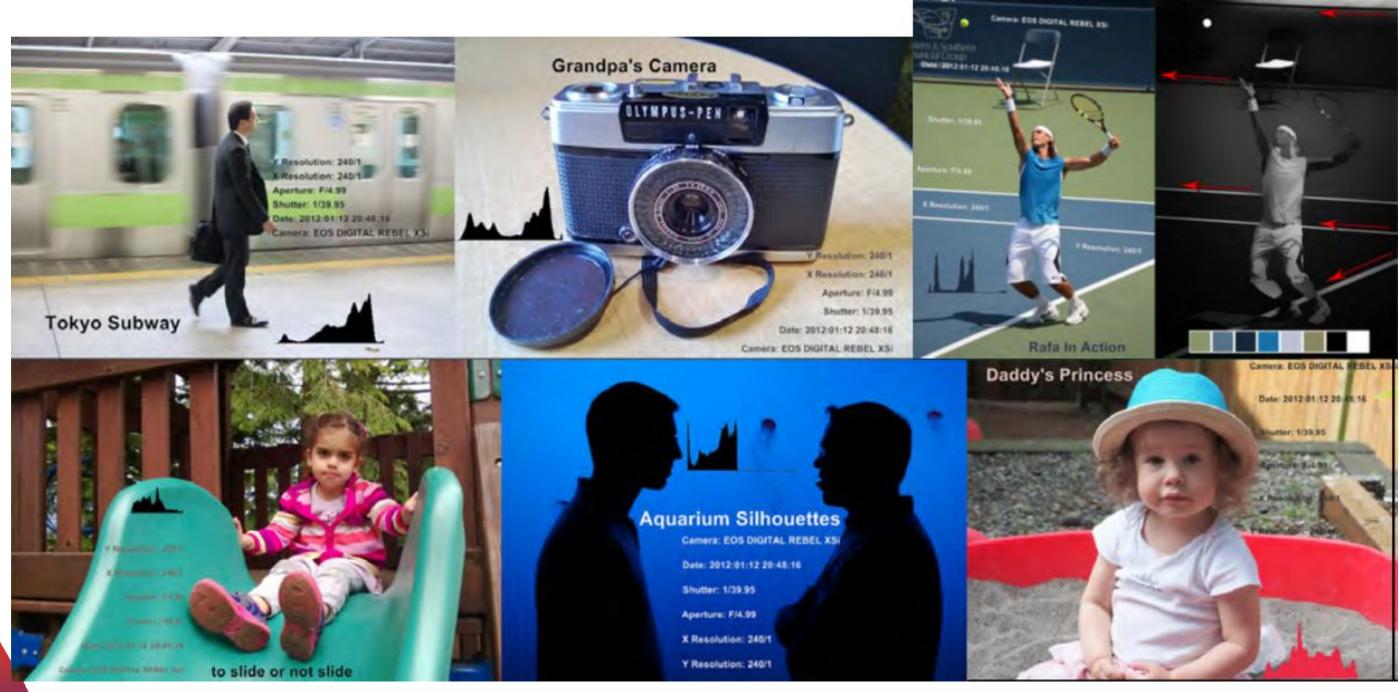
A Name -	O Surfaces 👻	O Hit Tests 🔹	O Meshi	O Markers -	O Relocaliz	Camera Pose 🔹	O Faces 🔹	Controller Tr •	O 3D Markers 🔹	Object Reco 🔻	O Light Estima 🔻	O Eye Trac
ARKit	Yes	Yes		Yes	Yes	Yes	Yes		Yes	Partial	Yes	
ARCore	Yes	Yes		Partial	Yes	Yes	Yes				Partial	
Tango (defunct)			Yes		Yes	Yes					Yes	
Hololens		Yes	Yes		Yes	Yes						
Magic Leap	Yes	Yes	Yes	Yes	Yes	Yes		Yes				Yes
6d.ai			Yes		Yes							
HTC Vive Pro	Yes	Yes	Yes		Yes	Yes		Yes				
Windows MR						Yes		Yes				
Mirage Solo						Yes		Yes				
HTC Vive						Yes		Yes				
Oculus Quest						Yes		Yes				
Oculus Rift						Yes		Yes				
Oculus Go								Yes				
Vuforia						Yes			Yes		Yes	
Placenote					Yes							
Selerio									Yes	Yes		
ULsee							Yes					
Visage							Yes					
Google Mobile Vision							Partial			Yes		
Apple Vision							Partial			Yes		
Wrnch.ai												
Leap Motion												
OpenCV	Partial		Yes	Yes		Partial						
dlib			Yes									
Resonai			Yes							Yes		



Tracking 👻	O Body Tracking 👻	O Hand Tracki 👻	O Hand Pose 🔹	🖸 Object Seg 👻
		Yes	Yes	
		Yes	Yes	
				Yes
	Yes	Yes	-	
	_	Yes	Yes	
	Yes	Yes		
				Yes

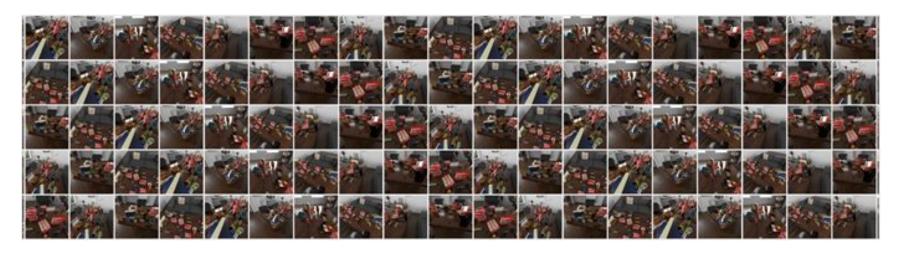








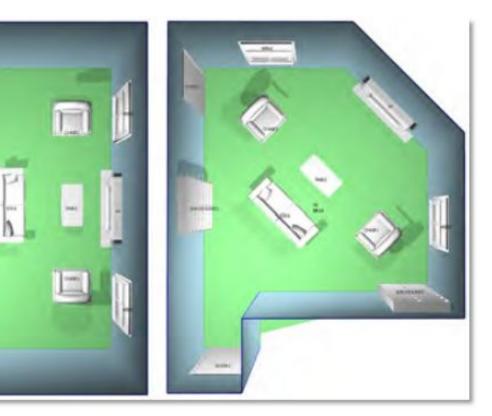




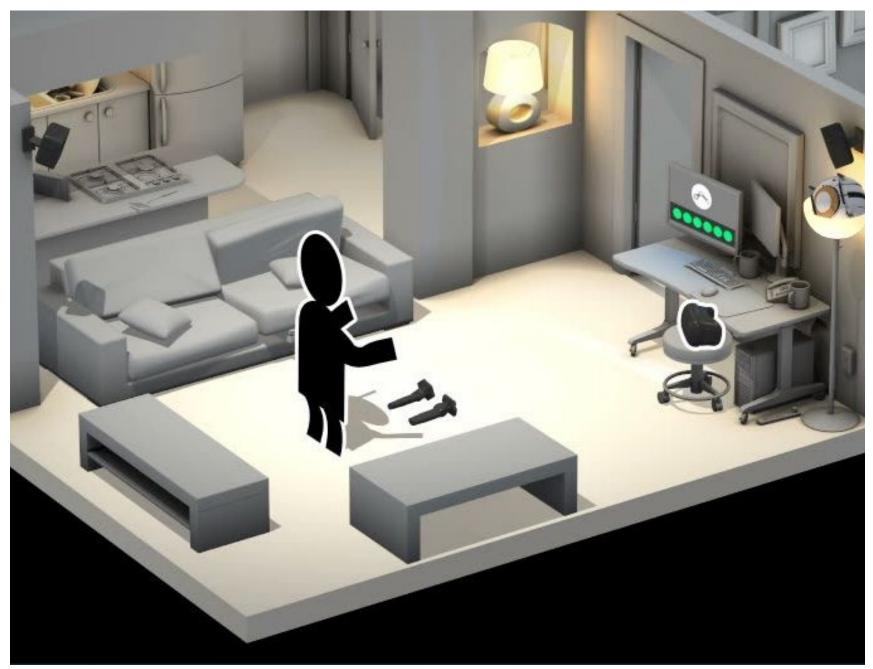
















## Much more to uncover

- Layers of apps, content, styles
- Permissions
- Privacy & Ethics



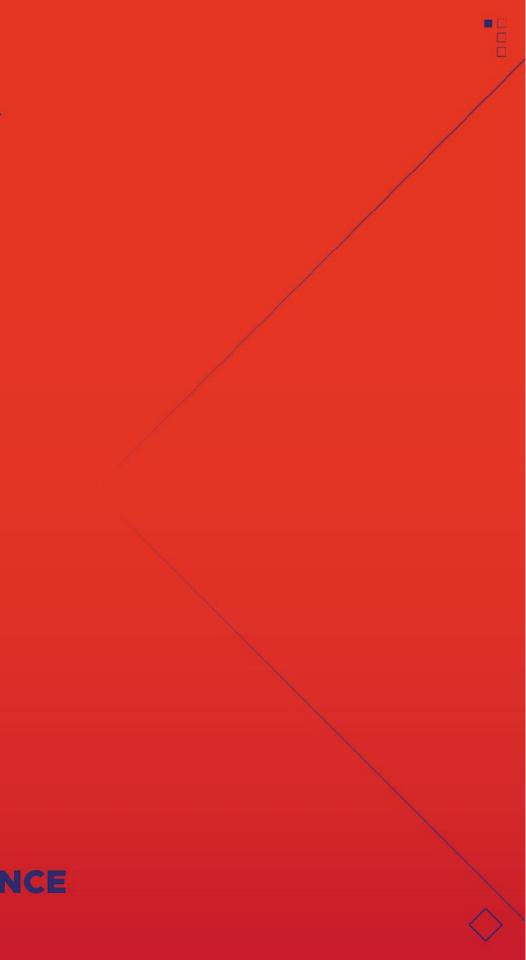
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### **Thank You!**

### Time for Questions?

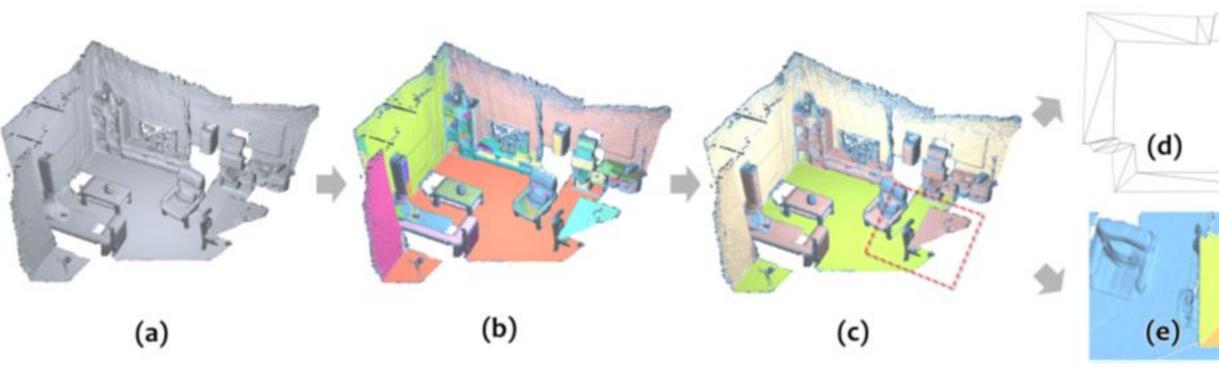


### **Additional Slides**



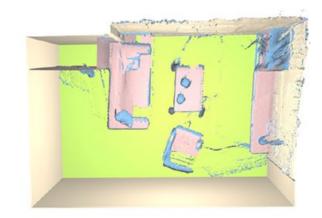


## Contour and Surface Completion









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(f)

## Contour and Surface Completion

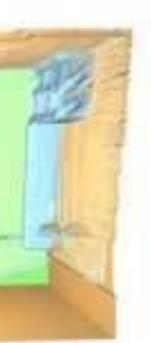
### Example 1: Living Room

Room after completion









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### Layout Design for AR Applications

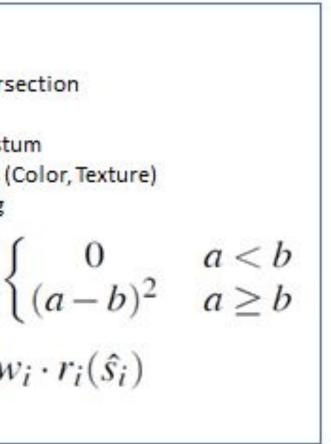
- A designer specifies the layout of the application
  - Elements
    - 3D Object -
      - Type, Orientation, Scale.
    - Frustum
      - Orientation, Field of view, Clipping Planes.
  - Rules
    - Algebraic notation
    - A library of predefined routines
    - Comparison and Boolean operators.
      - cost(OR(a, b)) = min(cost(a), cost(b)),
      - cost(AND(a, b)) = cost(a) + cost(b).

#### Predefined Routines:

- Distance / Angles
- BB / Geometry Intersection
- Line of Sight
- Inside/Outside Frustum
- Material Properties (Color, Texture)
- **Relative Positioning**

$$cost(a < b) =$$





```
// 'F' is the user's frustum.
Screen1:=Object3 ( [28 18 10], VERTICAL, OptPos );
                                                      // A screen on the wall
// 4 media objects.
```

```
01:=Object3 ( [10 10 10], HORIZONTAL, OptPos );
02:=Object3 ( [10 10 10], HORIZONTAL, OptPos );
O3:=Object3 ( [10 10 10], HORIZONTAL, OptPos );
04:=Object3 ( [10 10 10], HORIZONTAL, OptPos );
```

Assert ( LocalZ ( FloorFrame.Frame, Screen1.Frame.Position ) < 50 ); // be too high above the floor

// Prevent the hanged screen to

```
// Bring Screen1 to the center of view (as much as possible)
Assert ( Dot ( Normalize(Screen1.Frame.Position-F.Frame.Position), F.Frame.Axis3) = 1 );
```

```
// Screen1 IS inside the frustum
Assert ( Inside ( F, Screen1.Frame.Position) );
```

```
// Screen1 is not occluded from the point of view of the user.
Assert ( Visible ( F.Frame.Position, Screen1.Frame.Position) = 0 );
```

```
// The 4 media objects are INSIDE the frustum.
Assert ( Inside ( F, O1.Frame.Position) );
```

```
Assert ( Inside ( F, 02.Frame.Position) );
Assert ( Inside ( F, 03.Frame.Position) );
Assert ( Inside ( F, 04.Frame.Position) );
```

```
// They are all visible to the user.
```

```
Assert ( Visible ( F.Frame.Position, O1.Frame.Position) = 0 );
Assert ( Visible ( F.Frame.Position, 02.Frame.Position) = 0 );
Assert ( Visible ( F.Frame.Position, 03.Frame.Position) = 0 );
Assert ( Visible ( F.Frame.Position, 04.Frame.Position) = 0 );
```

```
// Limits to the distance of media objects from the user.
Assert ( Distance (F.Frame.Position, O1.Frame.Position) > 50 &&
Distance (F.Frame.Position, 01.Frame.Position) < 450
);
// Make all the objects lie at the same distance from the user.
// (The user position is represented by the frustum 'F'.
Assert ( Distance ( F.Frame.Position, O1.Frame.Position) =
           Distance ( F.Frame.Position, 02.Frame.Position)
);
Assert (
           Distance (F.Frame.Position, O1.Frame.Position) =
```

Distance (F.Frame.Position, O3.Frame.Position)

